

Binary Search Trees

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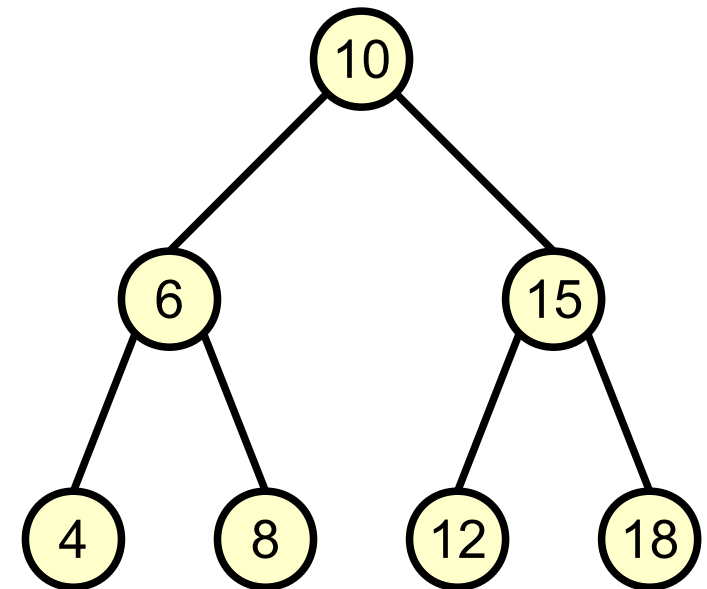
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Dictionary

- Dictionary
 - Dynamic set implementing the functions
 - Item search(Key key)
 - void insert(Key key, Item item)
 - void delete(Key key)
- Fundamental data structure for many applications
 - ex. to find a DB record by knowing the Key
- Possible examples of implementations
 - Sorted array
 - Search $O(\log n)$, insert/delete element $O(n)$
 - Unsorted list
 - Search/delete $O(n)$, insert $O(1)$

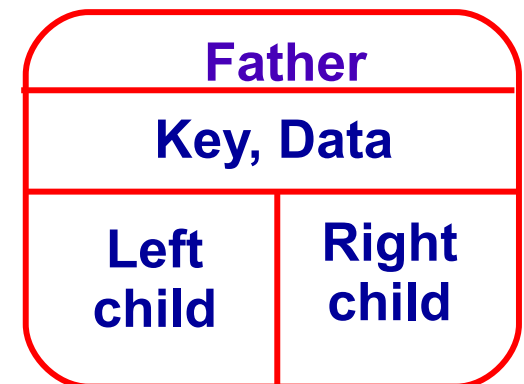
Binary Search Trees (BST)

- Idea
 - Implement a binary search in a tree
- Definition
 1. Every node v contains a set of data $v.data$ associated to a key $v.key$ taken from a totally ordered domain (duplicate keys are possible)
 2. Keys of nodes in the left subtree of v are $\leq (=?) v.key$
 3. Keys of nodes in the right subtree of v are $\geq (=?) v.key$



Binary Search Trees (BST)

- Search property
 - Properties 2 and 3 allows to implement a dicotomic search algorithm
- **Question:** order property
 - How should I visit the tree to get a list of ordered values?
- Implementation details
 - Every node in the tree should maintain
 - Left and right child
 - Father
 - Key
 - Satellite data

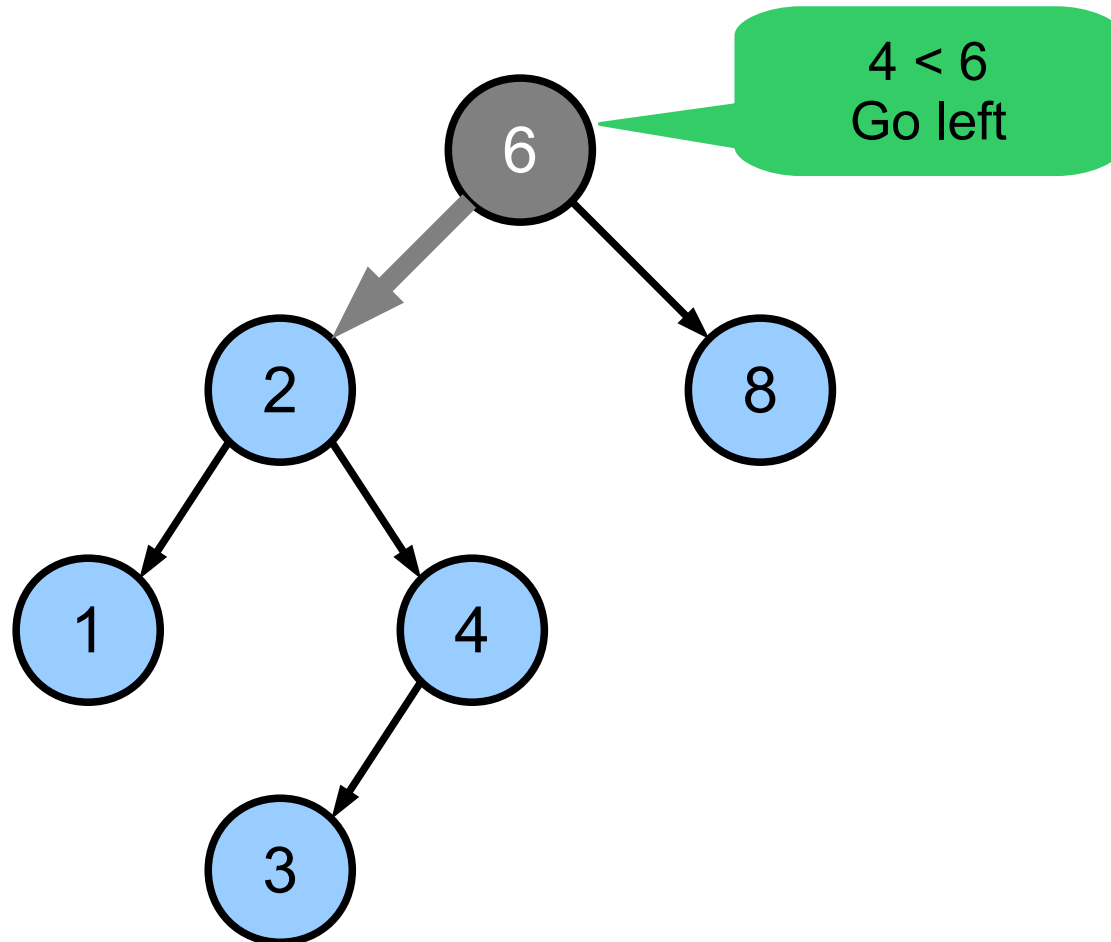


Dictionary interface

```
public interface Dictionary {  
    /**  
     * add the pair (e,k) to dictionary  
     */  
    public Rif insert(Object e, Comparable k);  
  
    /**  
     * deletes element u from dictionary  
     */  
    public void delete(Rif u);  
  
    /**  
     * returns element e with key k.  
     * In case of duplicate keys, it returns  
     * an arbitrary selected element with key k.  
     */  
    public Object search(Comparable k);  
}
```

