A group of five women in pink swimsuits are water skiing on a lake. They are holding onto a rope and have their arms outstretched. The water is blue and there are white waves around them. The background shows a hazy shoreline with trees.

Dynamic Choreographies

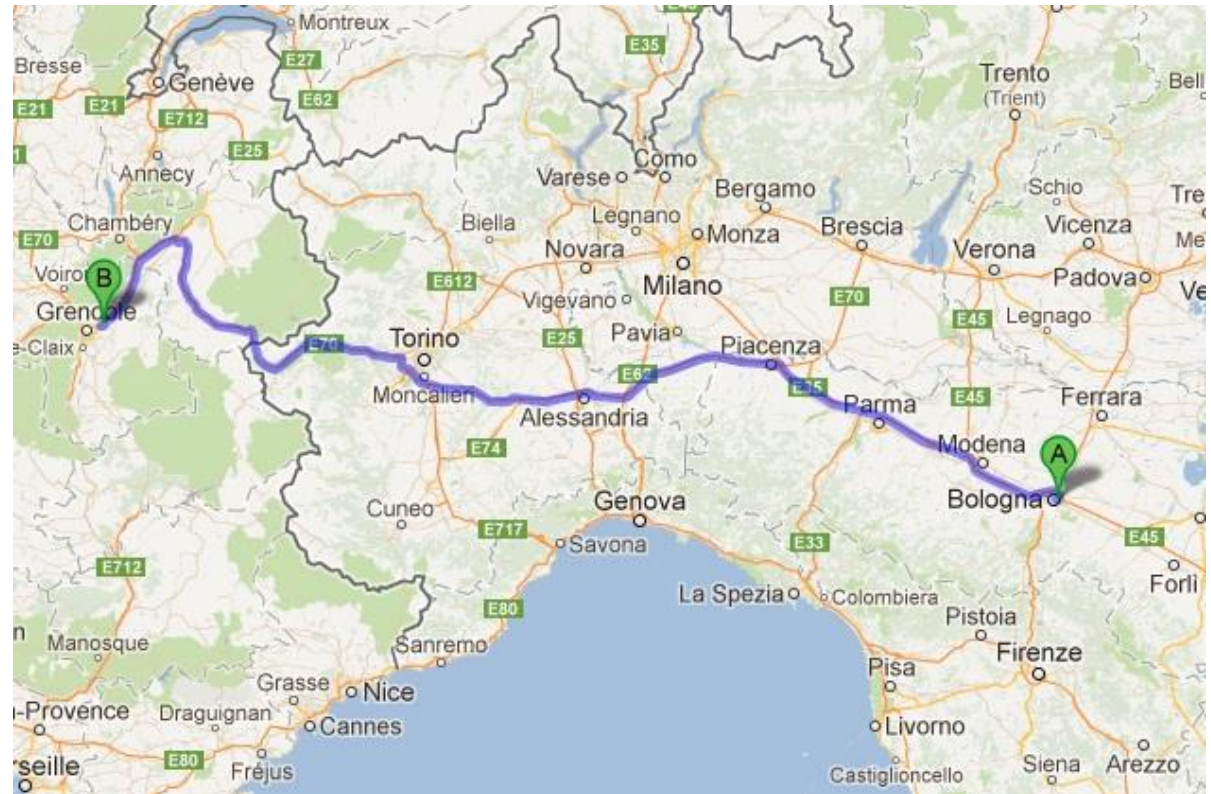
Safe Runtime Updates of Distributed Applications

