On Composing Communicating Systems

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ICE - June 17, 2022

The need of systems composability

- Concurrent/Distributed systems are **not**

  STAND-ALONE ENTITIES

- (expecially nowadays) they are parts of

  JIGSAWS NEVER COMPLETELY TERMINATED

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Composability is useful both

- at design phase (modular design);
- at deployment phase and beyond
  - modular deployment;
  - new functionalities needed;
  - system scalability
  - etc.

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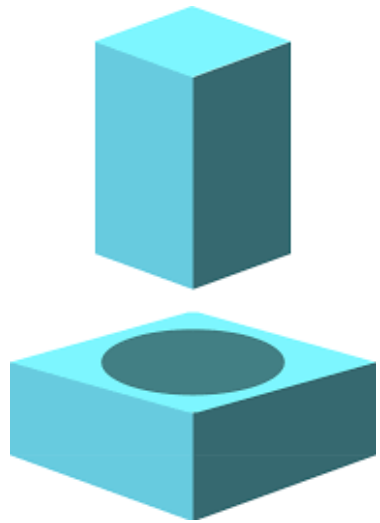
Good composition methods

They should be

- FLEXIBLE



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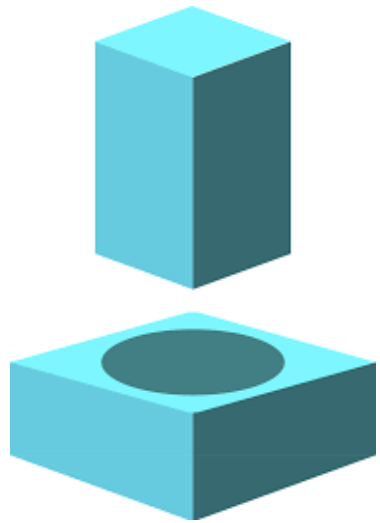

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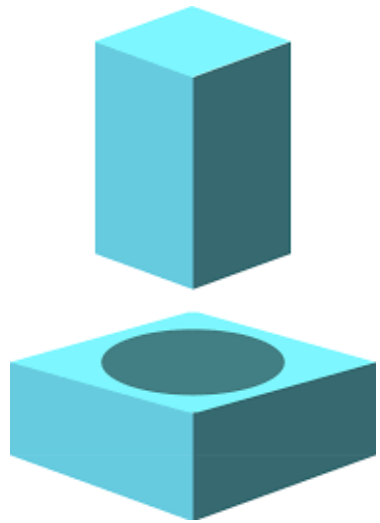

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Good composition methods are **safe**

If one starts from something like this....

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...should not end up with something like that

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Good composition methods are **safe**

Safe composition methods guarantee not to “break” any relevant property of the single systems we compose.

Good composition methods are **flexible**

A **flexible** composition method

- alters as less as possible the single systems
- is "system independent", that is
  - the composition mechanism is not part of the system
  - it allows to consider any system as potentially open

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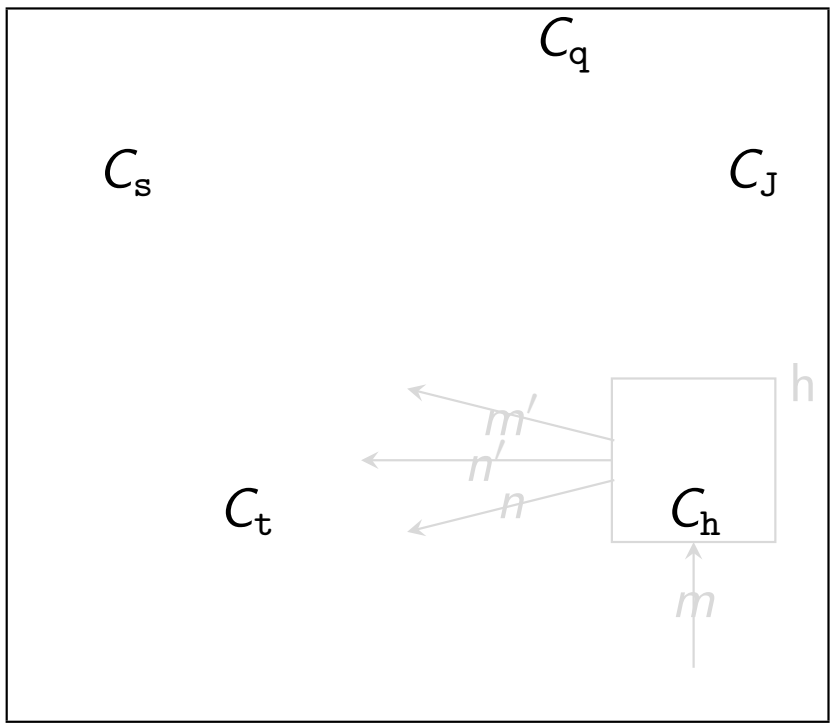
The "participants-as-interfaces" (PaI) approach

For systems with message-passing interactions

The "participants-as-interfaces" (PaI) approach

S_1



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C_h's behaviour can be looked at as what can be offered by an outer system

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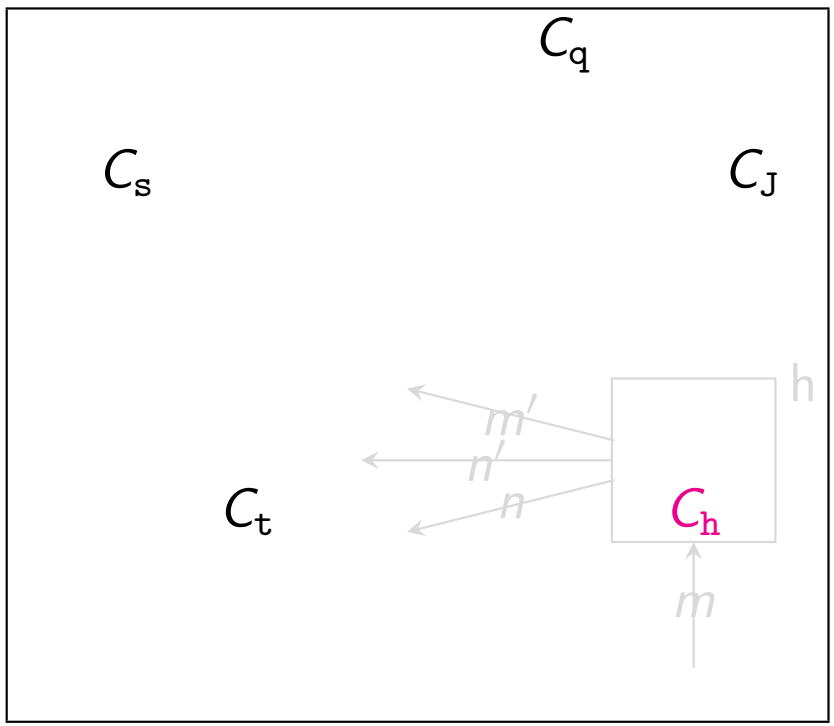

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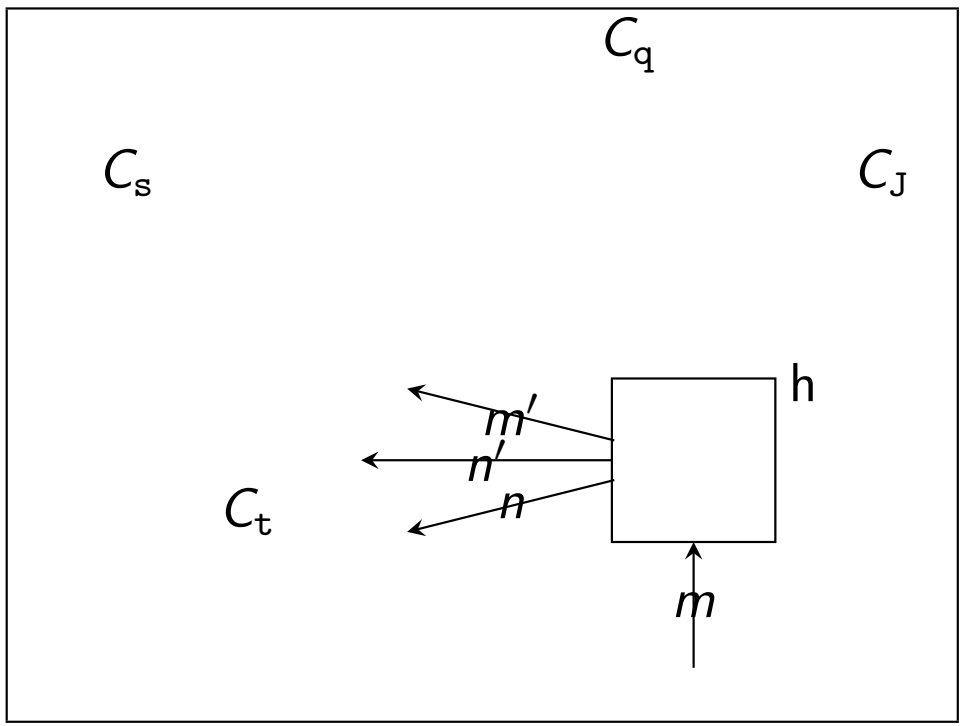