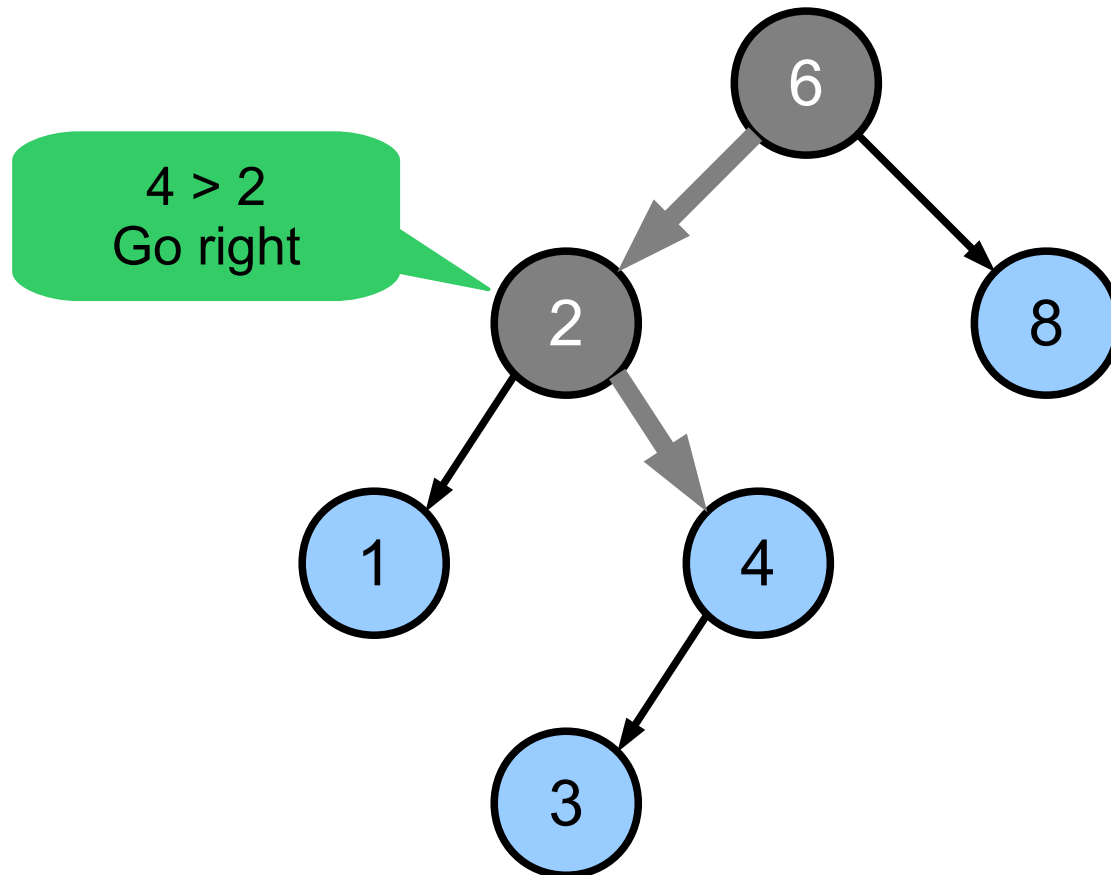
Example

searching key 4



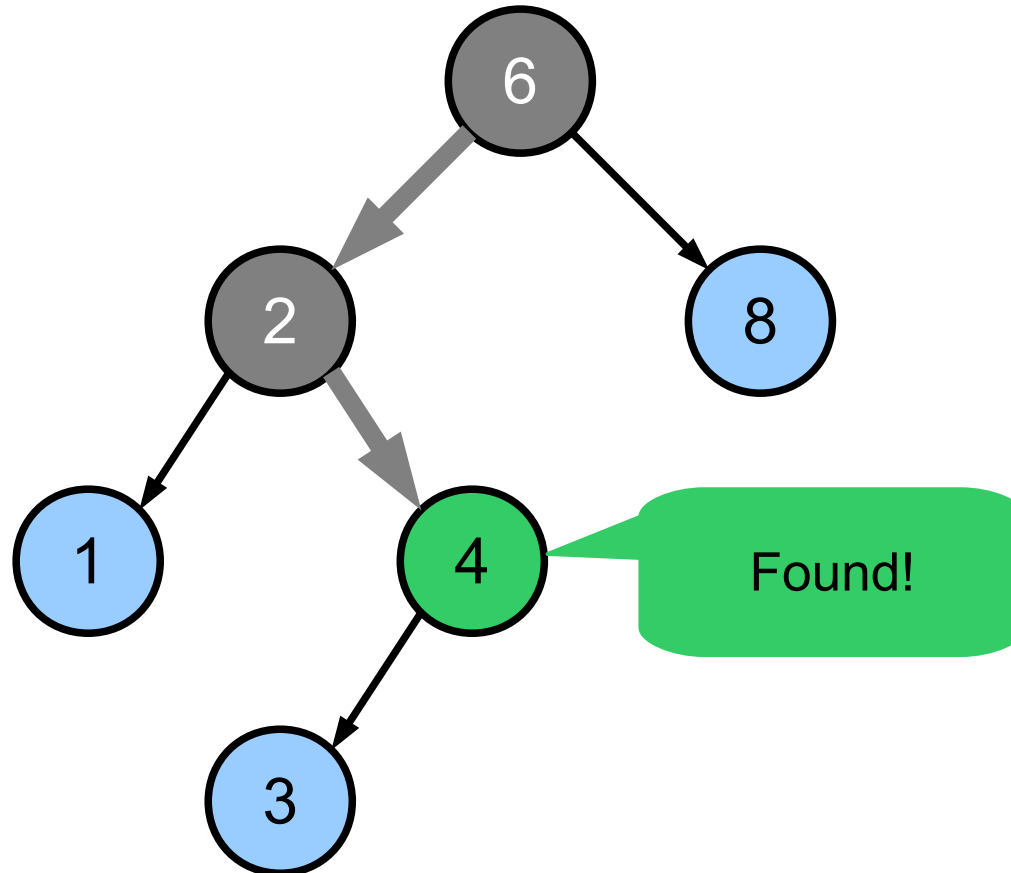
Example

searching key 4



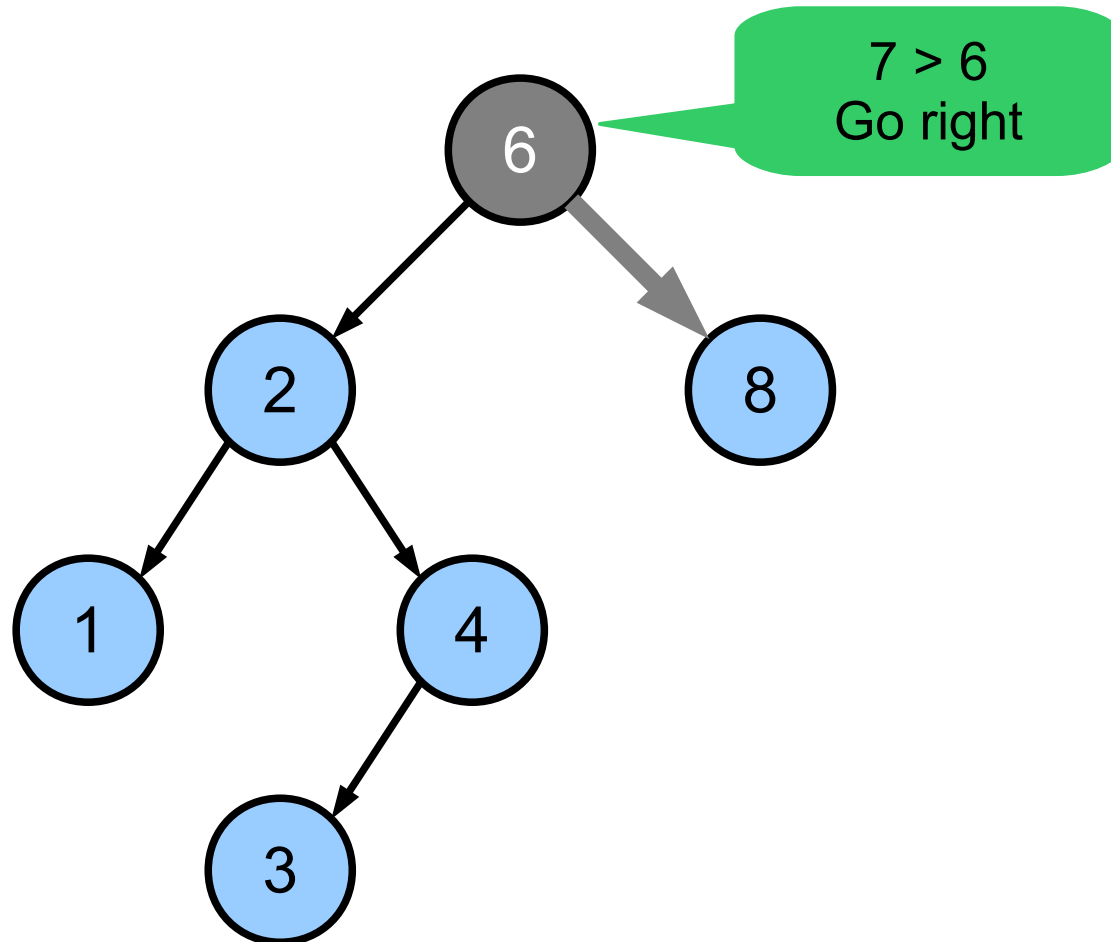
Example

searching key 4



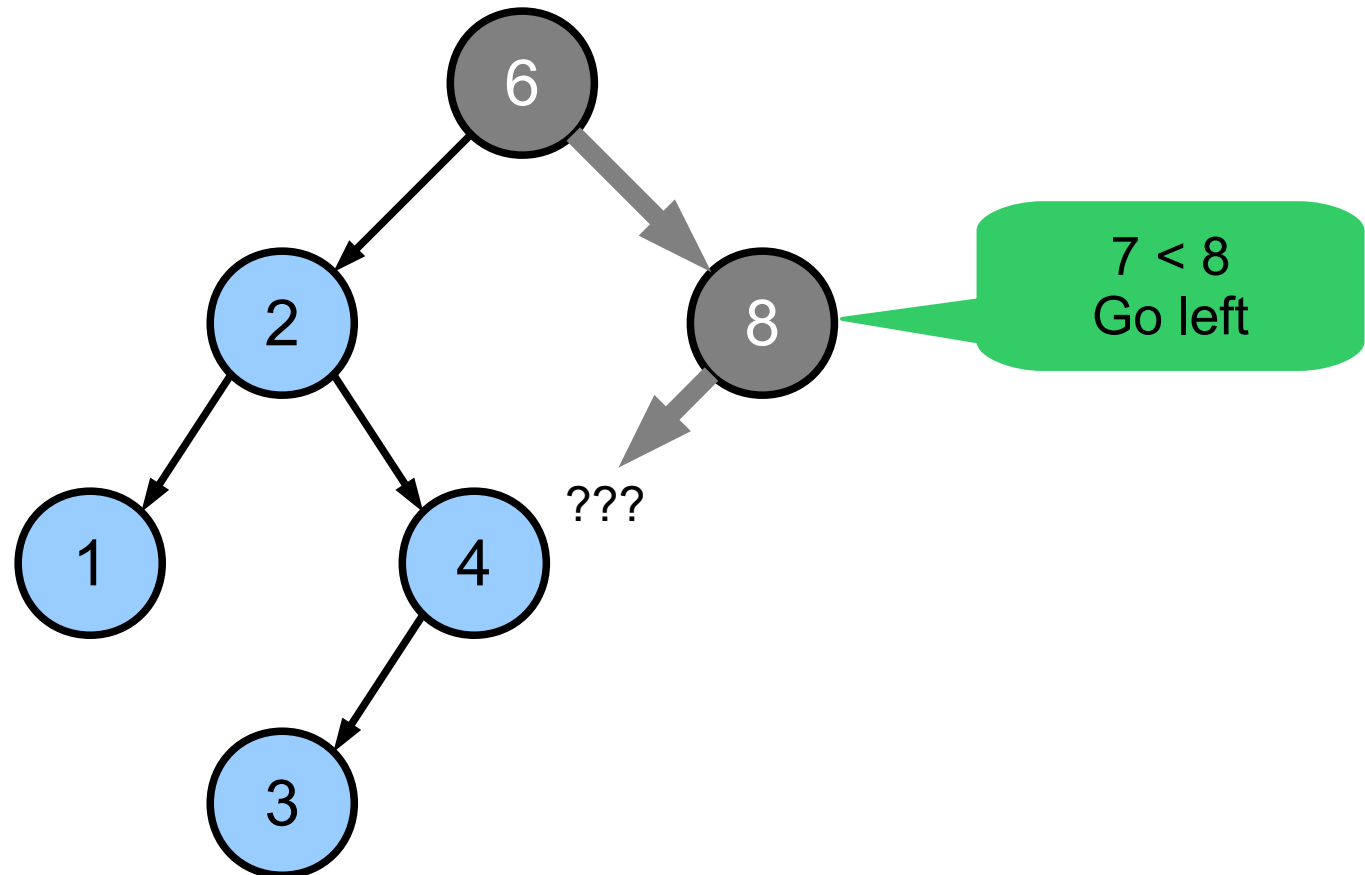
New example

searching key 7



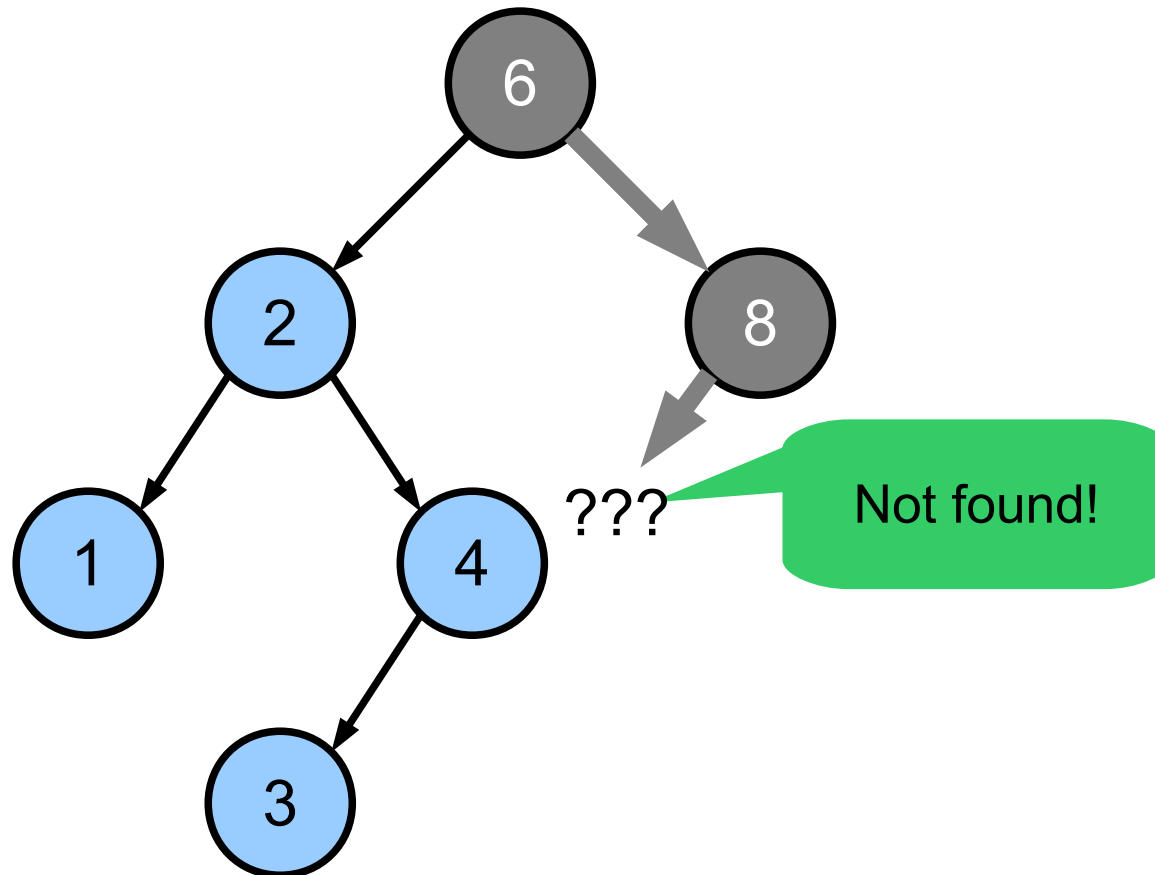
New example

searching key 7



New example

searching key 7



Search: pseudocode

```
algorithm search(Nodo T, Key k) → Nodo
  if (T == null || k == T.key) then
    return T;
  elseif (k < T.key) then
    return search(T.left, k)
  else
    return search(T.right, k)
  endif
```