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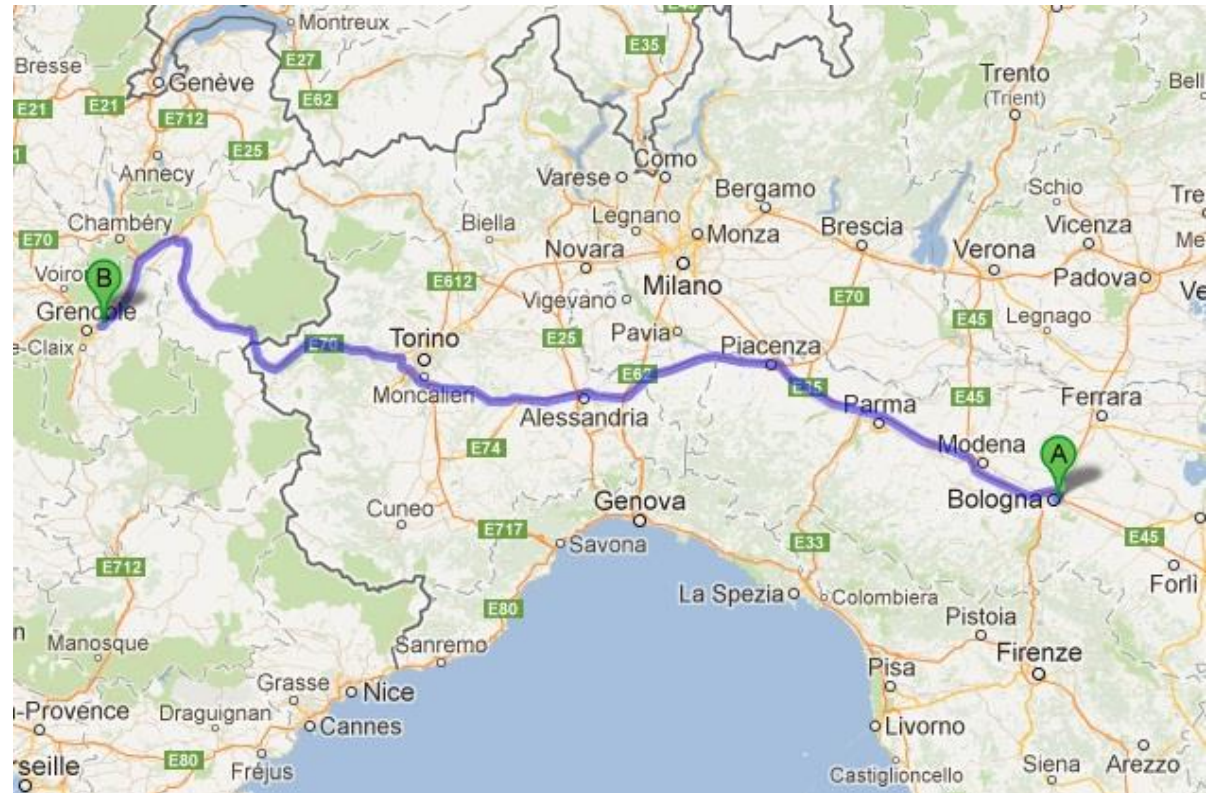
Map of the talk

- Choreographic programming
- Dynamic updates
- Results
- Conclusion



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Choreographic programming: aim

- Distributed applications are normally programmed using send and receive primitives
 - Difficult and error-prone
 - Deadlocks, races, ...
- Choreographic programming aims at solving these problems by raising the level of abstraction

Choreographic programming: basics

- The basic building block is an interaction, i.e. a communication between two participants
 - Not a send or a receive
- Interactions can be composed using standard constructs: sequences, conditionals, cycles,...
- One choreographic program describes a whole distributed application
 - Not a single participant

Choreographic syntax

- $I ::= o:r(e) \rightarrow s(x)$
 $x@r = e$
 1
 $I ; I'$
 $I | I'$
 $\text{if } b@r \{I\} \text{ else } \{I'\}$
 $\text{while } b@r \{I\}$
- For multiparty session types addicts
choreographic programs \approx global types + data + conditions

A sample choreographic program

- *prodName@buyer = getInput();*
priceReq: buyer(prodName) → seller(pName);
price@seller = getPrice(pName);
offer: seller(price) → buyer(pr);
...



Advantages of choreographic programming

- Clear view of the global behavior
- No deadlocks and races since send and receive are paired into interactions

How to execute choreographic programs?