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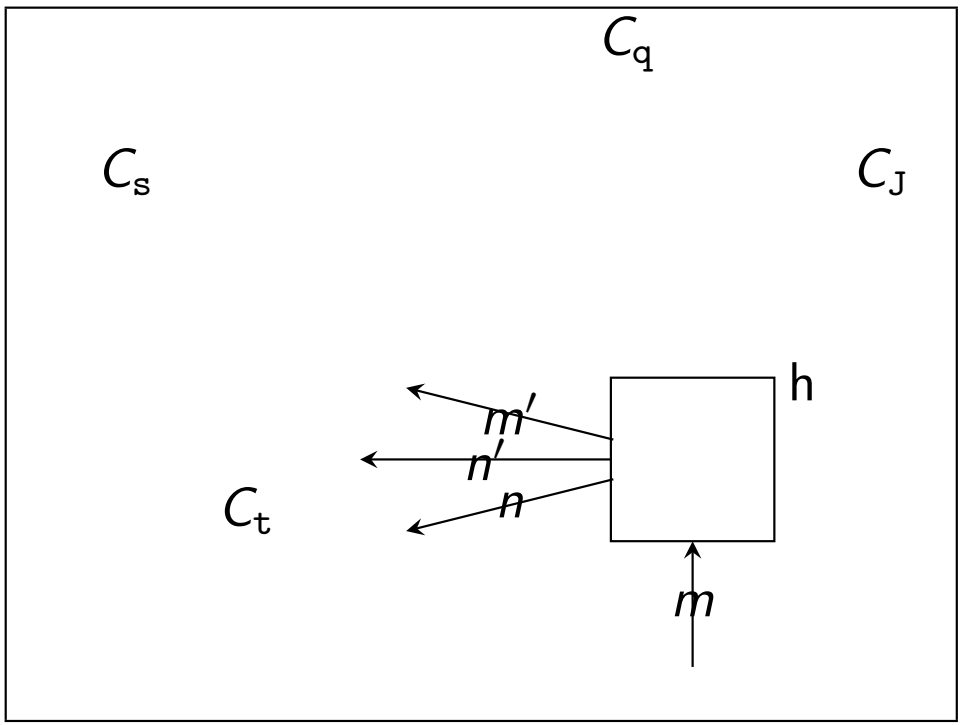

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We abstract here from the way communications are performed and from the logical order of the exchanged messages. C_h's behaviour can be looked at as what can be offered by an outer system.

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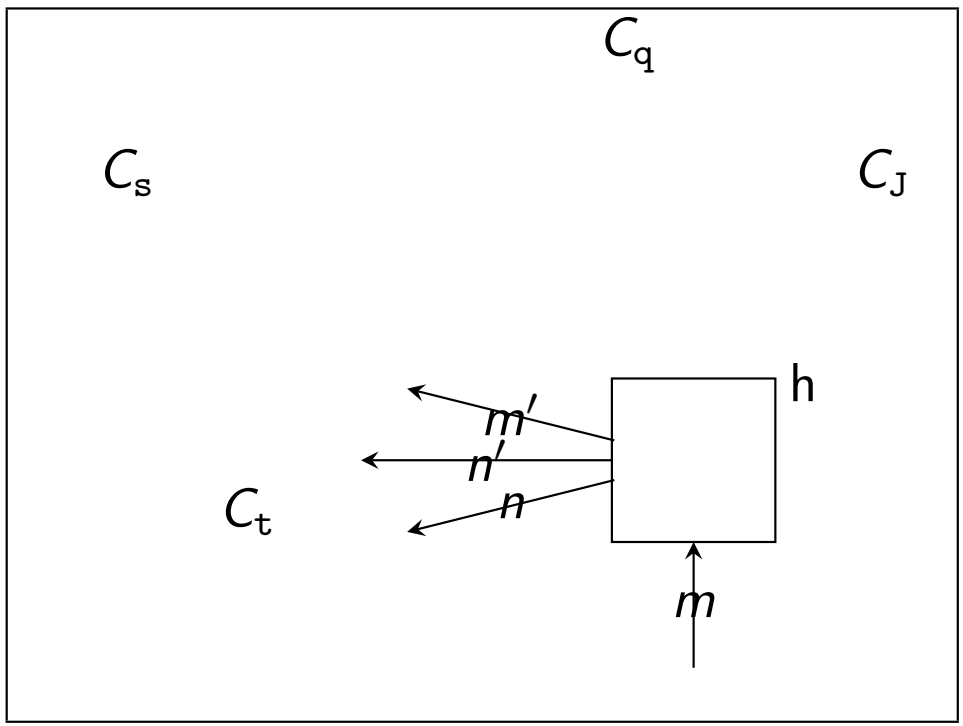

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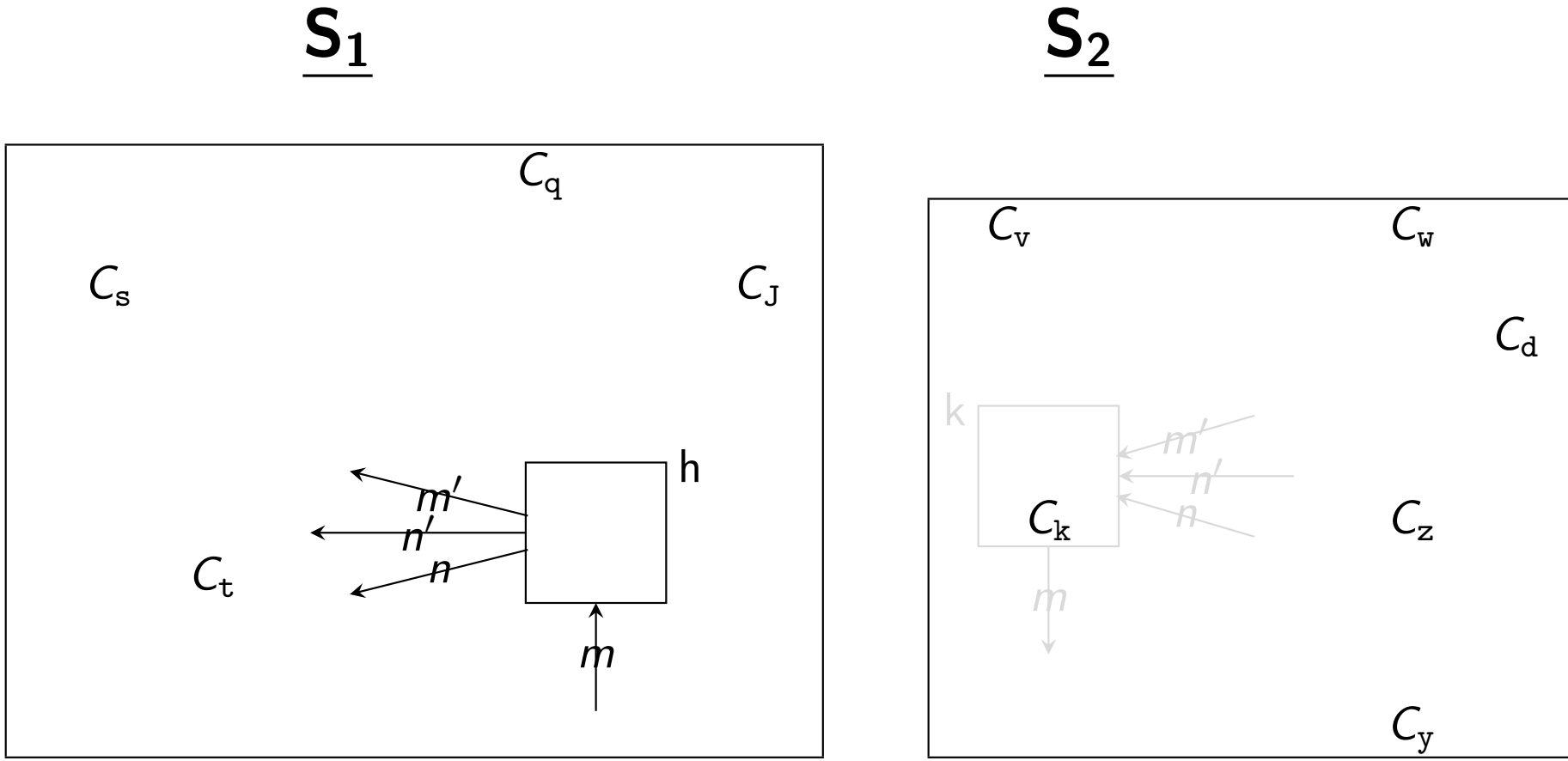