Recursive
version

Iterative
version

```
algorithm search(Nodo T, Key k) → Nodo
  while (T ≠ null) do
    if (k == T.key) then
      return T;
    elseif (k < T.key) then
      T := T.left;
    else
      T := T.right;
    endif
  endwhile
  return null
```

Class BSTree

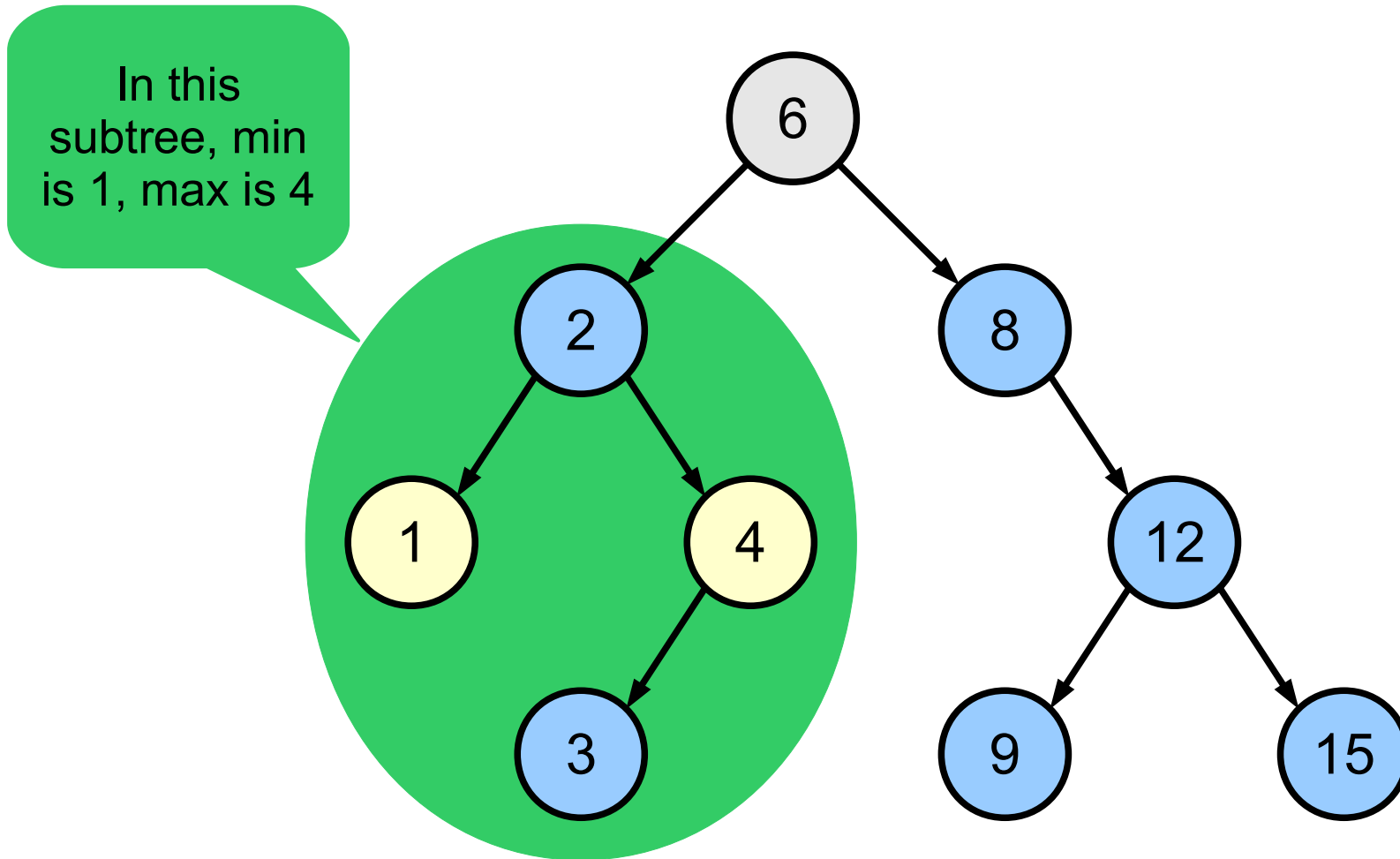
package asdlab.libreria.AlberiRicerca

```
public class BSTree implements Dictionary {  
  
    protected class InfoBR implements Rif {  
        protected Object elem;  
        protected Comparable key;  
        protected Node node;  
        protected InfoBR(Object e, Comparable k){  
            elem = e; key = k; node = null;  
        }  
    }  
  
    // Data structure containing the informations  
    protected BinTree tree;  
  
    public BSTree() { ... }  
  
    // additional operations ...  
}
```

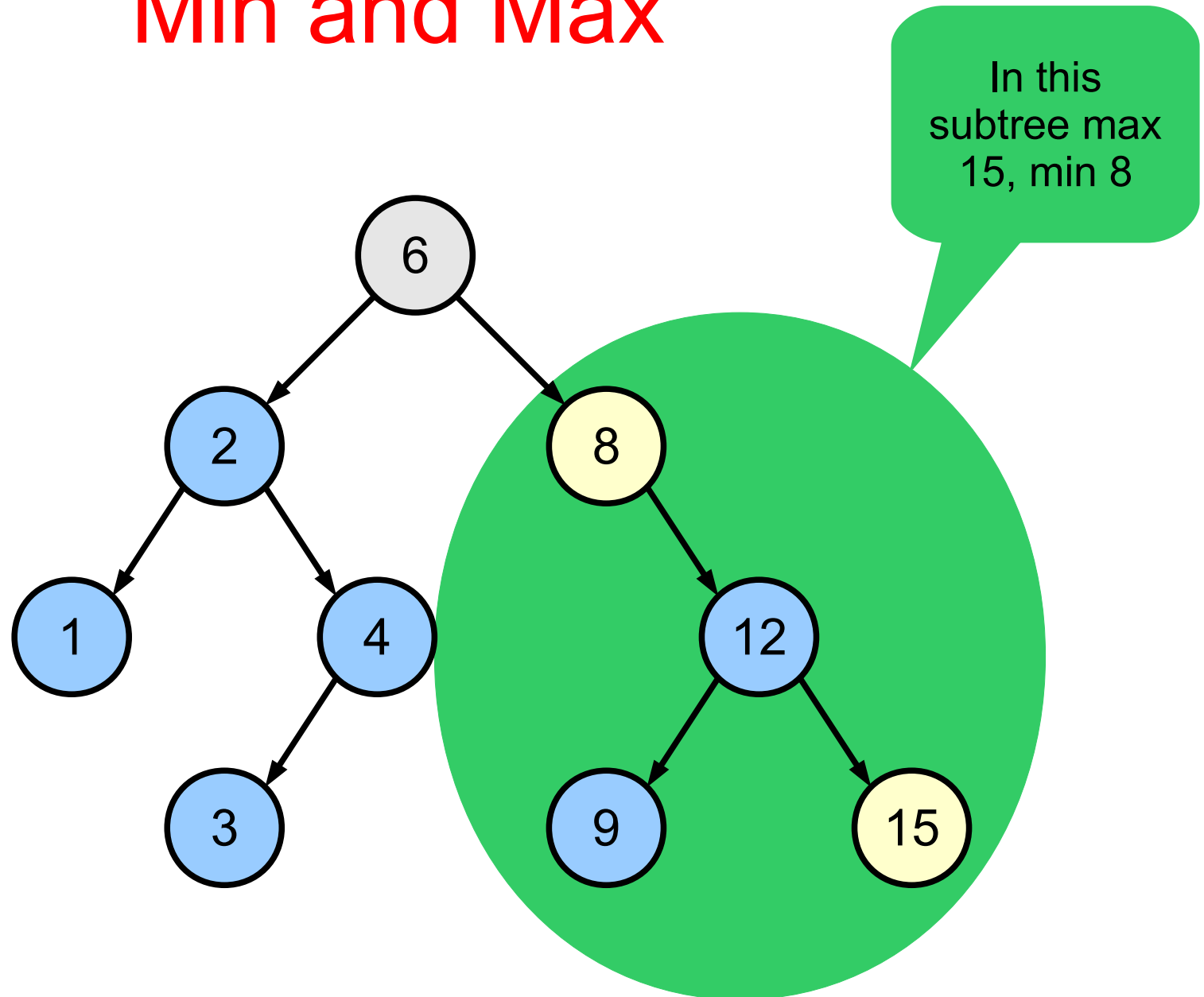
search: java implementation (iterative version)

```
public Object search(Comparable k) {
    Node v = tree.root();
    while (v != null) {
        InfoBR i = (InfoBR)tree.info(v);
        if (k.equals(i.key))
            return i.elem;
        if (k.compareTo(i.key) < 0)
            v = tree.sx(v);
        else
            v = tree.dx(v);
    }
    return null;
}
```