- Most constructs involve many participants
- What each participant should do?
- We want to compile the choreographic program into a local code for each participant
- We define a projection function to this end
- When executed, the derived participants should interact as specified in the choreographic program
 - Correctness of the compilation
 - No deadlocks and no races

The target language

- $P ::= o: e \text{ to } r$
 $o: x \text{ from } r$
 $x = e$
 1
 $P; P'$
 $P|P'$
 $\text{if } b \{P\} \text{ else } \{P'\}$
 $\text{while } b \{P\}$
- A distributed application is composed by named participants executing Ps

Projection: basic idea

- An interaction $o_1: r_1(5) \rightarrow s_1(x)$ becomes
 - A send $o_1: 5$ to s_1 on r_1
 - A receive $o_1: x$ from r_1 on s_1
 - A skip 1 on all the other participants
- Assignments $x@r = e$ are executed by the role r
- Other constructs are projected homomorphically

- Very simple...
- ...but it does not work

Projection: problems and solutions

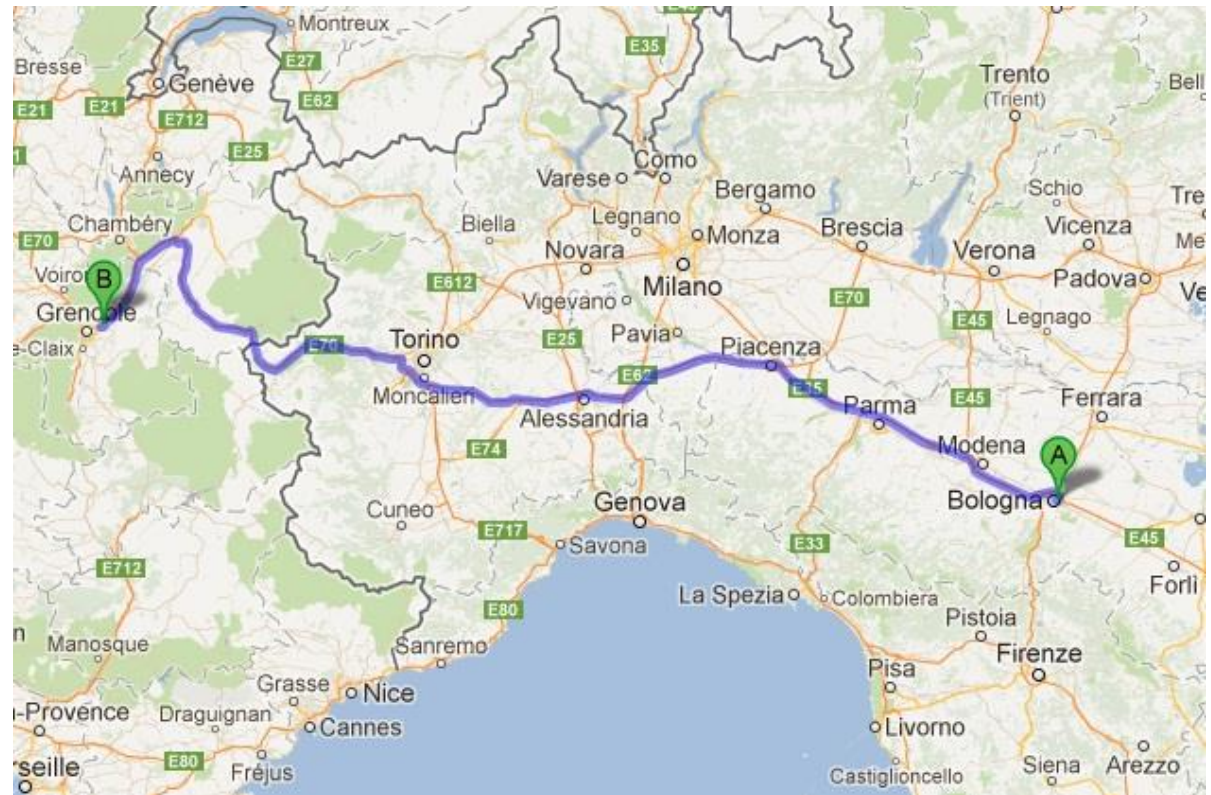
- Participants are independent

$$o_1: r_1(5) \rightarrow s_1(x); o_2: r_2(7) \rightarrow s_2(y)$$

- Interaction on o_2 should happen after interaction on o_1
 - No participant can force this
- Participants' execution may depend on other participants
 - if $x@r_1 \{o: r_2(5) \rightarrow s(x)\}$ else $\{o: r_2(7) \rightarrow s(x)\}$
- Participant r_2 should send 5 or 7 according to a local decision of r_1
- These problems are solved by
 - adding auxiliary communications beyond the ones specified
 - restricting the allowed compositions (connectedness)