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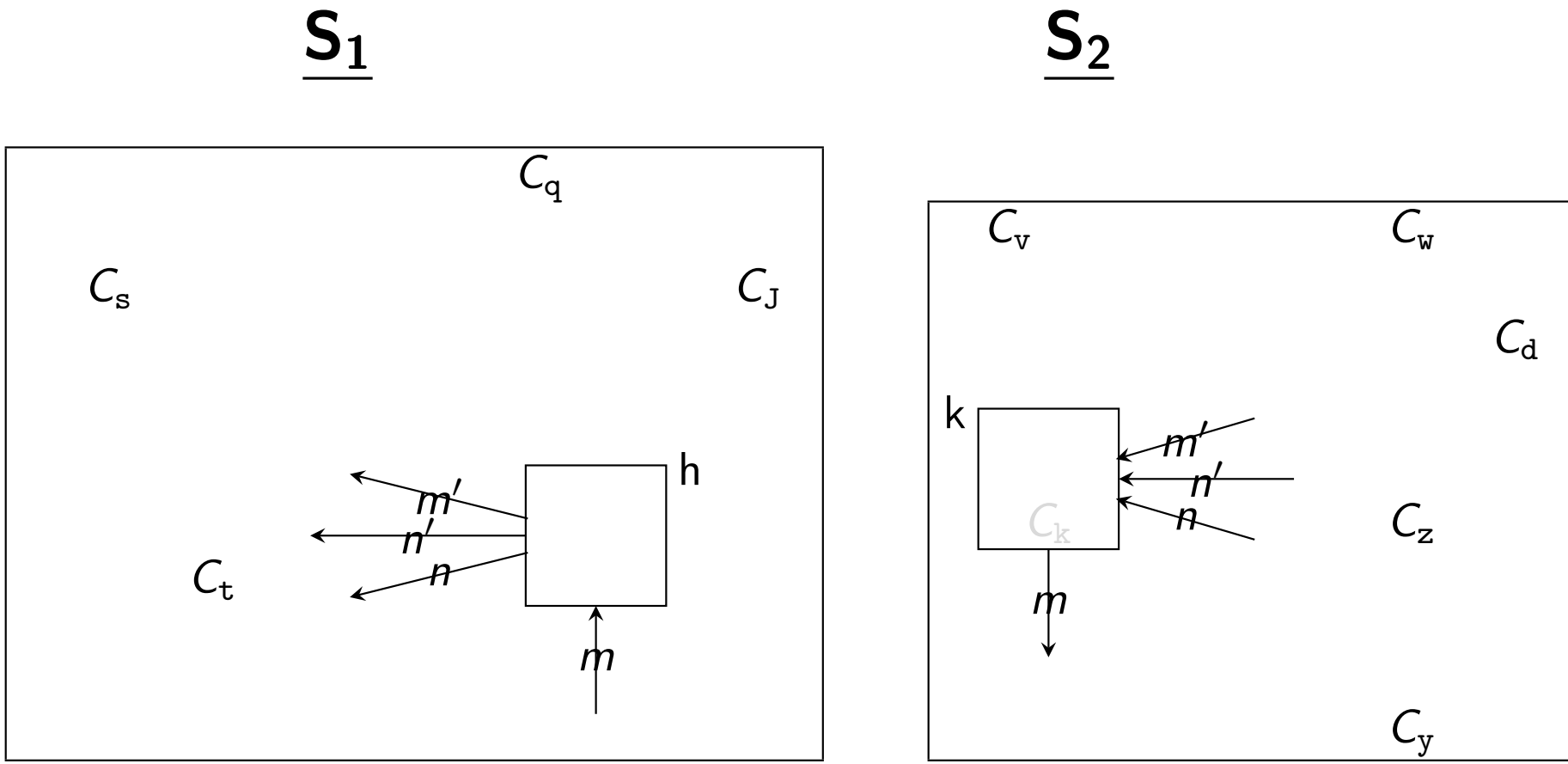

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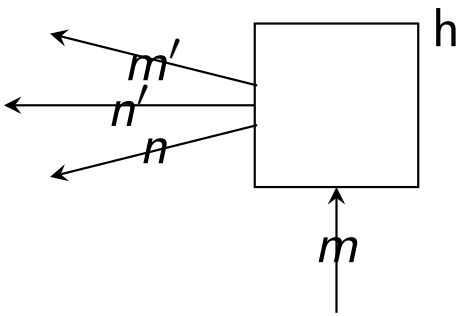

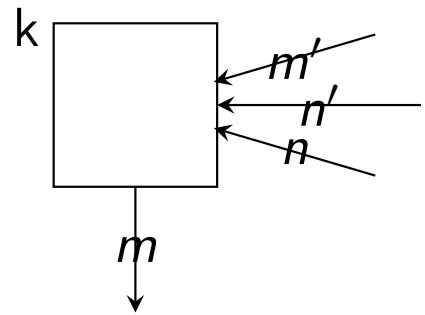

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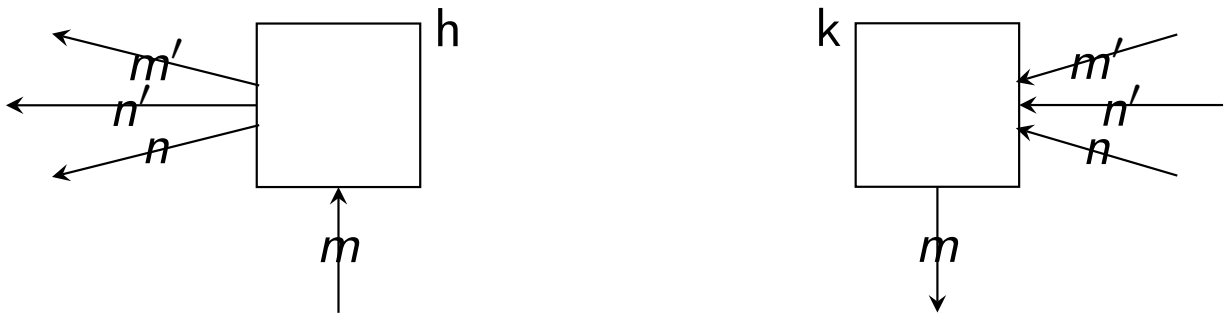

COMPATIBLE: an h's input is a k's output, and vice versa

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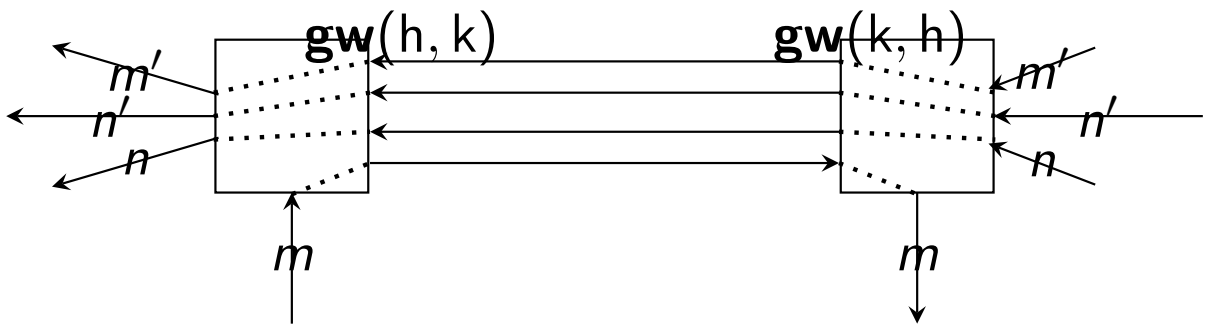