Min and max



Min and Max



Search of the max element

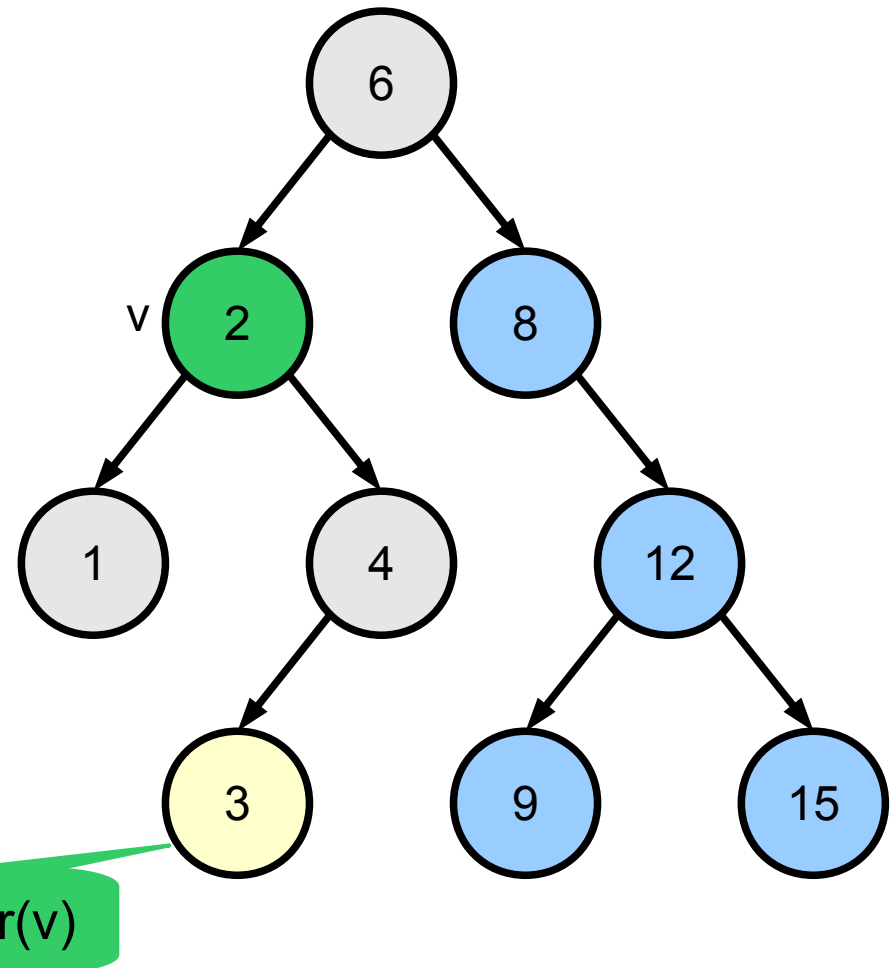
- Given a node v:
 - the **maximum** value in the tree rooted by v is in the “rightmost node”
 - the **minmum** value in the tree rooted by v is in the “leftmost node”

```
protected Node max(Node v) {  
    while (v != null &&  
           tree.dx(v) != null) {  
        v = tree.dx(v);  
    }  
    return v;  
}
```

```
protected Node min(Node v) {  
    while (v != null &&  
           tree.sx(v) != null) {  
        v = tree.sx(v);  
    }  
    return v;  
}
```

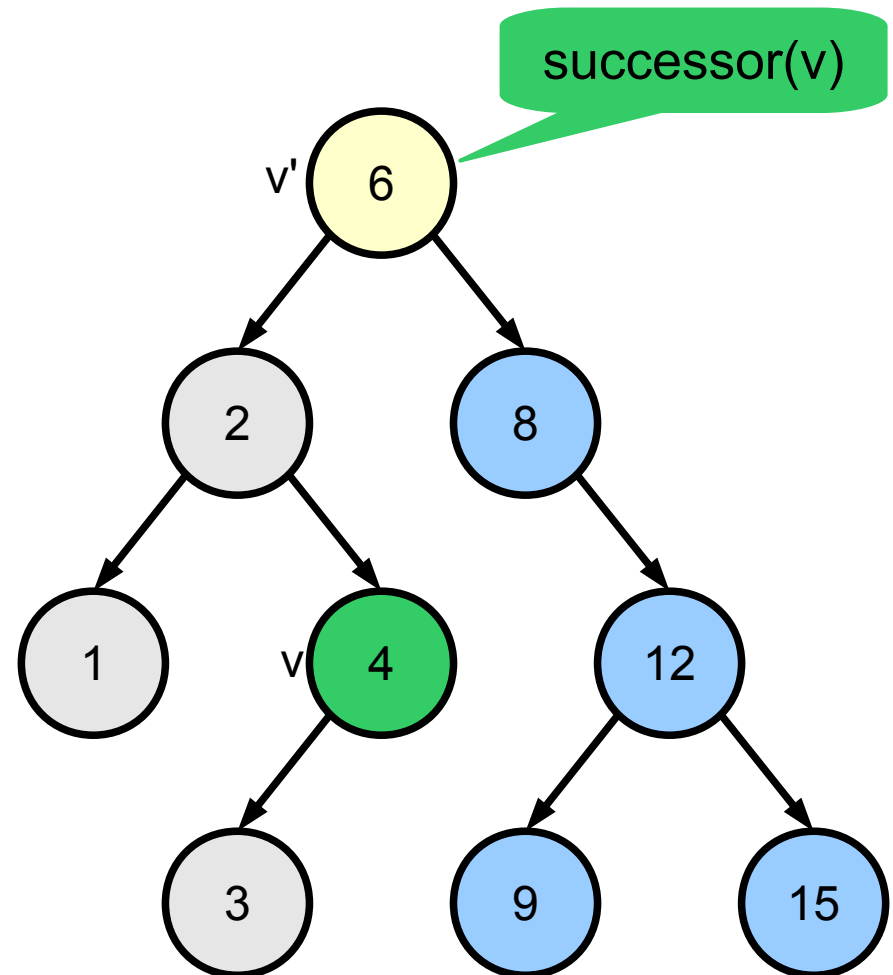
Search of the successor element

- Definition
 - A successor of a node v is the node containing the smallest value greater than v
- Two possible cases
 - v has a right child
 - The successor is the min of the right subtree of v
 - Example
successor of 2 is 3



Search of the successor element

- Definition
 - A successor of a node v is the node containing the smallest value greater than v
- Two possible cases
 - v does not have a right child
 - The successor is the first ancestor v' such that v is in the left subtree of v'
 - Example
successor of 4 is 6

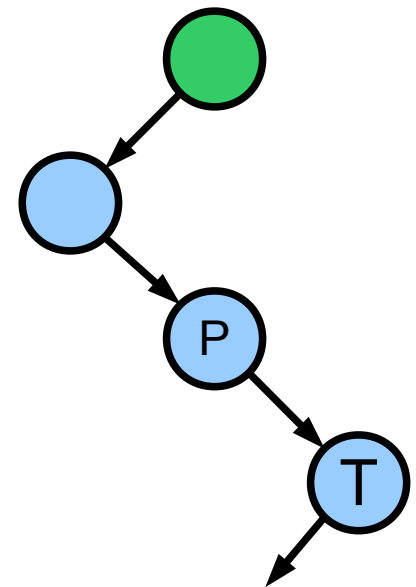


Search of successor Pseudo-code (iterative)

```
algorithm BST successor(BST T)
  if (T == null) then
    return null;
  endif
  if (T.right ≠ null) then
    return min(T.right);
  else
    P := T.parent
    while (P ≠ null && T == P.right) do
      T := P;
      P := P.parent;
    endwhile
    return P;
  endif
```

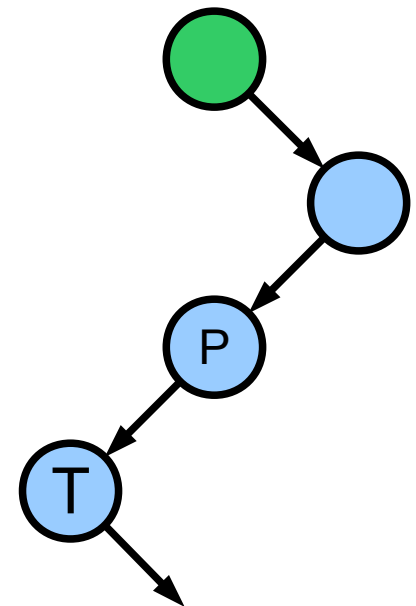
Case 1: right
child exists

Case 2: right
child missing



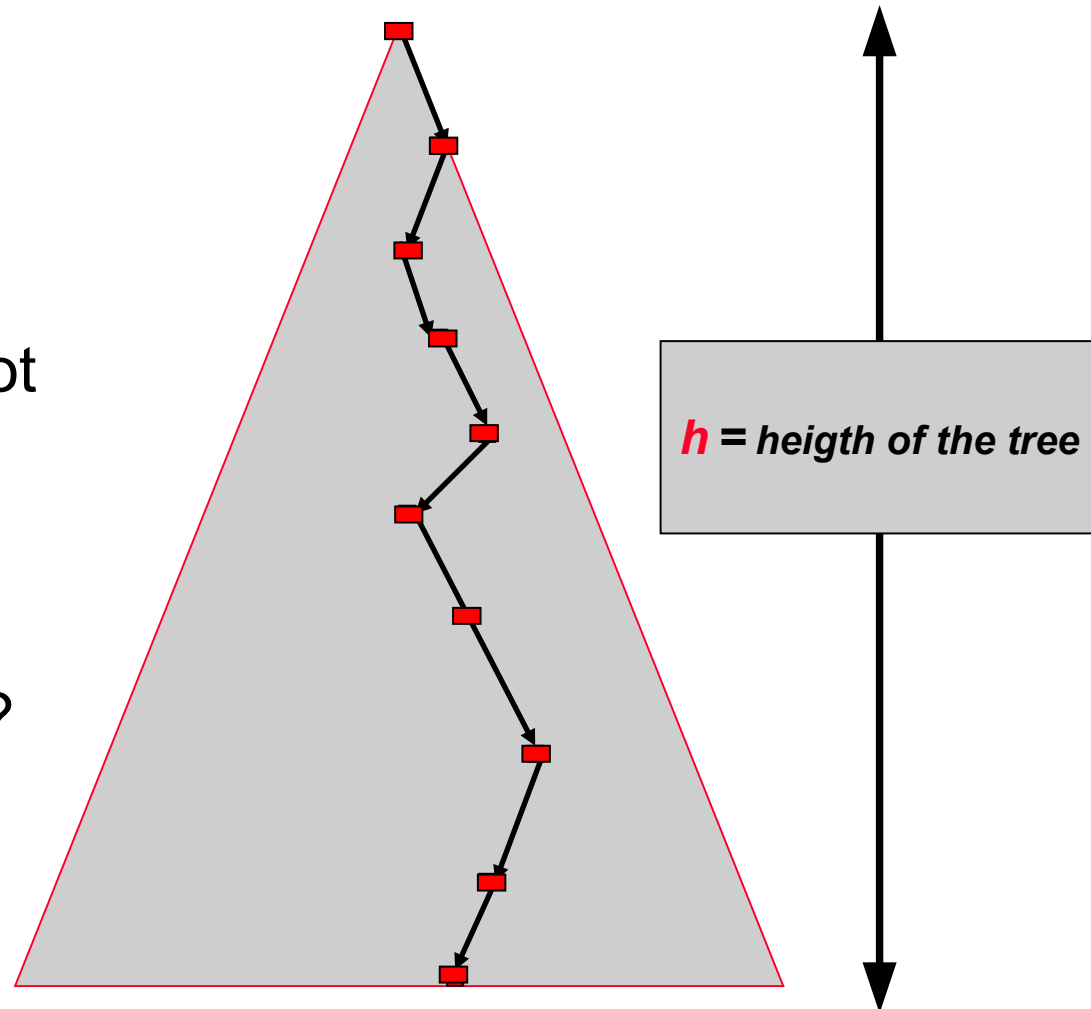
Search of predecessor Pseudo-code (iterative)

```
algorithm BST predecessor(BST T)
  if (T == null) then
    return null;
  endif
  if (T.left ≠ null) then
    return max(T.left);
  else
    P := T.parent;
    while (P ≠ null && T == P.left) do
      T := P;
      P := P.parent;
    endwhile
    return P;
  endif
```