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Dynamic updates



- We want to change the code of running applications, by integrating new pieces of code coming from outside
- Those pieces of code are called updates
- The set of updates
 - is not known when the application is designed, programmed or even started
 - may change at any moment and without notice
- Many possible uses
 - Deal with emergency behavior
 - Deal with changing business rules or environment conditions
 - Specialise the application to user preferences

Our approach, syntactically

- Pair a running application with a set of updates
 - Each update is a choreographic program
 - The set of updates may change at any time
- At the choreographic level, the update may replace a part of the application
 - Which part?
- Extend choreographic programs with scopes
 - scope $@r \{I\}$
 - Before starting, the scope may be replaced by an update

Our approach, semantically

- A scope can either execute, or be replaced by an update

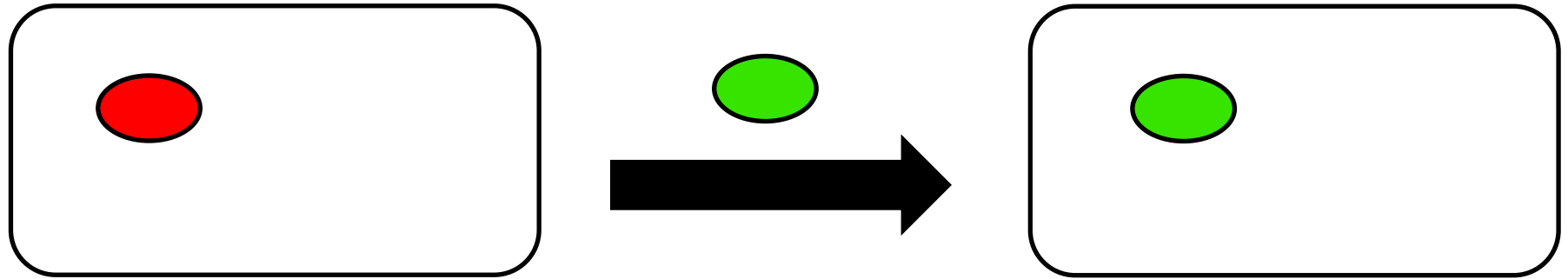
$$\langle \Sigma, \mathbf{I}, \text{scope @r } \{I\} \rangle \xrightarrow{\text{no-up}} \langle \Sigma, \mathbf{I}, I \rangle$$

$$\frac{\text{roles}(I') \subseteq \text{roles}(I) \quad I' \in \mathbf{I} \quad I' \text{ connected}}{\langle \Sigma, \mathbf{I}, \text{scope @r } \{I\} \rangle \xrightarrow{I'} \langle \Sigma, \mathbf{I}, I' \rangle}$$