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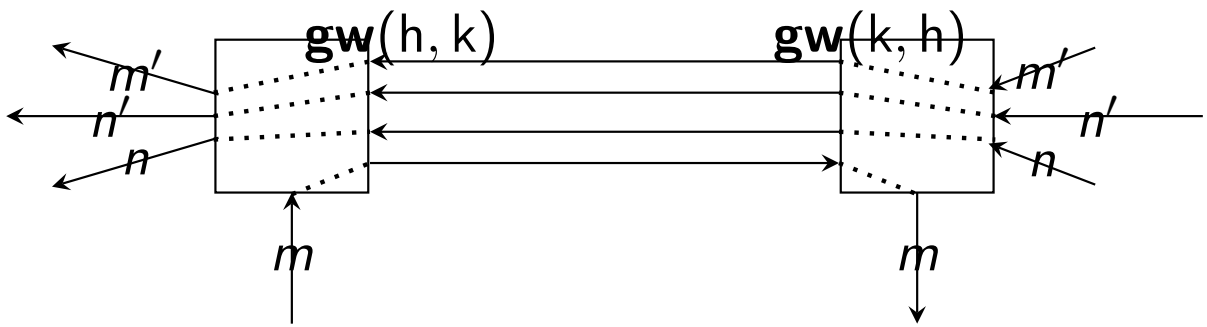
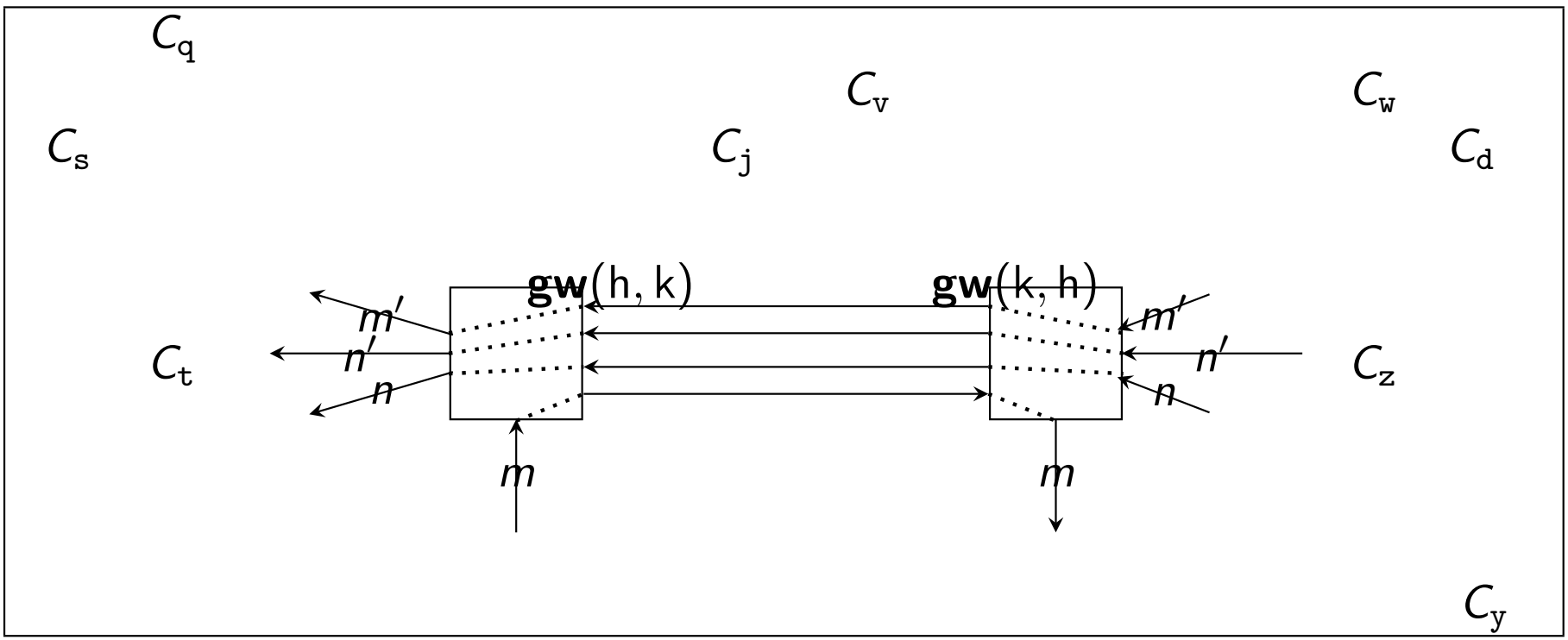


Composition via gateways (forwarders)

The "components-as-interfaces" (PaI) approach

$$\underline{\mathbf{S_1}} \; \mathrm{J}\!\!\not\!\!\mapsto\!\!\not\!\!\mathrm{K} \; \underline{\mathbf{S_2}}$$



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Investigating the PaI approach:
which formalism for participants' behaviours?

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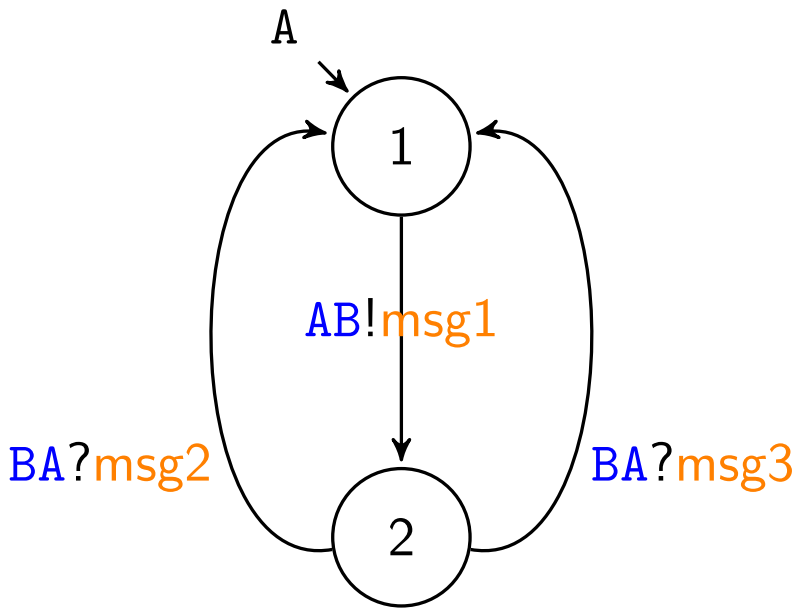

Communicating Finite State Machines (CFSMs)

An **automata-based** formalism for the description and the analysis of distributed systems. [Brand and Zafiropulo, 1983]

A machine $M_{\mathtt{A}}$

- $M_{\mathtt{A}}$ can send msg1 to machine $M_{\mathtt{B}}$;
- Then, either msg2 or msg3 can be received from $M_{\mathtt{B}}$;
- and so on....

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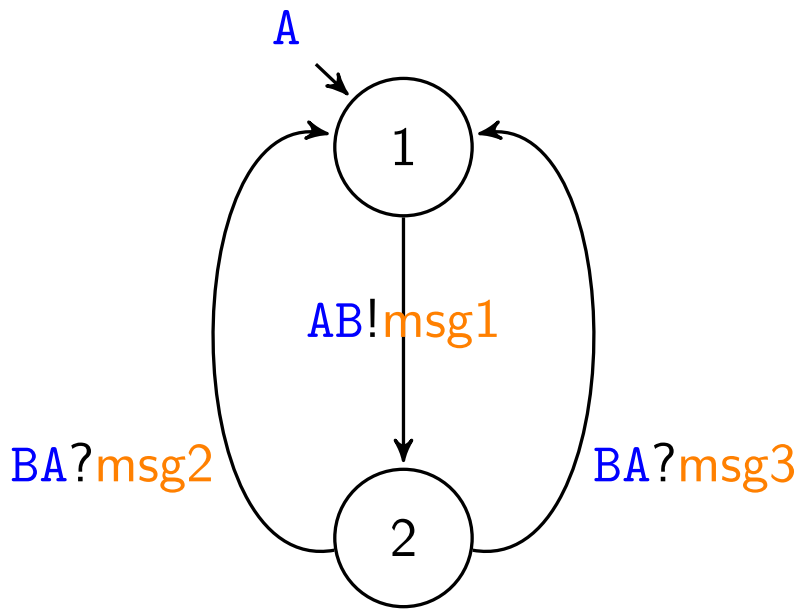

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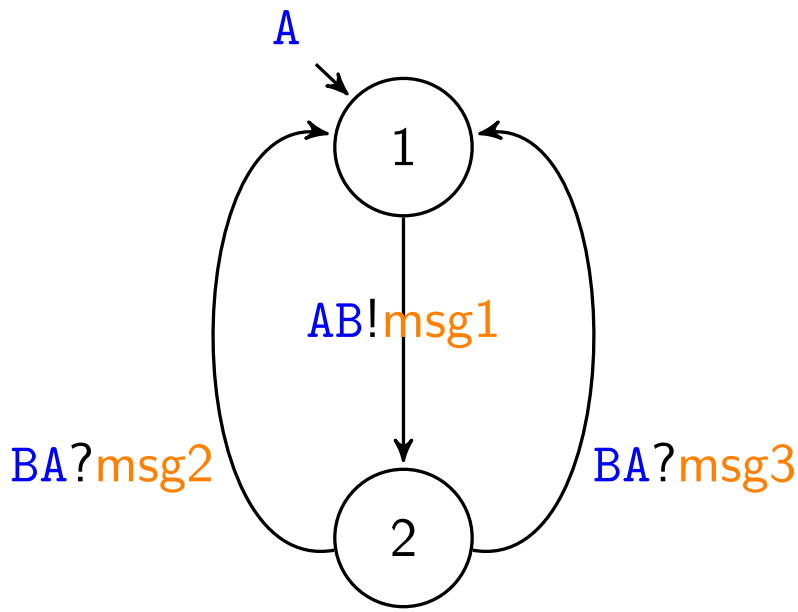