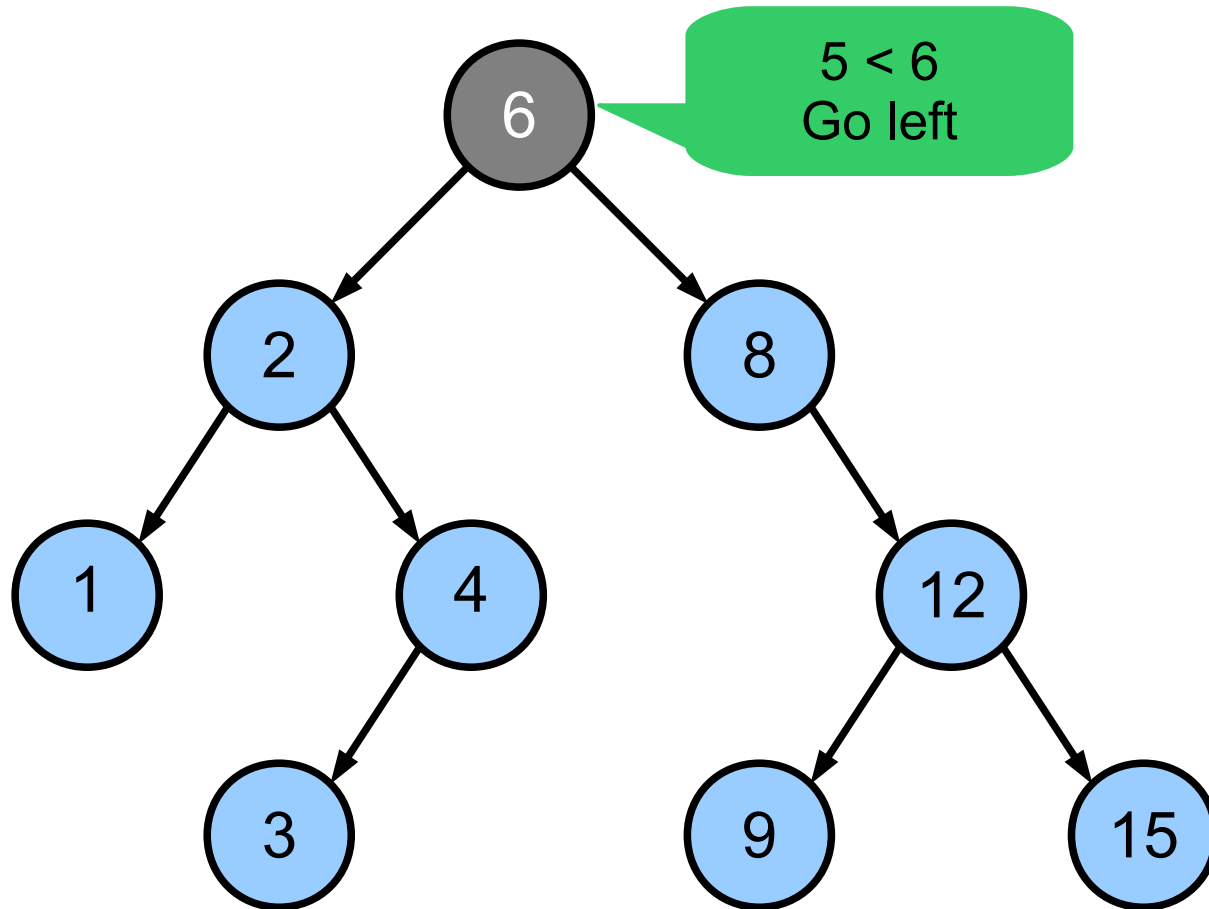
Search: computational cost

- In general
 - Search operations are limited to positions along a single path from the root to the leaf
 - Time needed: $O(h)$
- **question**
 - Which is the Worst case?
- **question**
 - Which is the best case?