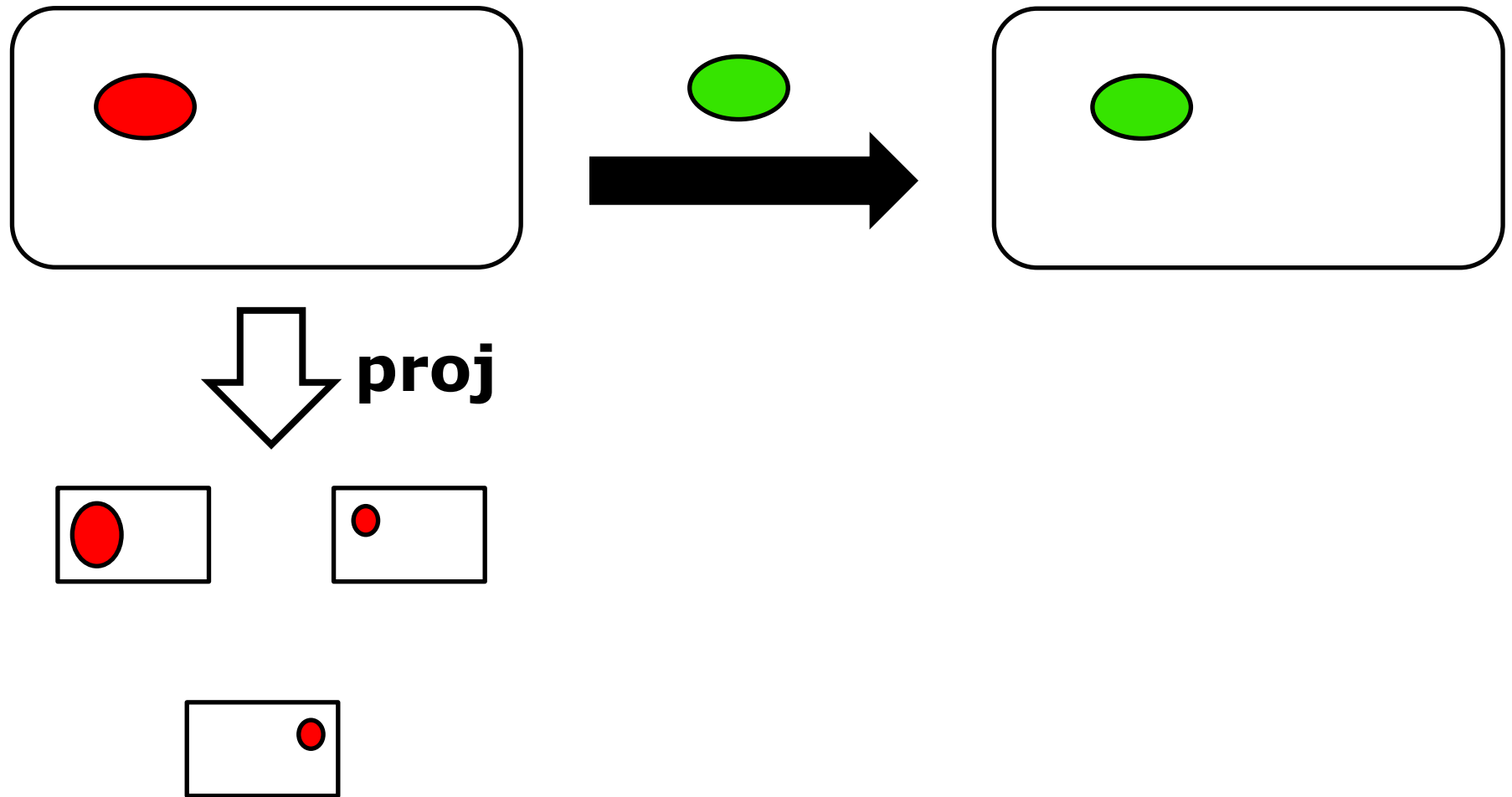
- Updates can change at any time

$$\langle \Sigma, \mathbf{I}, I \rangle \xrightarrow{I'} \langle \Sigma, \mathbf{I}', I \rangle$$

