

# *Implicit computational complexity : Light types for lambda-calculus*

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# Light Affine Logic (LAL)

Light linear logic and its affine variant were introduced as logics with polynomial time *dynamics*, t.i.t.s. normalization/cut-elimination.

Language of LAL formulas

$$A, B ::= \alpha \mid A \multimap B \mid A \otimes B \mid !A \mid \S A \mid \forall \alpha. A$$

- LAL *captures Ptime*: All and only polynomial time functions can be represented by LAL proofs of conclusion  $\vdash \mathbb{B} \multimap \S^k \mathbb{B}$ , for  $k \in \mathbb{N}$ .
- however: proofs have to be normalized (evaluated) using *proof-nets*.

thus:

underlying intuition	:	lambda-calculus
$\neq$ actual machinery needed	:	proof-nets

## Skimming LAL ...

In practice, we rarely use types of the following forms

$$A \multimap !B, \quad \S !A \multimap B, \quad !A .$$

However ! is definitely needed for types of the kind:

$$!A \multimap B$$

No surprise there: LL precisely arose from this decomposition of the intuitionistic arrow ...

Let us thus consider the fragment of LAL where ! is only used in types  $!A \multimap B$ :

to make this clearer, let us even drop ! and consider instead a non-linear arrow  $\Rightarrow$ , together with  $\multimap$ .

# Dual Light Affine Logic (DLAL)

the resulting system is called *Dual Light Affine Logic*, as it will handle two kinds of variables (linear vs non-linear ones).

language of DLAL types:

$$A, B ::= \alpha \mid A \multimap B \mid A \Rightarrow B \mid \S A \mid \forall \alpha. A$$

translation  $(.)^* : DLAL \longrightarrow LAL$ :

- $(A \Rightarrow B)^* = !A^* \multimap B^*$ ,
- $(.)^*$  commutes to other connectives.

Note that the following types are not in the image of DLAL :

$$A \multimap !B, \quad \S !A \multimap B, \quad !A .$$

# DLAL typing judgements

mixed judgements: the context is split into two parts

$$\Gamma; \Delta \vdash t : C$$

linear       $x : A \in \Delta$  at most 1 occurrence

harmless

non-linear     $y : B \in \Gamma$  any number of occurrence

dangerous:    *beware of substitutions*

a variable can change status from linear to non-linear (with some conditions)

# DLAL, sequent calculus style

$$\frac{}{; x : A \vdash x : A} (\text{Id})$$

$$\frac{\Gamma_1; \Delta_1, x : A \vdash t : B}{\Gamma_1; \Delta_1 \vdash \lambda x. t : A \multimap B} (\multimap r)$$

$$\frac{\Gamma_1, x : A; \Delta_1 \vdash t : B}{\Gamma_1; \Delta_1 \vdash \lambda x. t : A \Rightarrow B} (\Rightarrow r)$$

$$\frac{\Gamma_1; \Delta_1 \vdash t : A}{\Gamma_1, \Gamma_2; \Delta_1, \Delta_2 \vdash t : A} (\text{Weak})$$

$$\frac{; \Gamma, x_1 : B_1, \dots, x_n : B_n \vdash t : A}{\Gamma; x_1 : \S B_1, \dots, x_n : \S B_n \vdash t : \S A} (\S)$$

$$\frac{\Gamma; x : A[B/\alpha], \Delta \vdash t : C}{\Gamma; x : \forall \alpha. A, \Delta \vdash t : C} (\forall l)$$

$$\frac{\Gamma_1; \Delta_1 \vdash u : A \quad \Gamma_2; x : A, \Delta_2 \vdash t : C}{\Gamma_1, \Gamma_2; \Delta_1, \Delta_2 \vdash t[u/x] : C} (Cut)$$

$$\frac{\Gamma_1; \Delta_1 \vdash u : A \quad \Gamma_2; x : B, \Delta_2 \vdash t : C}{\Gamma_1, \Gamma_2; y : A \multimap B, \Delta_1, \Delta_2 \vdash t[(y u)/x] : C} (\multimap l)$$

$$\frac{; z : D \vdash u : A \quad \Gamma; x : B, \Delta \vdash t : C}{z : D, \Gamma; y : A \Rightarrow B, \Delta \vdash t[(y u)/x] : C} (\Rightarrow l)(*)$$

$$\frac{x_1 : A, x_2 : A, \Gamma_1; \Delta_1 \vdash t : B}{x : A, \Gamma_1; \Delta_1 \vdash t[x/x_1, x/x_2] : B} (\text{Cntr})$$

$$\frac{\Gamma; \Delta \vdash t : A}{\Gamma; \Delta \vdash t : \forall \alpha. A} (\forall r), \alpha \text{ not free in } \Gamma, \Delta$$

(\*)  $z : D$  can be absent.