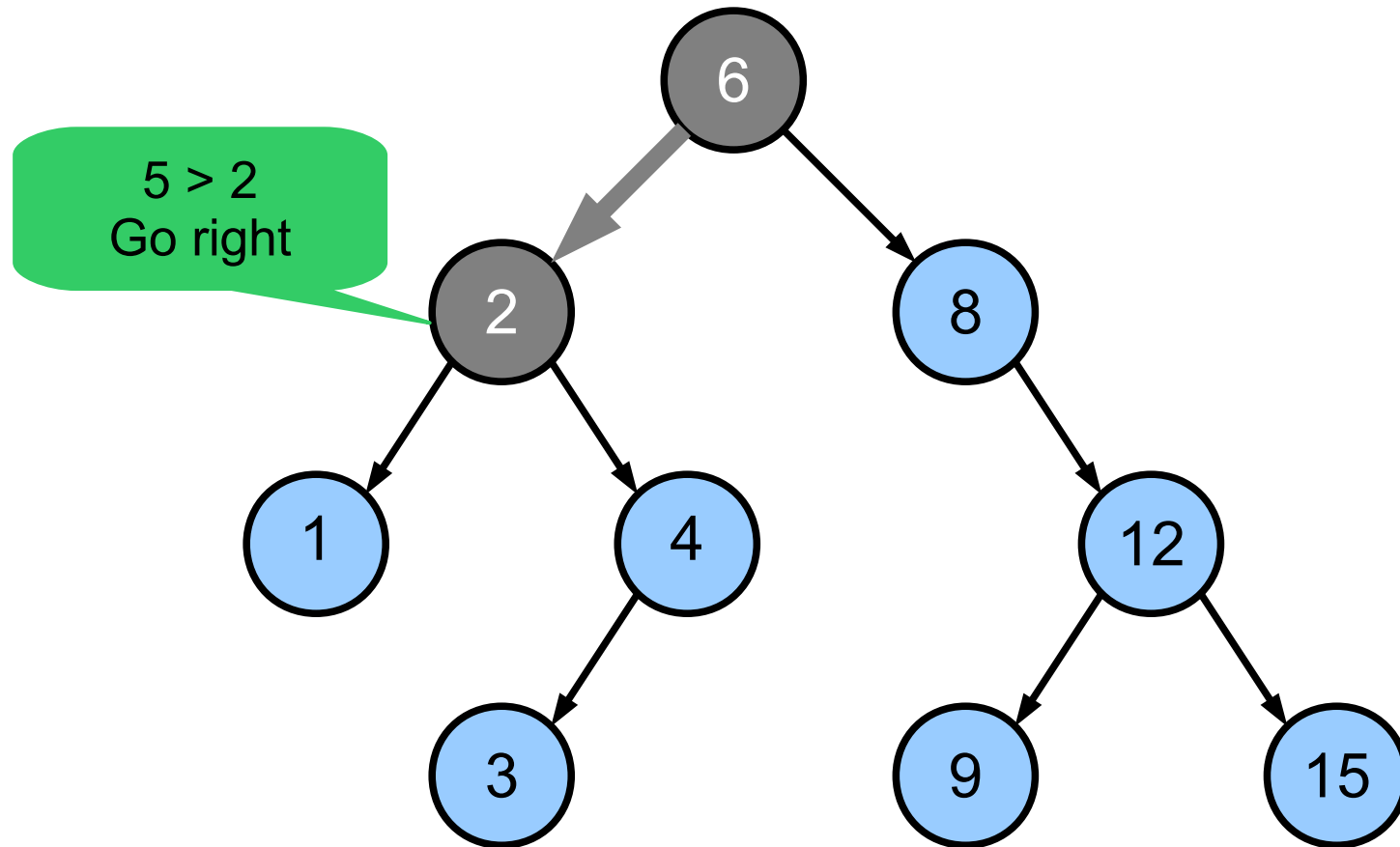
Insertion

Insertion of value 5



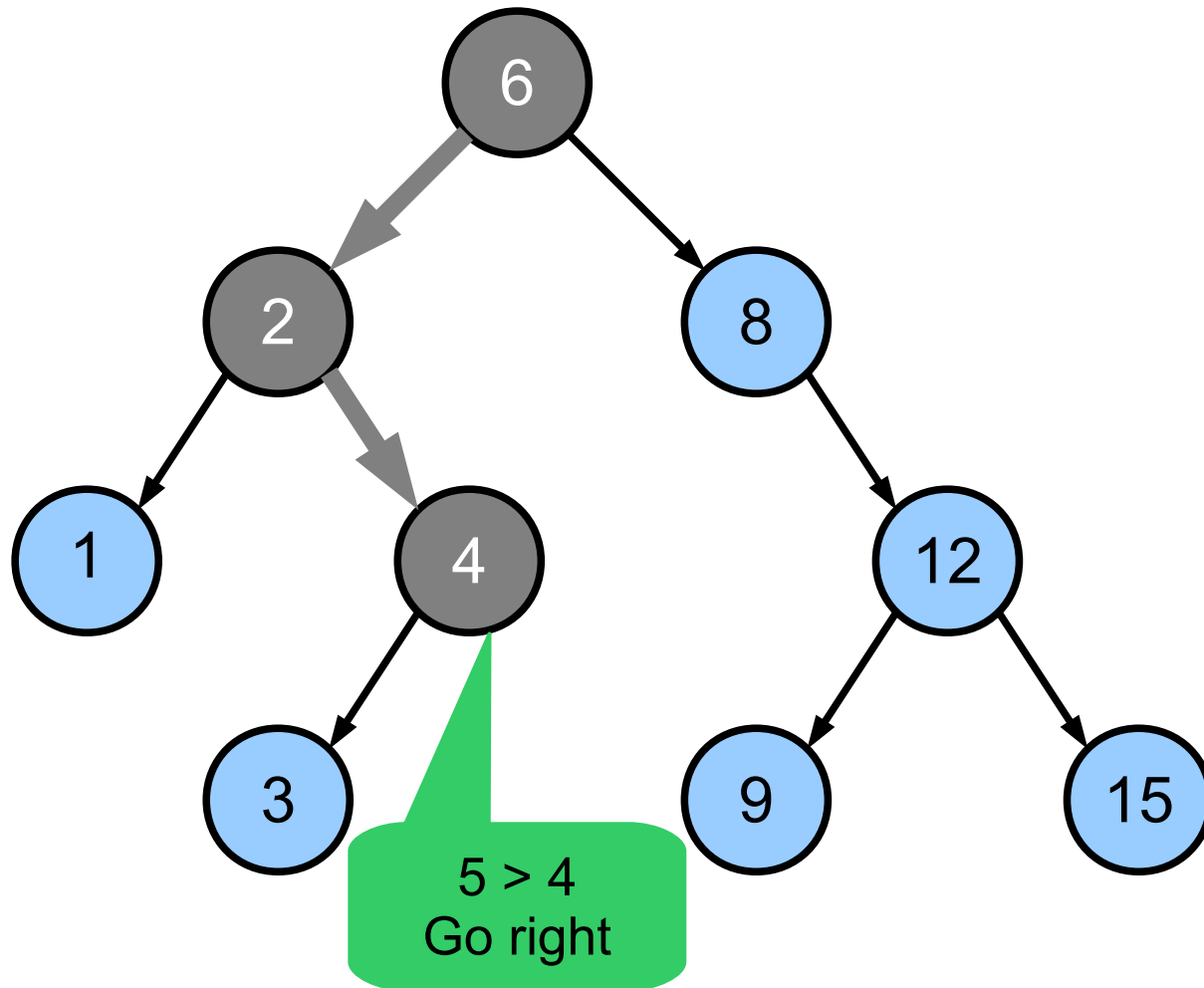
Insertion

Insertion of value 5



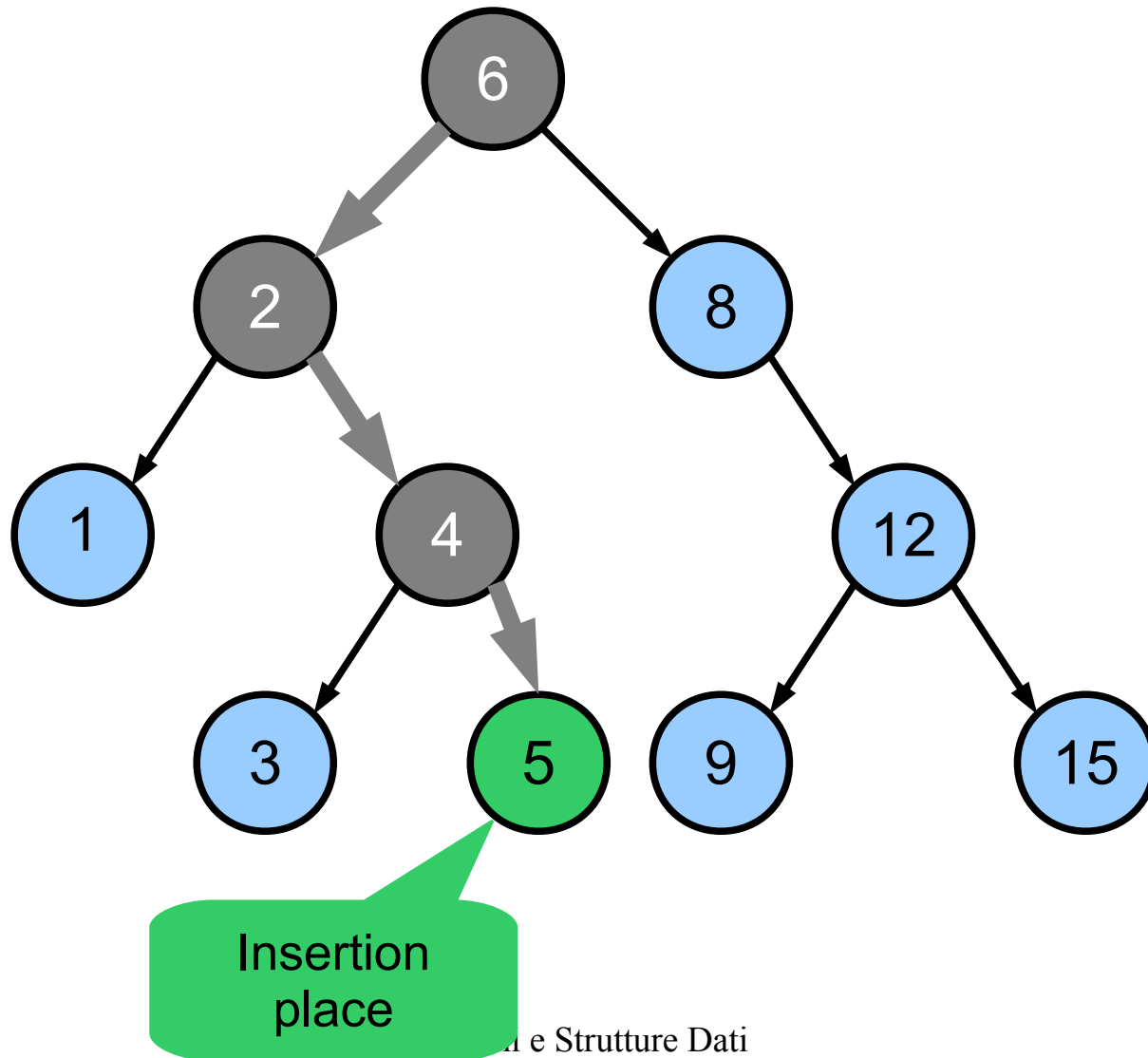
Insertion

Insertion of value 5



Insertion

Insertion of value 5



Insertion: pseudo-code (iterative)

Algorithm BST_insert(BST T, Key k, Data d)

P := nil

```
while (T != null) do
  P := T
  if T.key > key then
    T := T.left
  else
    T := T.right
  endif
endwhile
```

N := new BST(k, d)

N.parent := P

```
if (P == null) then
  return N;
```

```
if (k < P.key) then
  P.left := N
else
  P.right := N
```

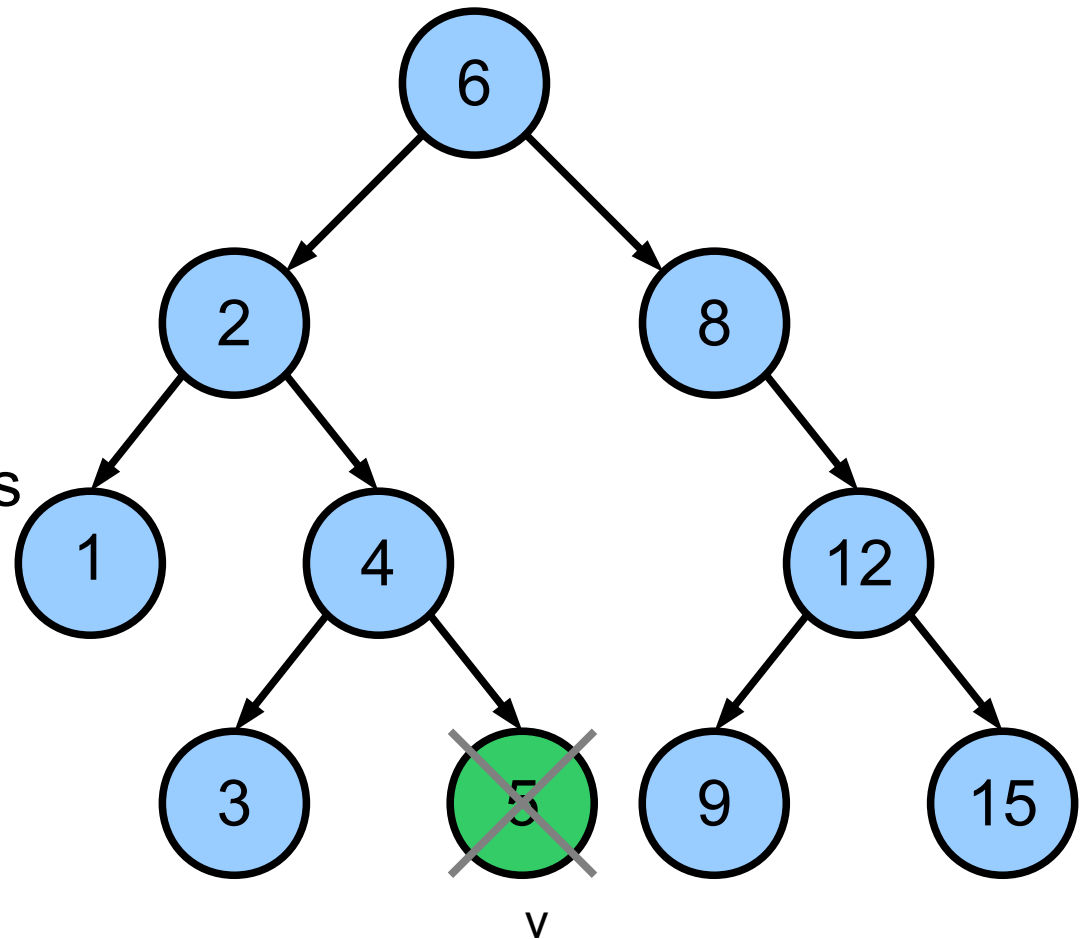
Search position of new node

Base case (insert in empty tree)

General case

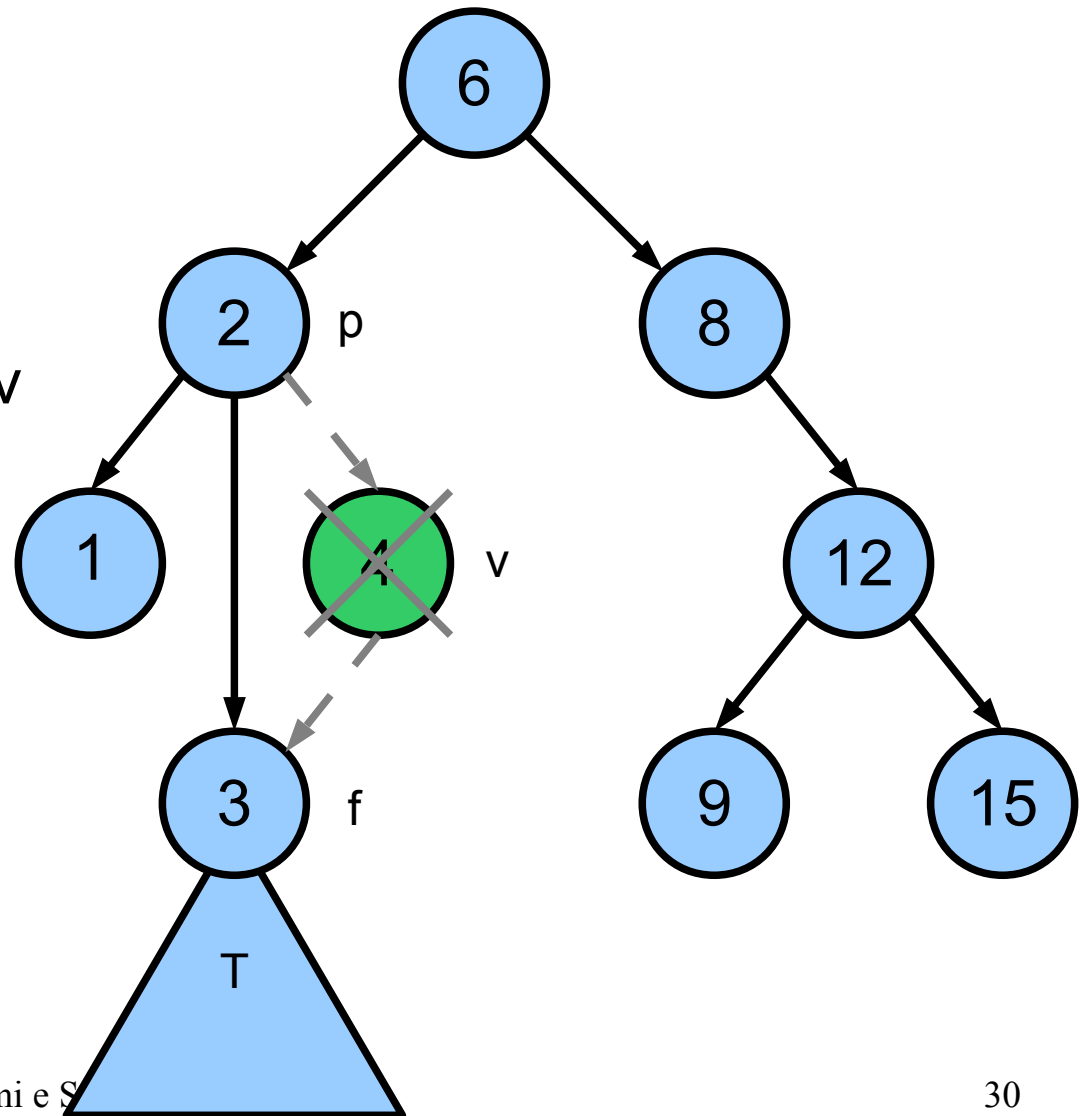
deletion

- Case 1
 - Deleted node v has no children
 - Simply delete it....
- Correctness?
 - Deleting a leaf node does not modify the ordering property of any other node in the BST