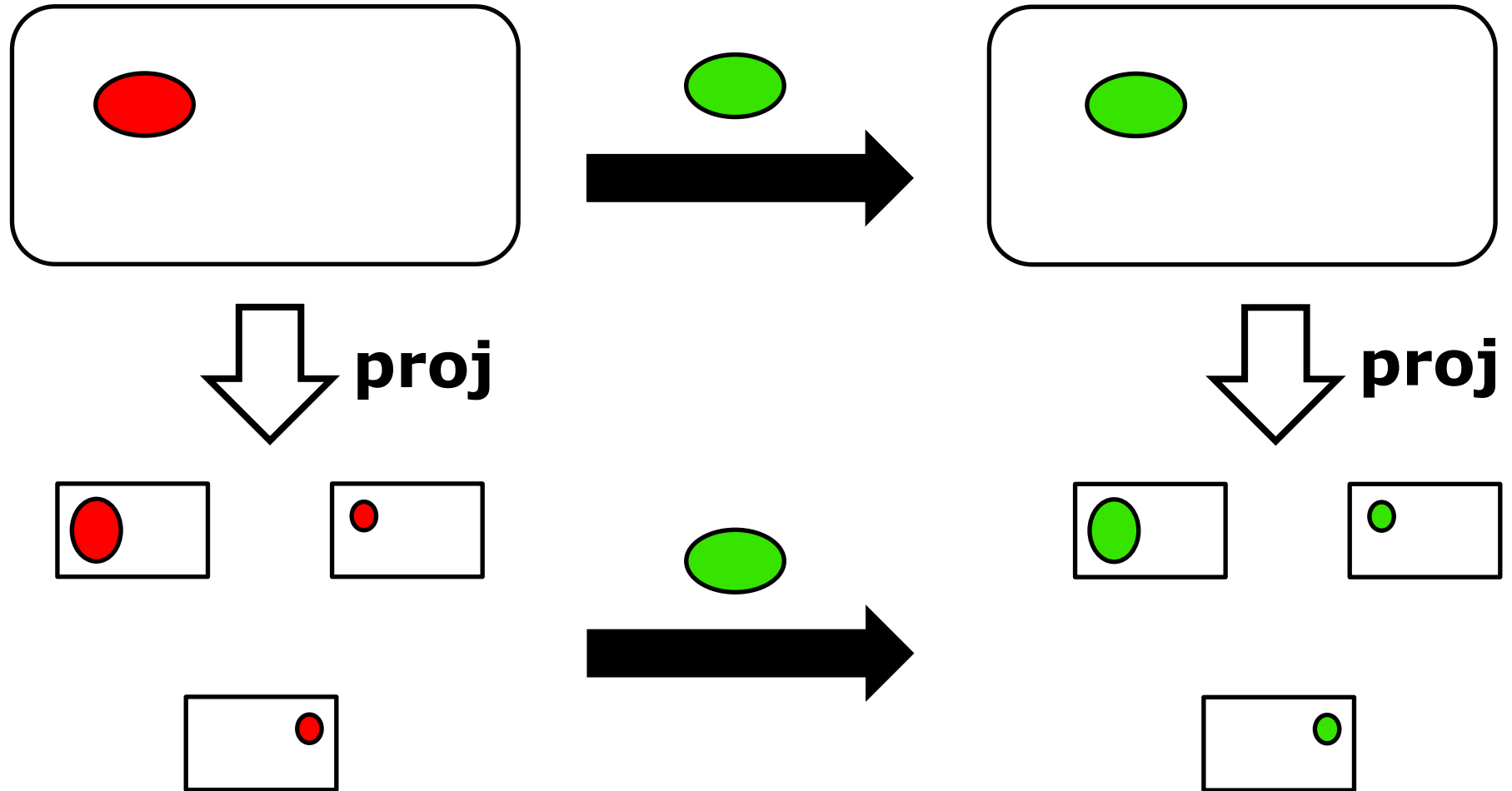
Our approach, graphically



Our approach, graphically



Our approach, graphically



A sample update

- *cardReq: seller() → buyer();*
cardSend: buyer(cardId) → seller(buyerId);
if(isValid(buyerId))@seller
 *{price@seller = getPrice(pName) * 0.9; }*
else
 {price@seller = getPrice(pName); }
offer: seller(price) → buyer(pr);



Making the choreographic program updatable

- $prodName@buyer = getInput();$
 $priceReq: buyer(prodName) \rightarrow seller(pName);$
 $price@seller = getPrice(pName);$
 $offer: seller(price) \rightarrow buyer(pr);$
...



Making the choreographic program updatable

- *prodName@buyer = getInput();*
priceReq: buyer(prodName) → seller(pName);
scope @seller {
 price@seller = getPrice(pName);
 offer: seller(price) → buyer(pr);
}
...



