

On Randomization in (Higher-Order) Programming

Part V

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Part I

From Randomized to Bayesian

From Randomised Algorithms to Bayesian Programming

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- ▶ In recent years, starting from the pioneering works on languages like CHURCH, ANGLICAN, or HANSEI, functional programs have been also employed as means to represent probabilistic *models* rather than *algorithms*.
- ▶ The languages above can be modeled [Staton2017] as λ -calculi endowed with two new operators:
 - ▶ **sample**, modeling sampling from the uniform distribution on $[0, 1]$.
 - ▶ **score**, which takes a positive real number r as a parameter, and modify the *weight* of the current probabilistic branch by multiplying it by r .

Beyond Randomized Algorithms: The Grass Problem

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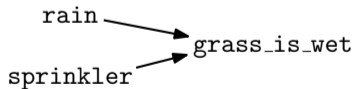
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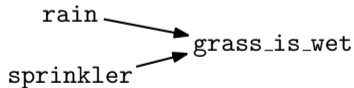
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- ▶ You get up in the morning, and notice that the grass in your garden is wet.
- ▶ You know that there is 30% probability that it rains during the night.
- ▶ The sprinkler is activated once every two days.
- ▶ You further know that:
 - ▶ *If it rains*, there is 90% probability that the grass is wet the following morning.
 - ▶ *If the sprinkler is activated*, there is 80% probability that the grass is wet the following morning.
 - ▶ *In any other case*, there is anyway a 10% probability that the grass is wet.
- ▶ In other words, you are in a situation like the following:



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- ▶ Now: how likely it is that it rained?

The Grass Model

```
let grass_model () = (* unit -> bool *)
  let rain = flip 0.3 and sprinkler = flip 0.5 in
  let grass_is_wet =
    (flip 0.9 && rain) || (flip 0.8 && sprinkler) || flip 0.1 in
  if not grass_is_wet then fail ();
  rain
```

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- ▶ One needs to switch from distributions to *measures*, and assume the underlying set, namely \mathbb{R} to have the structure of a measurable space
- ▶ Adapting the rule for **let**-terms naturally leads to

$$\frac{M \rightarrow \mu}{\text{let } M = x \text{ in } N \rightarrow \text{let } \mu = x \text{ in } N}$$

where **let** $\mu = x$ **in** N should itself be a measure.

- ▶ The key rule in step-indexed reduction needs to be adapted:

$$\frac{M \rightarrow \mu \quad \forall N \in \text{SUPP}(\mu). N \Rightarrow_n \sigma_N}{M \Rightarrow_{n+1} A \mapsto \int \sigma_N(A) \mu(dN)}$$

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- ▶ Explicitly building a normalized version of μ (if it exists) is the goal of so-called *inference algorithms*.
- ▶ The operational semantics we have just introduced, called **distribution-based** is thus just an *idealized* form of semantics.
- ▶ An *executable* semantics can be given in the form of **sampling-based semantics**.

Sampling-Based Semantics (1)

$$\begin{aligned} & \langle (\lambda x.M)V, s \rangle \xrightarrow{1} \langle M[V/x], s \rangle \\ & \langle \text{let } V = x \text{ in } M, s \rangle \xrightarrow{1} \langle M[V/x], s \rangle \\ & \langle \text{if } 0 \text{ then } M \text{ else } N, s \rangle \xrightarrow{1} \langle M, s \rangle \\ & \langle \text{if } r \text{ then } M \text{ else } N, s \rangle \xrightarrow{1} \langle N, s \rangle \text{ if } r \neq 0 \\ & \langle \text{sample}, r :: s \rangle \xrightarrow{1} \langle r, s \rangle \\ & \langle \text{score}(r), s \rangle \xrightarrow{r} \langle \star, s \rangle \\ & \langle f(r_1, \dots, r_n), s \rangle \xrightarrow{1} \langle f^*(r_1 \dots, r_n), s \rangle \\ & \frac{\langle M, s \rangle \xrightarrow{r} \langle L, t \rangle}{\langle \text{let } M = x \text{ in } N, s \rangle \xrightarrow{r} \langle \text{let } L = x \text{ in } N, s \rangle} \end{aligned}$$

Sampling-Based Semantics (2)

$$\frac{}{\langle V, s \rangle \stackrel{1}{\Rightarrow} \langle V, s \rangle} \quad \frac{\langle M, s \rangle \xrightarrow{r} \langle N, t \rangle \quad \langle N, t \rangle \stackrel{s}{\Rightarrow} \langle L, u \rangle}{\langle M, s \rangle \stackrel{r \cdot s}{\Rightarrow} \langle L, u \rangle}$$

Part II

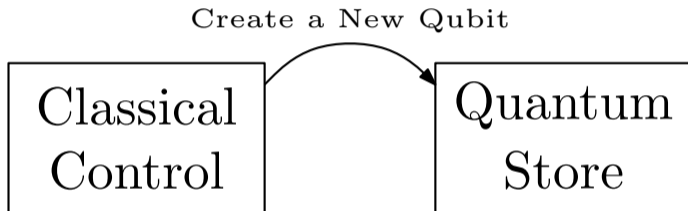
From Randomized to Quantum Higher-Order Programming