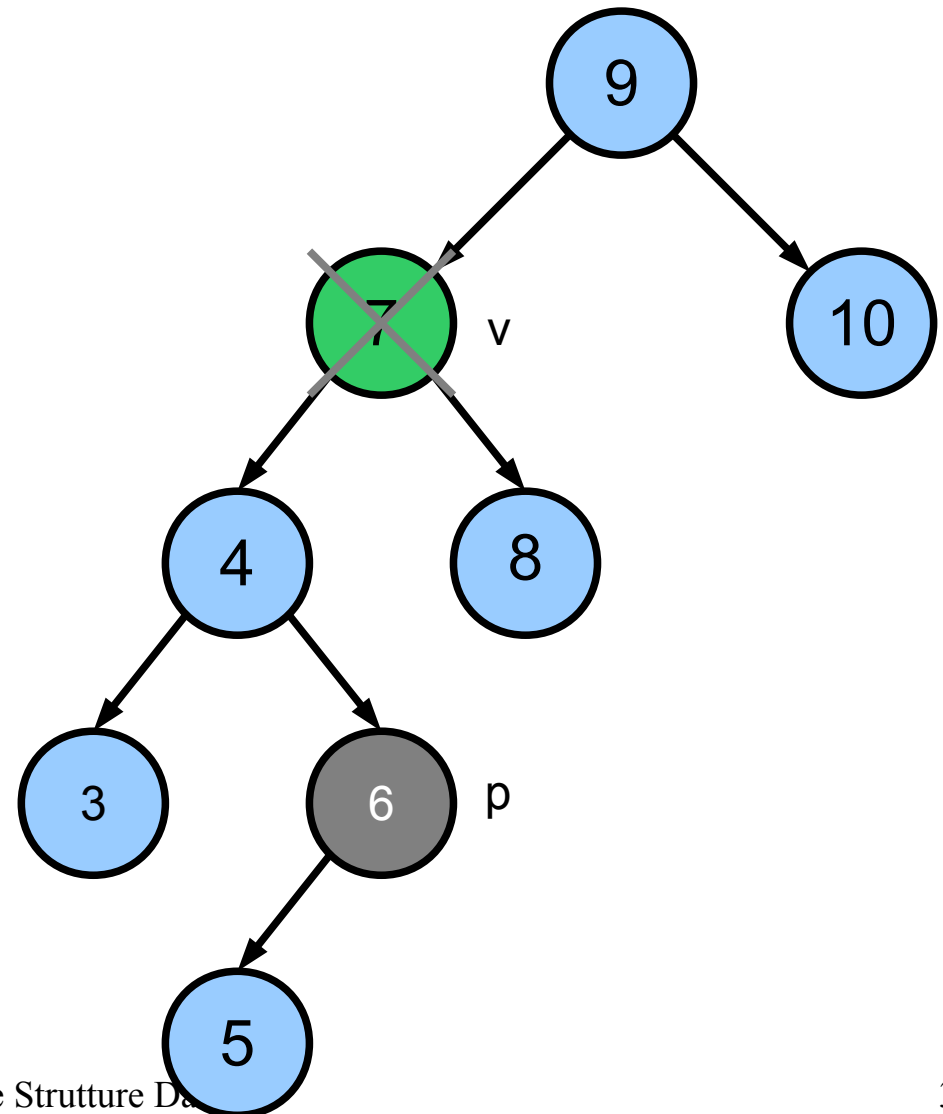
deletion

- Case 2
 - Deleted node v has only one child f
 - delete v
 - attach f to ex-father p of v in substitution of v
- Correctness
 - Given the ordering property, all the key values in subtree T are $\geq p$



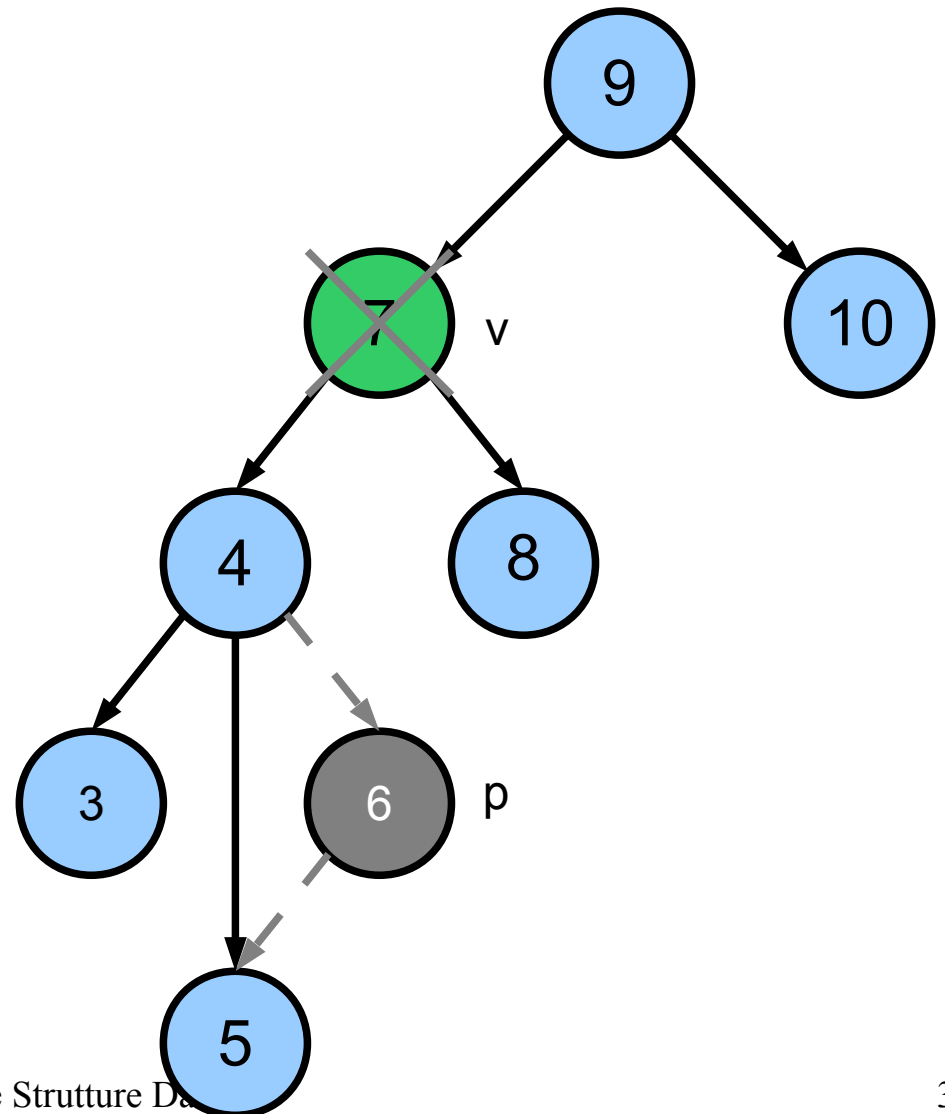
deletion

- Case 3
 - Deleted node v has two children
 - Search predecessor p of v
 - The predecessor p has not a right child
 - why?



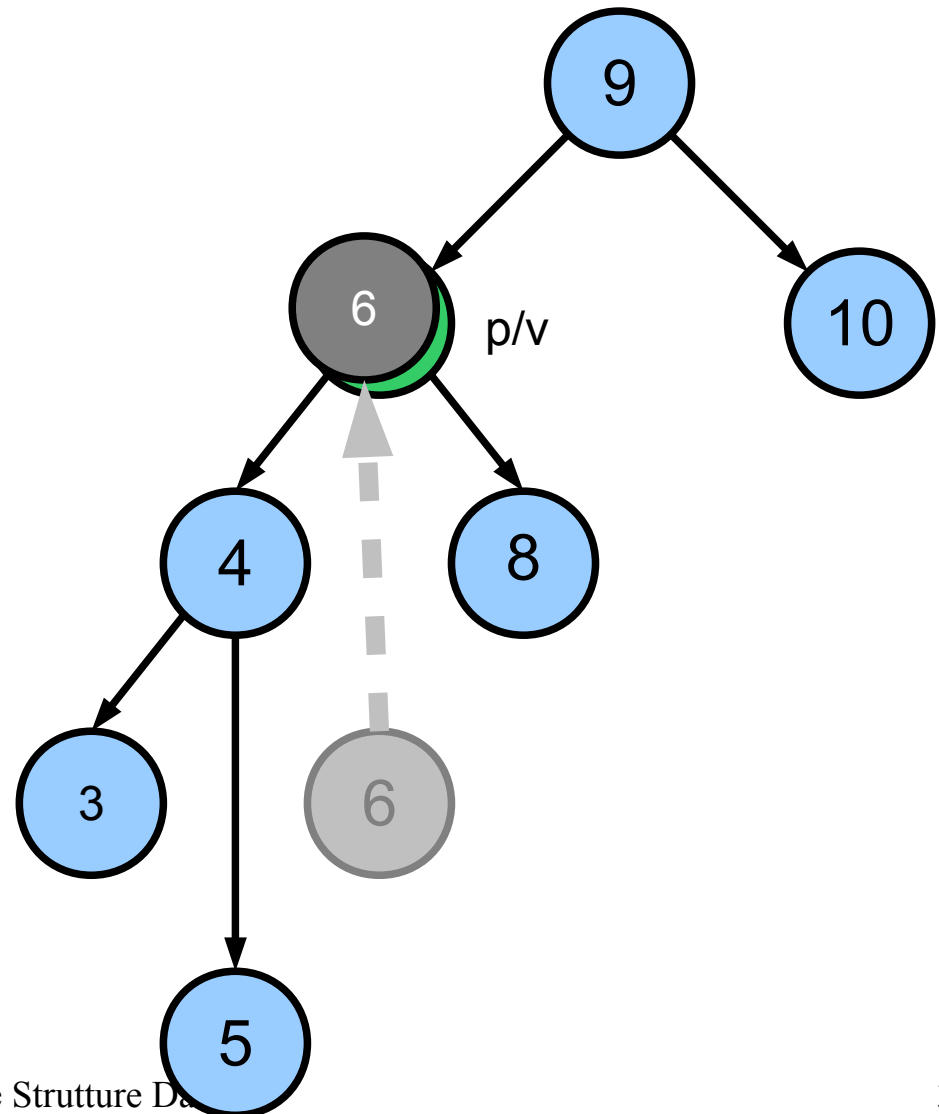
deletion

- Case 3
 - Deleted node v has two children
 - Search predecessor p of v
 - The predecessor p has not a right child
 - Detach the predecessor
 - Attach the (if existing) left child of p to the father of p