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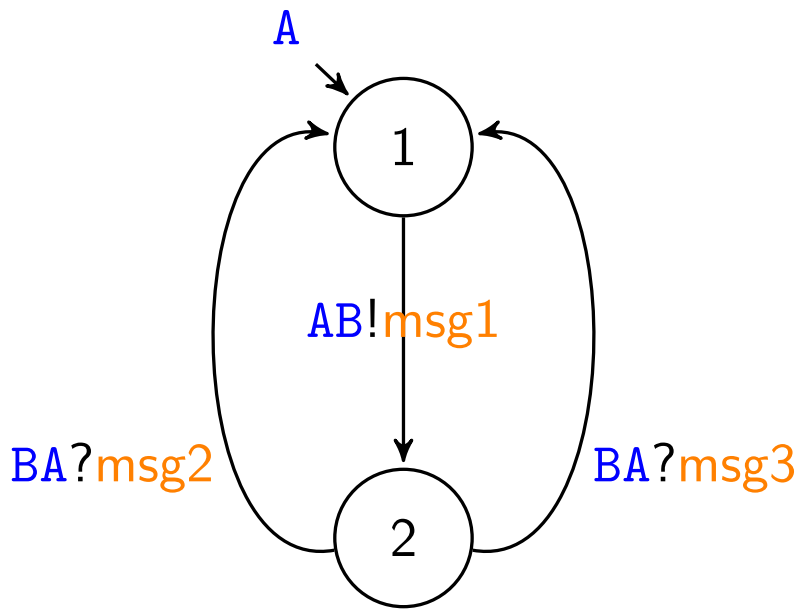

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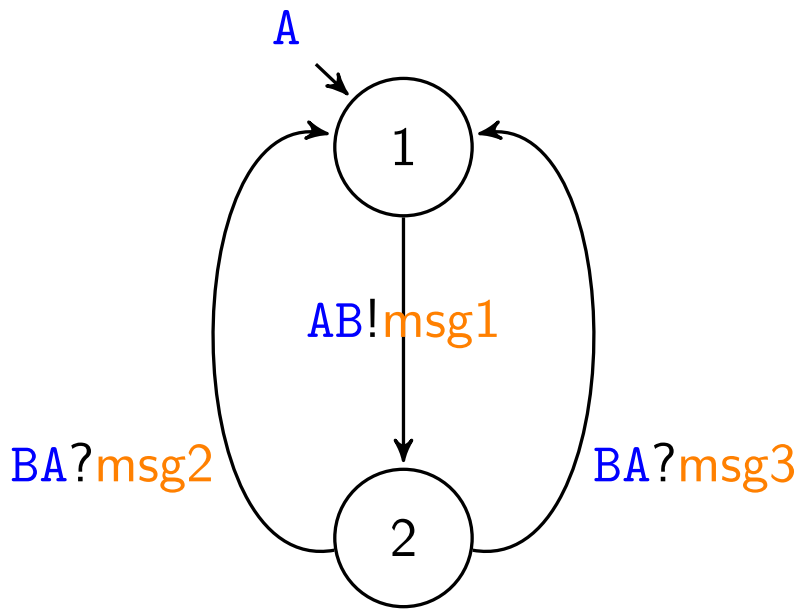

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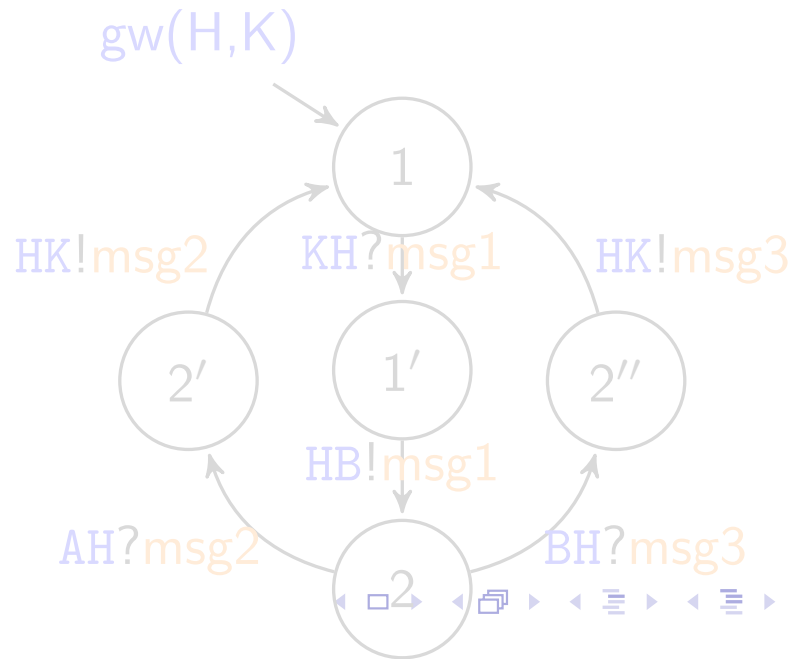
The PaI approach for systems of CFSMs

An "interface" participant like

Is replaced by



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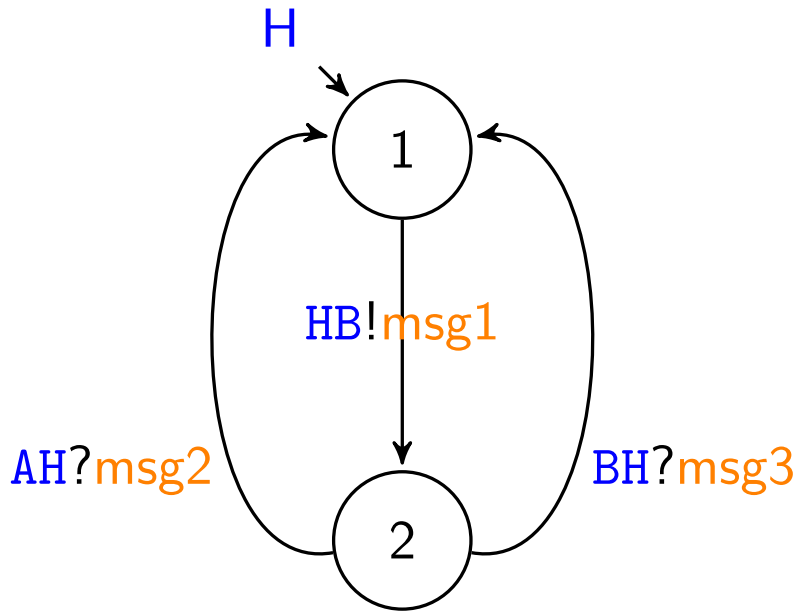

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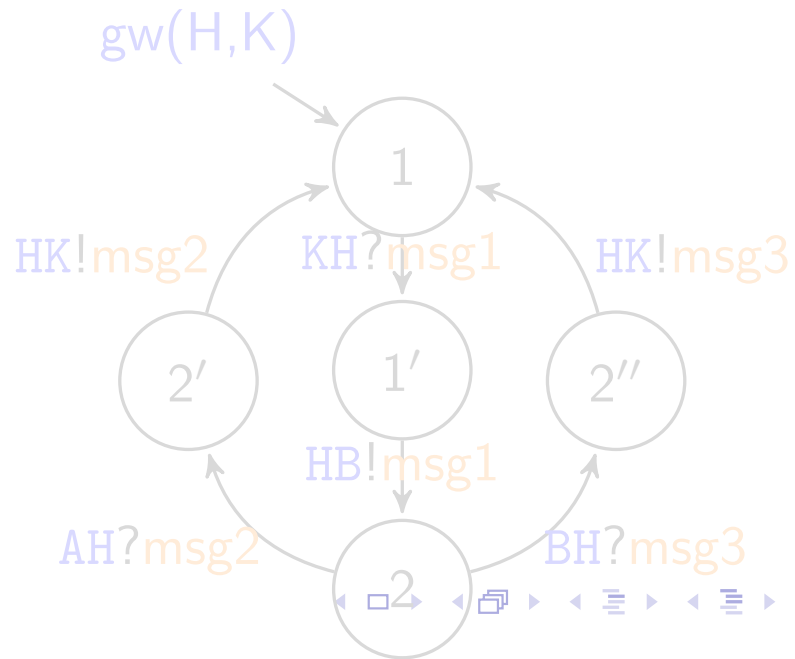