Quantum Data and Classical Control

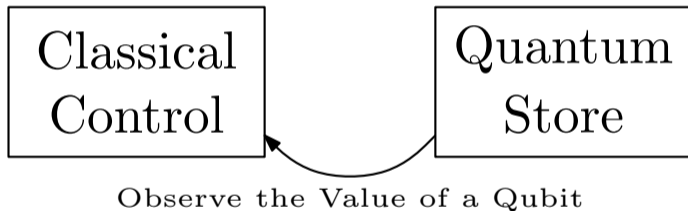
Classical
Control

Quantum
Store

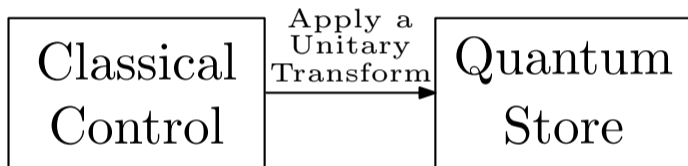
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A Naïve Attempt

- ▶ While looking for a quantum generalization of the λ -calculus, one could be tempted to proceed merely by enriching its syntax of **terms** as follows:

$$M, N ::= x \mid \lambda x.M \mid MN \mid r \mid U \mid \mathbf{new} \mid \mathbf{meas}$$

where:

- ▶ r is a **quantum variable** pointing to the quantum store;
 - ▶ the operator **new** **creates** a new qubit;
 - ▶ the operator **meas** **measures** a qubit from the quantum store;
 - ▶ U applies a unitary transform to one (or more) qubits from the quantum store.
- ▶ This would be enough to express, e.g., some simple quantum circuits:

$$\lambda x.\lambda y.\mathbf{CNOT}\langle \mathbf{H} x, y \rangle \qquad \lambda x.\mathbf{meas}(\mathbf{H}(\mathbf{new} x))$$

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$[\emptyset, (\lambda x.\lambda y.\text{CNOT}\langle\text{H } x, y\rangle)\langle\text{new } \bar{0}, \text{new } \bar{0}\rangle]$

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- ▶ Qubits can be freely duplicated or erased!
 - ▶ And this goes against the principles of quantum mechanics.
- ▶ We need a way to force qubits to be used **exactly** once when passed to functions.

Linearity and the λ -Calculus

- ▶ First of all, let us impose that in any abstraction $\lambda x.M$, the variable x occurs **exactly** once in M .
 - ▶ Copying and erasure **not** possible, anymore.
 - ▶ But the calculus **loses** much of its expressive power.

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 - ▶ Copying and erasure **not** possible, anymore.
 - ▶ But the calculus **loses** much of its expressive power.
- ▶ The idea is to **refine** the calculus in such a way as to reintroduce erasure and copying, but in a controlled way.
 - ▶ We mark as $!M$ all those subterms which can be (potentially) copied or erased;
 - ▶ Besides the usual linear abstraction $\lambda x.M$, there is a non-linear abstraction $\lambda !x.M$.
- ▶ Altogether, then, the language of terms becomes:

$$M, N ::= x \mid \lambda x.M \mid \lambda !x.M \mid MN \mid !M$$
$$r \mid \mathbf{U} \mid \mathbf{new} \mid \mathbf{meas}$$

where we insist that any term in the form $!M$ does not contain any quantum variable.

Evaluation Contexts

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Small Step Rules

$$[\mathcal{Q}, E[(\lambda x.M)N]] \Rightarrow \{[\mathcal{Q}, E[M[N/x]]]^1\}$$

$$[\mathcal{Q}, E[(\lambda!x.M)!N]] \Rightarrow \{[\mathcal{Q}, E[M[N/x]]]^1\}$$

$$[\mathcal{Q}, E[\text{meas } r]] \Rightarrow \{[\Pi_r^0(\mathcal{Q}), E[0]]^{\Xi_r^0(\mathcal{Q})}, [\Pi_r^1(\mathcal{Q}), E[1]]^{\Xi_r^1(\mathcal{Q})}\}$$

$$[\mathcal{Q}, E[\text{U } r]] \Rightarrow \{[\text{U}_r(\mathcal{Q}), E[r]]^1\}$$

$$[\mathcal{Q}, E[\text{new } 0]] \Rightarrow \{[\mathcal{Q} \otimes |r \rightarrow 0\rangle, E[r]]^1\}$$

$$[\mathcal{Q}, E[\text{new } 1]] \Rightarrow \{[\mathcal{Q} \otimes |r \rightarrow 1\rangle, E[r]]^1\}$$

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Theorem

*Any **meas**-free term M computes the same function as a uniform quantum circuit family $\{C_n\}_{n \in \mathbb{N}}$.*

- ▶ A term M can be evaluated by first reducing all the “classical” redexes, and then reducing the “quantum” ones.
- ▶ This is possible due to a standardization result.