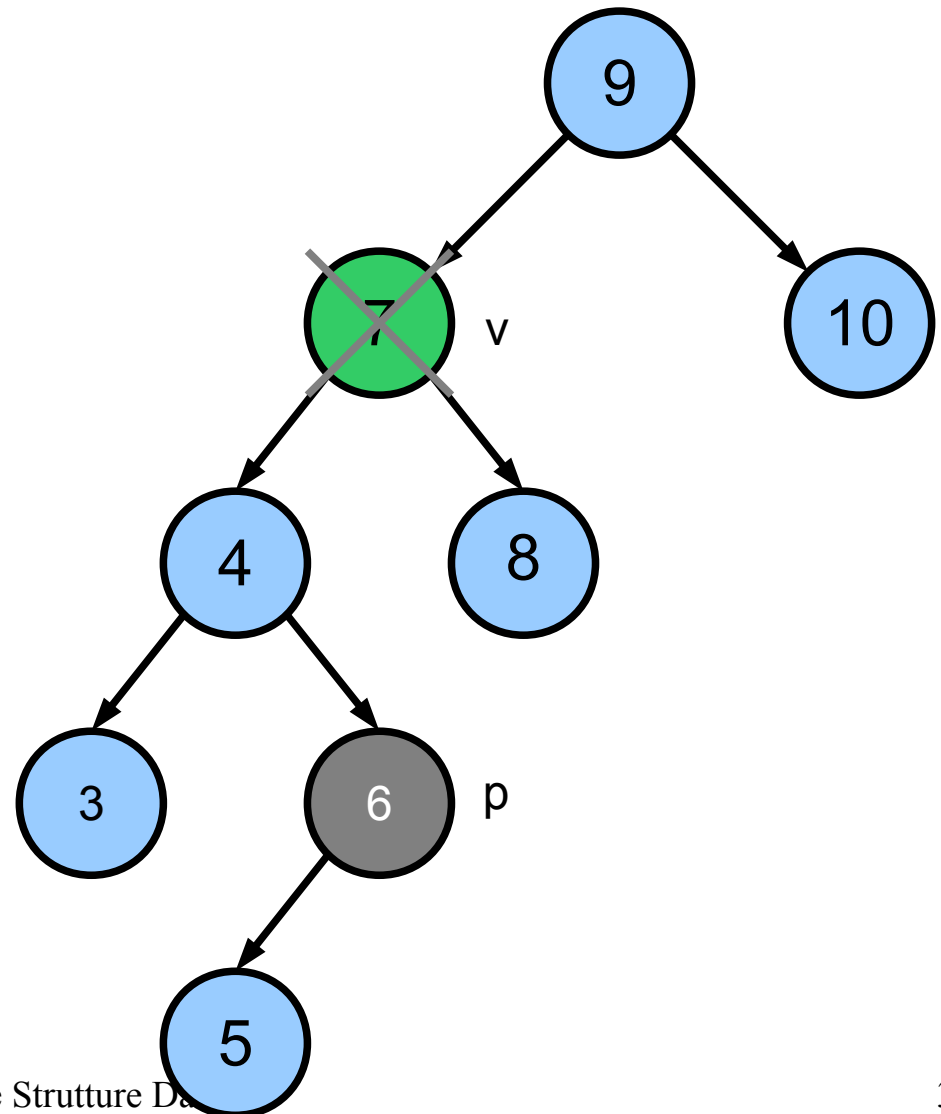
deletion

- Case 3
 - Deleted node v has two children
 - Search predecessor p of v
 - The predecessor p has not a right child
 - Detach the predecessor
 - Attach the (if existing) left child of p to the father of p
 - Copy p on v 's position



deletion

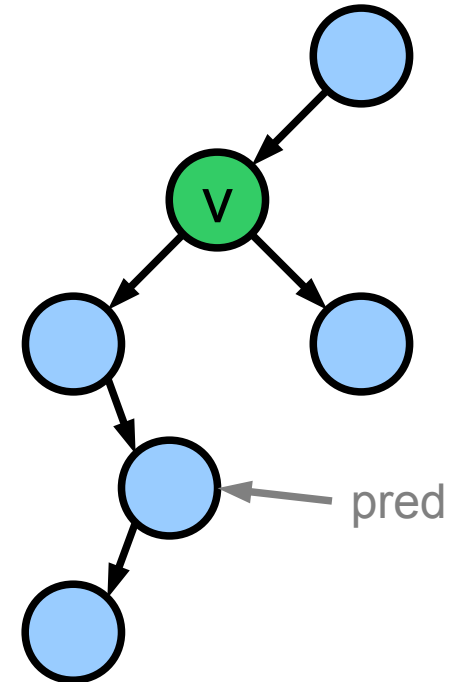
- Case 3 (correctness)
- predecessor p of v
 - Is certainly \geq of all nodes in left subtree of v
 - Is certainly \leq of all nodes in right subtree of v
- Then it CAN be substitute of v



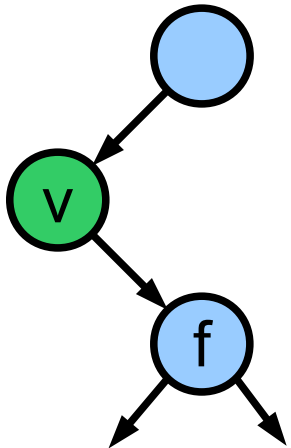
e.g. Java implementation

```
protected Node delete(InfoBR i) {  
    Node v = i.node;  
    if (tree.degree(v) == 2) {  
        Node pred = max(tree.sx(v));  
        exchangeInfo(v, pred);  
        v = pred;  
    }  
    Node p = tree.father(v);  
    compactNode(v);  
    return p;  
}
```

Delete node v
(may have more
than one child)



e.g. Java implementation



```
protected void compactNode(Node v) {
    Node f = null ;
    if (tree.sx(v) != null)
        f = tree.sx(v);
    else
        if (tree.dx(v) != null)
            f = tree.dx(v);
    if (f == null)
        tree.cut(v);
    else {
        exchangeInfo(v, f);
        BinTree a = tree.cut(f);
        tree.innestSx(v, a.cut(a.sx(f)));
        tree.innestDx(v, a.cut(a.dx(f)));
    }
}
```

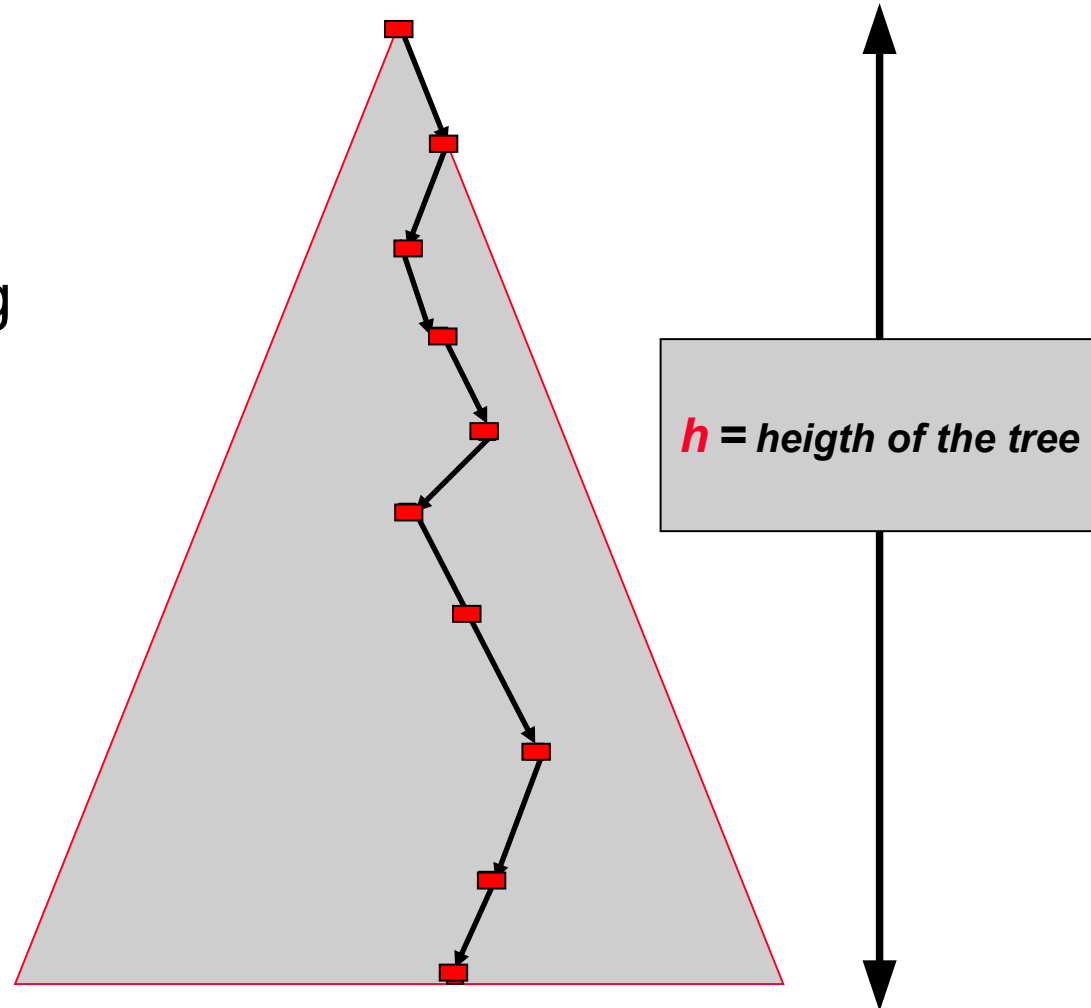
Delete node v
(has at most one
child)

v has no
children

Detach
subtree
rooted in f

Modify: computational cost

- In general
 - Modify operations are located in positions along a single path from root to leaf
 - Time complexity: $O(h)$



Average complexity

- What is the average height of a BST?
 - General case (generalized insertions + deletions)
 - Hard to define
 - Simple case: random insertions
 - We can show that average height is $O(\log n)$
- In general:
 - We need techniques to keep the tree balanced
 - Example of such implementations
 - AVL tree (Adelson-Velsky, Landis)
 - Red-Black Tree
 - Splay Tree
 - We will see in the next slides.

Some nice exercises

- **Exercise**
 - Write a non recursive algorithm to visit (in-order) a BST
- **Exercise**
 - Proof that any algorithm based on comparisons to realize a BST is $\Omega(n \log n)$
 - hint: sorting based on comparison of n elements is $\Omega(n \log n)$, so ...
- **Exercise**
 - Proof that if a BST node has two children, then the successor has not left child, and the predecessor has not right child

More exercises

- **Exercise**
 - The visit of a BST can be done by finding the minimum element and then calling $n-1$ times the successor().
 - Proof that this algorithm is $\Theta(n)$
- **Exercise**
 - Write a recursive version of insert()
- **Exercise**
 - Is the BST deletion property commutative? In other words, delete(x), delete(y) provides the same result as delete(y), delete(x) for any x,y?