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**Proposition 0** If  $\mathcal{D}$  has conclusion  $\Gamma; \Delta \vdash_{DLAL} t : A$  then  $|t| \leq |\mathcal{D}|$ .

# DLAL, sequent calculus style

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(*) $z : D$ can be absent.	

# Type derivations in DLAL

**Proposition 0** if  $\Gamma; \Delta \vdash_{DLAL} t : A$  and  $x \in \Delta$ , then  $x$  has at most one occurrence in  $t$  ( $x$  linear).

**Proposition 0** If  $\Gamma; \Delta \vdash_{DLAL} t : A$  then  $!\Gamma^*, \Delta^* \vdash_{LAL} t : A^*$ .  
We obtain in this way a simulation from DLAL to LAL.

The *depth* of a DLAL derivation is the depth of the corresponding LAL derivation.

# DLAL data types

## ■ unary integers

LAL:

$N^{LAL}$

$$\forall \alpha. !(\alpha \multimap \alpha) \multimap \S(\alpha \multimap \alpha),$$

DLAL

$N^{DLAL}$

$$\forall \alpha. (\alpha \multimap \alpha) \Rightarrow \S(\alpha \multimap \alpha).$$

## ■ binary lists

LAL:

$\mathbb{B}^{LAL}$

$$\forall \alpha. !(\alpha \multimap \alpha) \multimap !(\alpha \multimap \alpha) \multimap \S(\alpha \multimap \alpha), \quad \forall \alpha. (\alpha \multimap \alpha) \Rightarrow (\alpha \multimap \alpha) \Rightarrow \S(\alpha \multimap \alpha).$$

DLAL

$\mathbb{B}^{DLAL}$

# Types in DLAL

examples of types:

$$\vdash \text{addition} : N \multimap N \multimap N$$

$$\vdash \text{double} : N \Rightarrow \S N$$

The functions representable in DLAL are given by types  $\mathbb{B} \multimap \S^k \mathbb{B}$ .

Typing of iterators:

$$\text{iter}_A = \lambda f xn. (n\ f\ x) : (A \multimap A) \Rightarrow \S A \multimap N \multimap \S A$$

$$\text{iter}^{\mathbb{B}}_A = \lambda f_1 f_2 x w. (w\ f_1\ f_2\ x) : (A \multimap A) \Rightarrow (A \multimap A) \Rightarrow \S A \multimap \mathbb{B} \multimap \S A$$

# Coercions in DLAL

Type coercions on data-types are needed to compose programs suitably.

in LAL:  $coer^{p,q} : N \multimap \S^{p+1}!^q N$

in DLAL, the following rules are derivable:

$$\frac{n : N; \Delta \vdash t : A}{; n : N, \S\Delta \vdash C_1[t] : \S A} \text{ (coerc1)} \quad \frac{\Gamma; n : \S N, \Delta \vdash t : A}{\Gamma; n : N, \Delta \vdash C_2[t] : A} \text{ (coerc2)}$$

with  $C_i$  contexts such that  $C_i[t]$  is extensionally equivalent to  $t$  (represents the same function)

Example  $mult : N \Rightarrow (N \multimap \S N)$

$mult' : N \multimap \S(N \multimap \S N)$  by (coerc1)

$mult'' : N \multimap N \multimap \S\S N$  by (coerc2)

**Proposition 1** *If  $P \in \mathbb{N}[X]$ , then there exists a term  $t_P$  representing  $P$  and an integer  $k$  such that:  $\vdash_{DLAL} t_P : N \multimap \S^k N$ .*

## DLAL: complexity bounds

**Proposition 2** *DLAL satisfies the subject-reduction property.*

**Theorem 3 (strong polynomial bound)** *If  $t$  is typeable in DLAL with a derivation of depth  $d$ , then any sequence of  $\beta$ -reducts of  $t$  has length bounded by  $O(|t|^{2^d})$ .*

*Moreover this reduction is performed in time  $O(|t|^{2^{d+2}})$  on a Turing machine.*

Remarks:

- we are dealing here with  $\beta$ -reduction, and not anymore with proof-net reduction;
- this bound holds for any reduction strategy;
- in particular, if  $\vdash t : \mathbb{B} \multimap \S^k \mathbb{B}$  then we can normalize  $(t \ u)$  in a number of steps (and time) polynomial in  $\text{length}(w)$ .

**Theorem 4** *The functions representable by terms typeable in DLAL are exactly the functions computable in polynomial time.*

# Conclusion

- LL brings a logical, proof-based approach to implicit computational complexity,
- this is one approach relating ICC on the one hand and functional programming, typing, proofs on the other . . .
- however, the *intensional* expressivity is limited : all polynomial time *functions* are representable, but some common polynomial time algorithms are not (directly) typeable  
→ more flexible systems in the typing approach ?