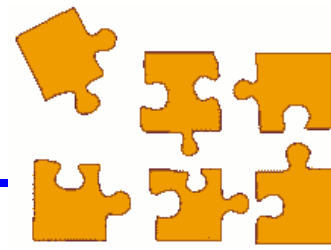
Dynamic updates: challenges

- All the participants should agree on
 - whether to update a scope or not
 - in case, which update to apply
- All the participants need to retrieve (their part of) the update
 - Not easy, since updates may disappear
- No participant should start executing a scope that needs to be updated

Dynamic updates: our approach

- For each scope a single participant coordinates its execution
 - Decides whether to update it or not, and which update to apply
 - Gets the update, and sends to the other participants their part
- The other participants wait for the decision before executing the scope
- We add scopes (and higher-order communications) to the target language, with the semantics above

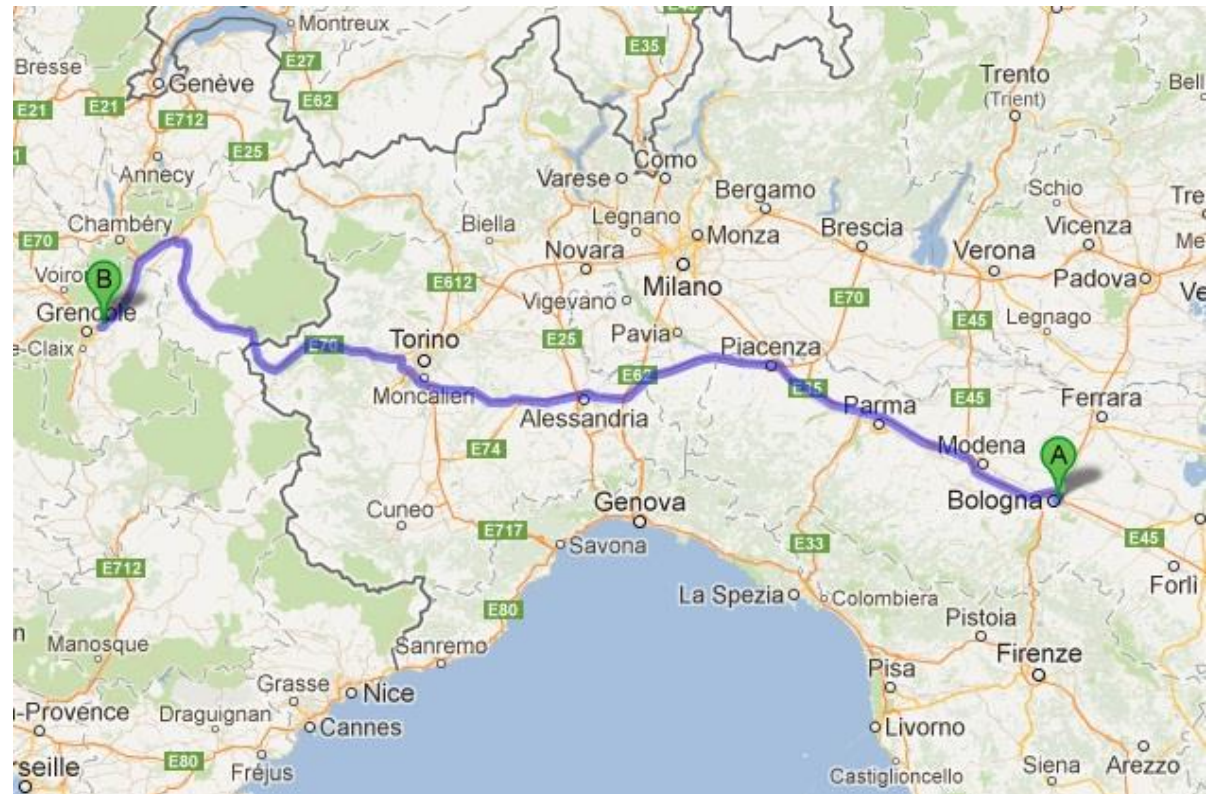
Compositionality issue



- Applying an update at the choreographic level results in a new choreographic program, composed by
 - The unchanged part of the old choreographic program
 - The update
- Even if the two parts are connected, the result may not be connected
- Auxiliary communications are added to ensure connectedness