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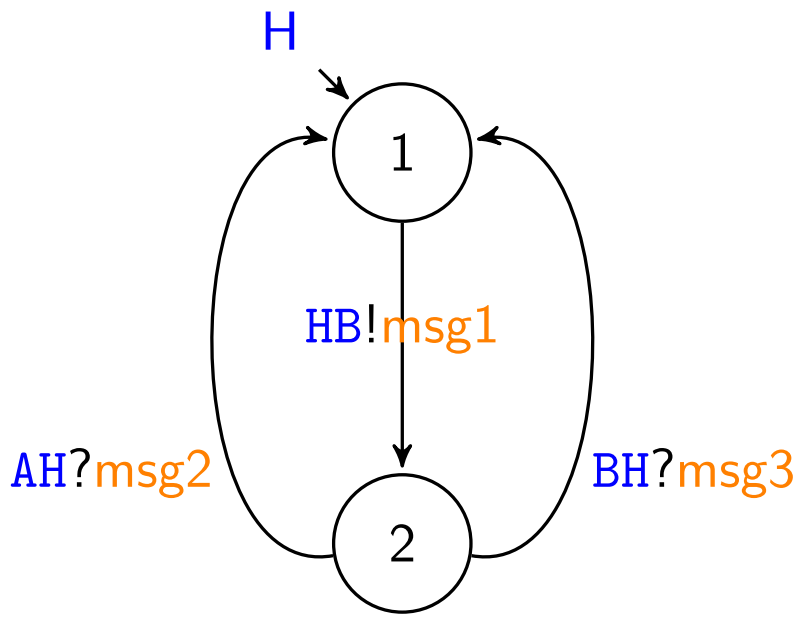

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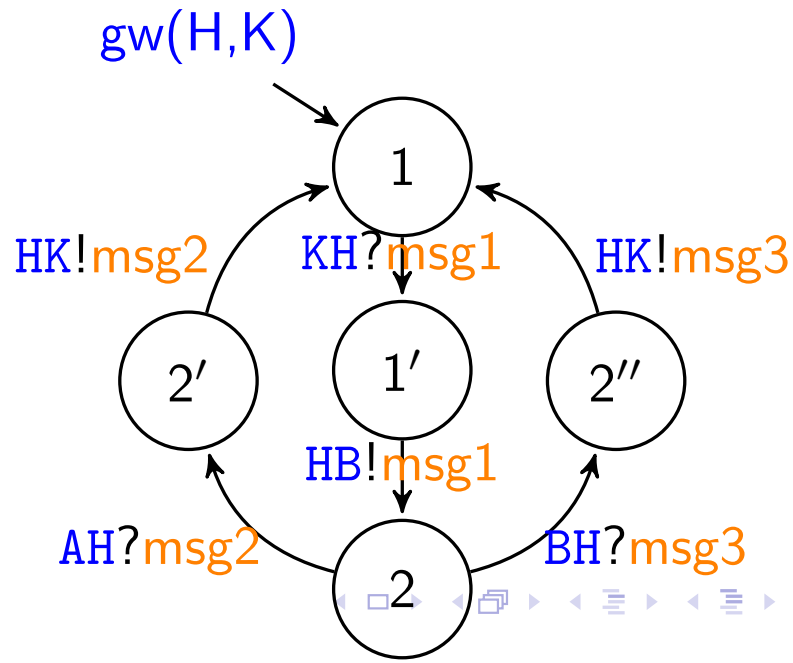

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Which underlying interaction model?

- **asynchronous**; *through the directed buffered FIFO channels (also other possibilities)*
- **synchronous**; *also for this, there is not just one formalization*

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PaI Composition of Systems of **asynchronous** CFSMs

Barbanera, de'Liguoro, Hennicker

> Connecting open systems of communicating finite state machines (JLAMP)

Several communication properties preserved by composition:

- deadlock freedom
- orphan message freedom
- unspecified reception
- progress

Required conditions on interfaces, besides **compatibility** (essentially bisimulation)

- **!(?)-determinism**: the message does uniquely determine the receiver(sender)
- **no-mixed-state**: from each state, either input or output actions, not both.

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And for systems of **symmetric synchronous** CFSMs?

What is a synchronous communication (in the CFSM model)?
The **symmetric** approach:

sender and receiver play the same role in an interaction.

Any choice is "external" ("agreed upon").

In a sense, in CCS style

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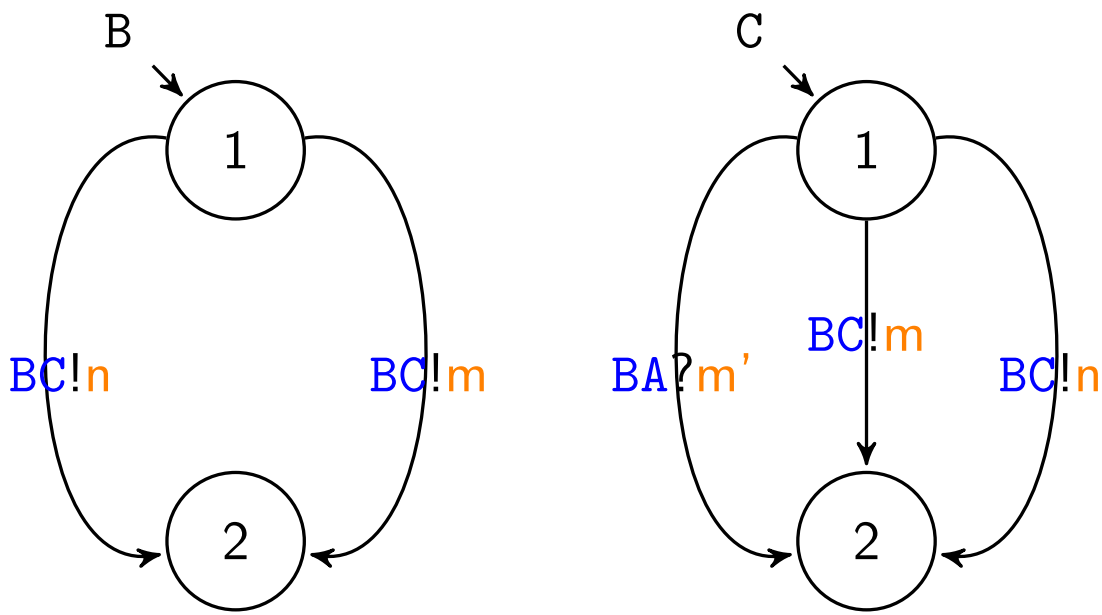

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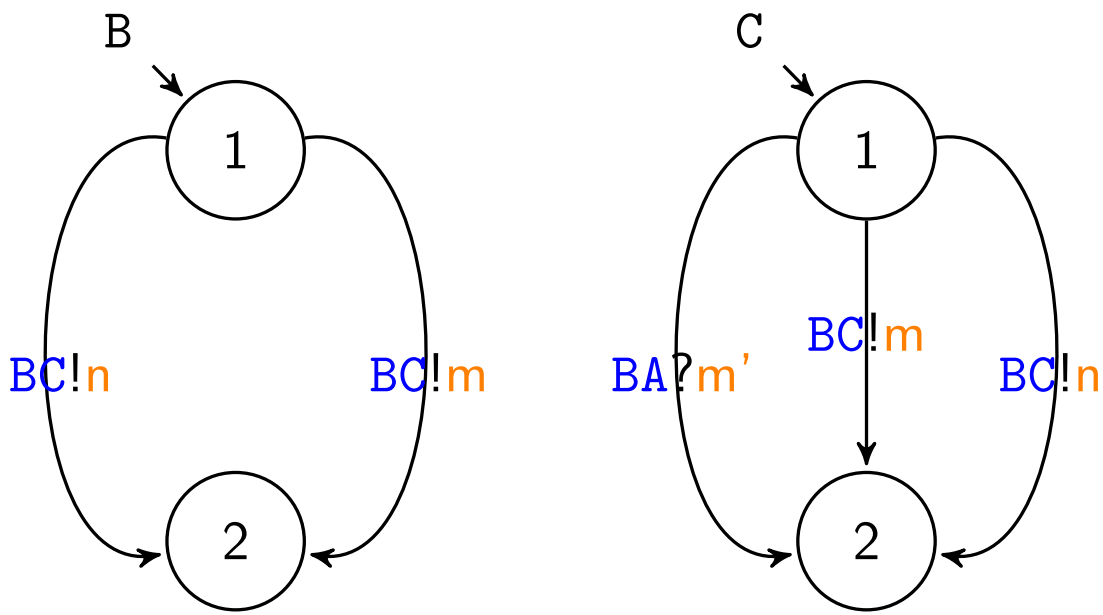