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Results

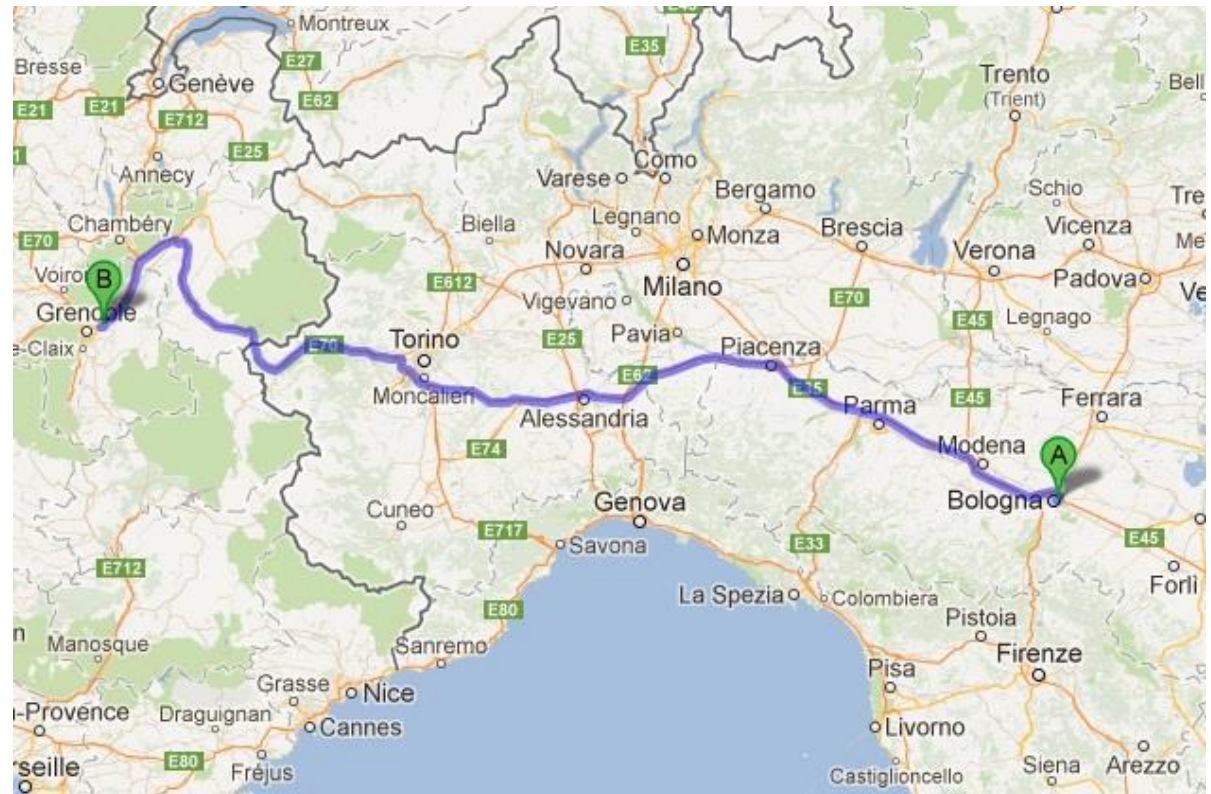
- A choreographic program and its projection behave the same
 - They have the same set of traces (up to auxiliary actions)
 - Under all possible, dynamically changing, sets of updates
- The projected application is deadlock free and race free by construction
- These results are strong given that we are considering an application which is
 - distributed
 - updatable

Implementation

- Our result is quite abstract, and can be instantiated in different ways
- AIOCJ is one such way [SLE 2014]
- A framework for safe rule-based adaptation of distributed applications
- Updates are embedded into adaptation rules specifying when and where to apply them
- Scopes include some more information driving the application of adaptation rules
- Projection produces service-oriented code
- <http://www.cs.unibo.it/projects/jolie/aiocj.html>

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Conclusion

- A choreographic approach to dynamic updates
- The derived distributed application follows the behavior defined by the choreographic program
- We ensures deadlock freedom and race freedom in a challenging setting
- We instantiated the theoretical framework to adaptable service-oriented applications

Future work



- Extend the approach to asynchronous communication
- How to cope with multiple interleaved sessions?
- How to improve the performance?
 - Drop redundant auxiliary communications
- Can we instantiate our approach on existing frameworks for adaptation?
 - E.g., dynamic aspect-oriented programming
 - To inject correctness guarantees

End of talk

Thanks!

QUESTIONS?