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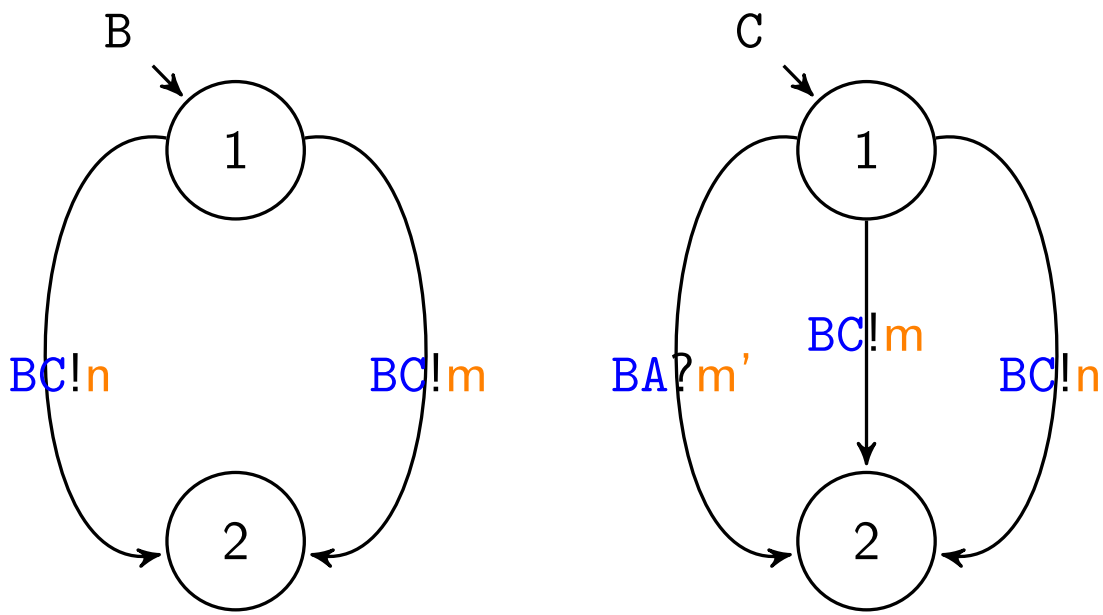

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Composing systems of **symmetric synchronous** CFSMs

Barbanera, Lanese, Tuosto

> Composing Communicating Systems, Synchronously.
> ISoLA (1) 2020

where

- Compatibility = Bisimulation (forgetting senders and receivers, and exchanging '!' and ''?' on one side);
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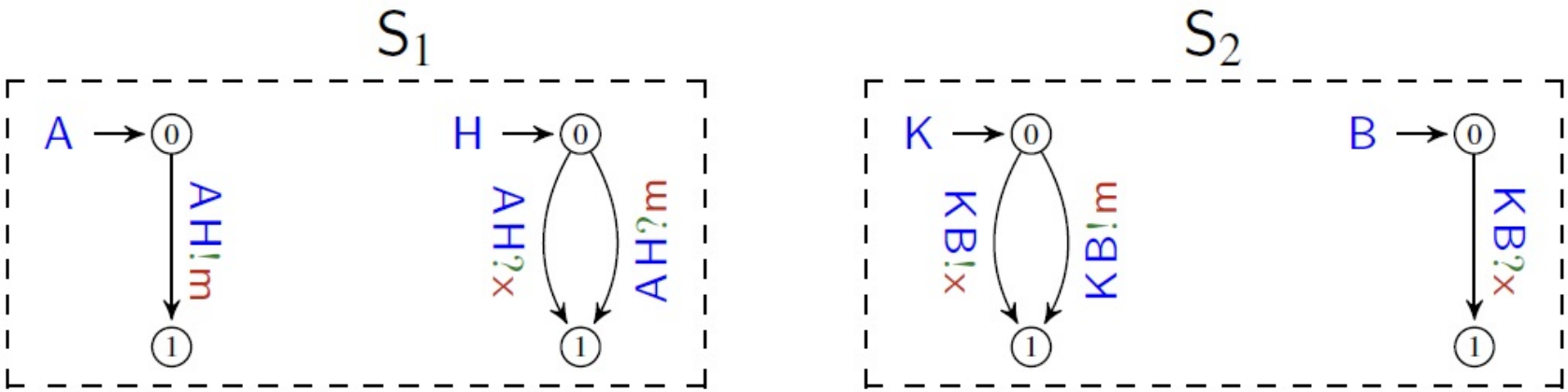

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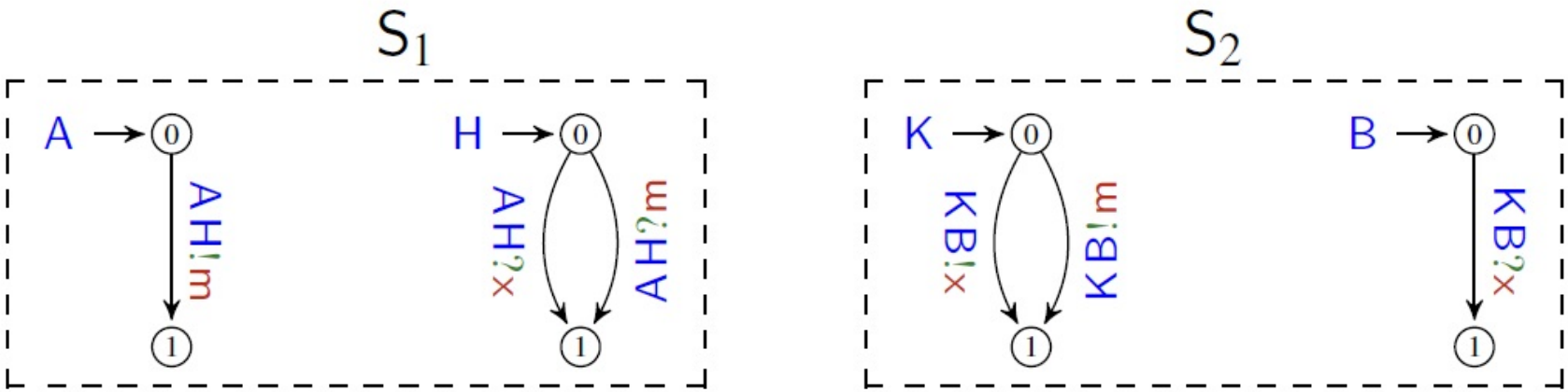

Both deadlock-free

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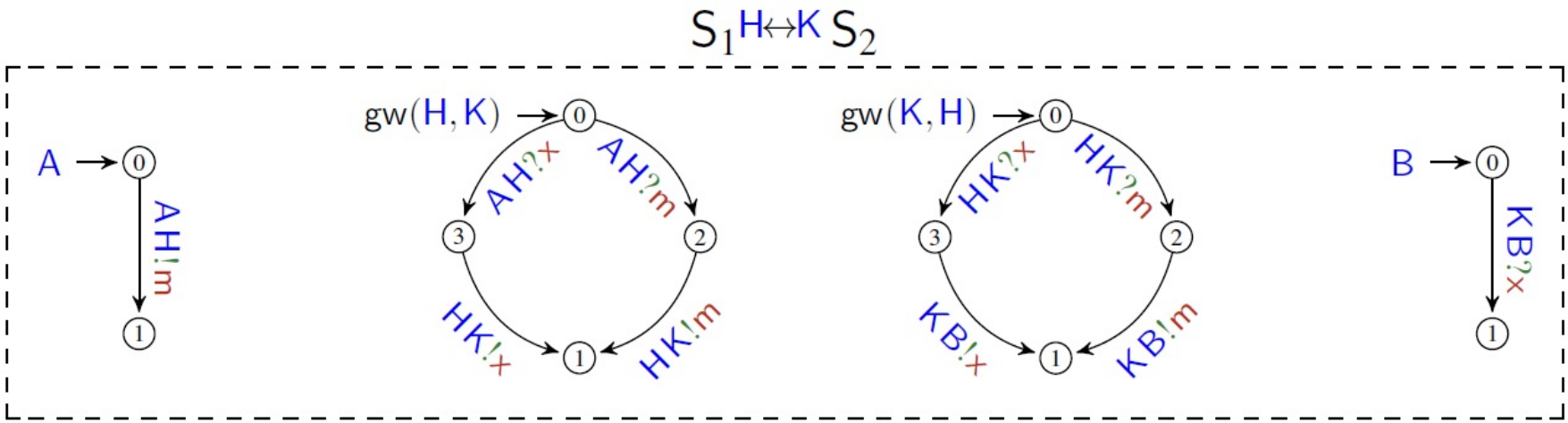

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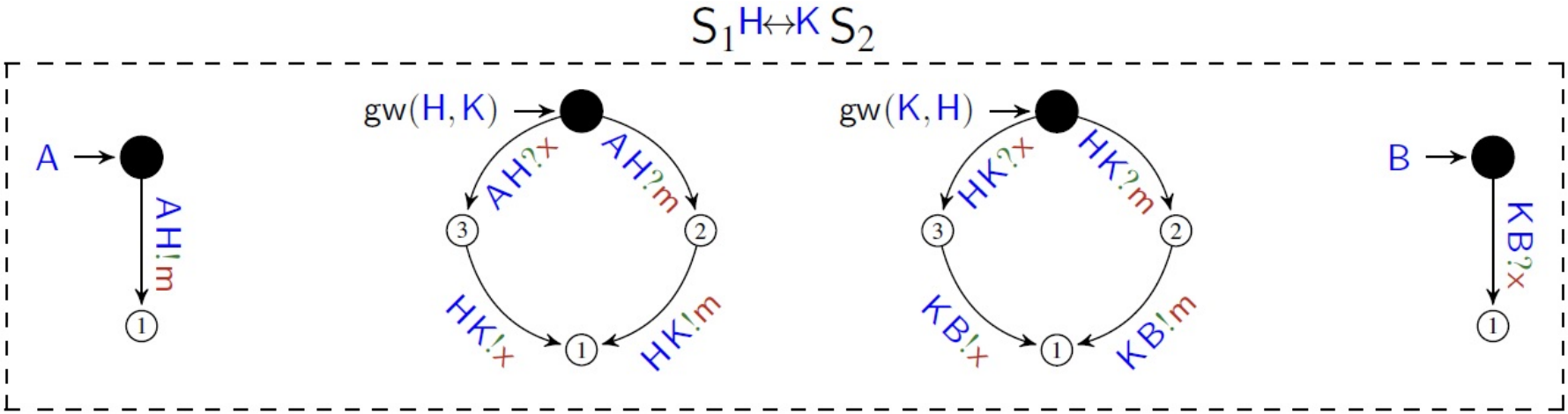

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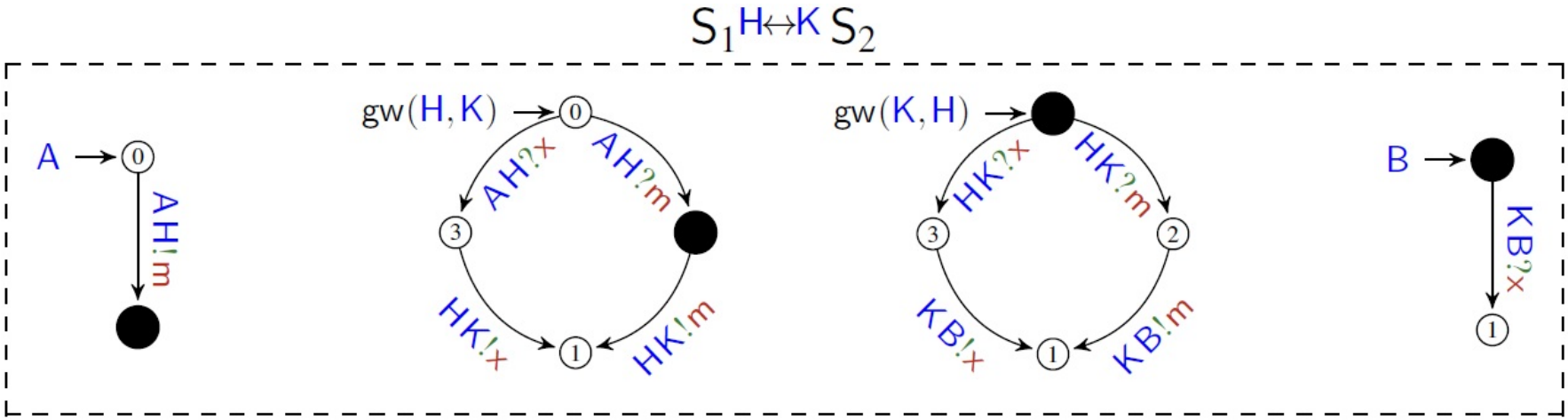

$\mathtt{A} \longrightarrow \mathtt{H} : \mathsf{m}$

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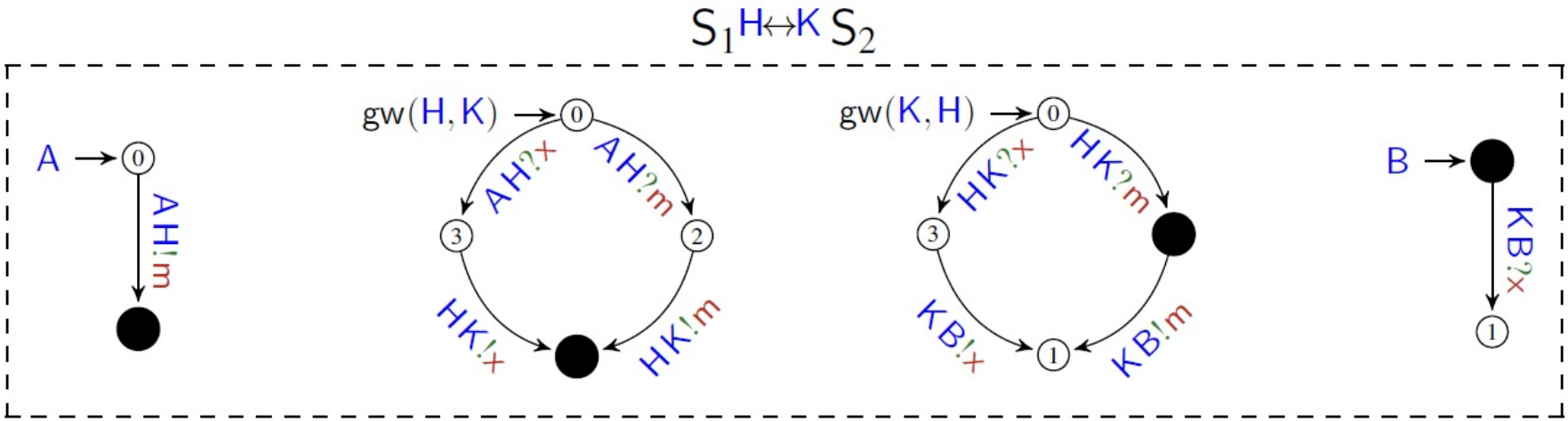

$\mathtt{gw(H,K)} \rightarrow \mathtt{gw(K,H)} : \mathtt{m}$

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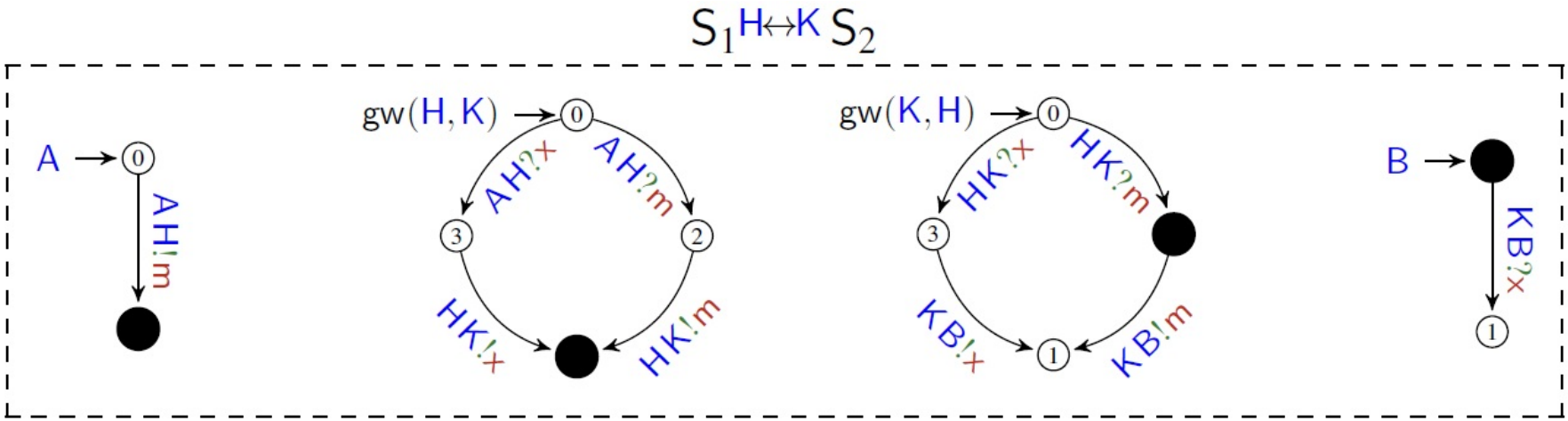

Deadlock!

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A CFSM A is

1. is **sequential** if each state has **at most** one outgoing transition.
2. is **!-live** if, for any reachable configuration s: any output action A can perform occurs in a continuation of the system. Formally

$$s(\mathsf{A}) \xrightarrow{\mathsf{A}\,\mathsf{B}!\mathsf{m}} \textit{ implies } s \rightarrow^* s' \xrightarrow{\mathsf{A}\rightarrow\mathsf{B}:\,\mathsf{m}} \textit{ for some } s'$$

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Sender and receiver play different roles in choice resolution while still relying on "handshakes"

In particular: Choices of outputs are "internal" ("sender chooses").

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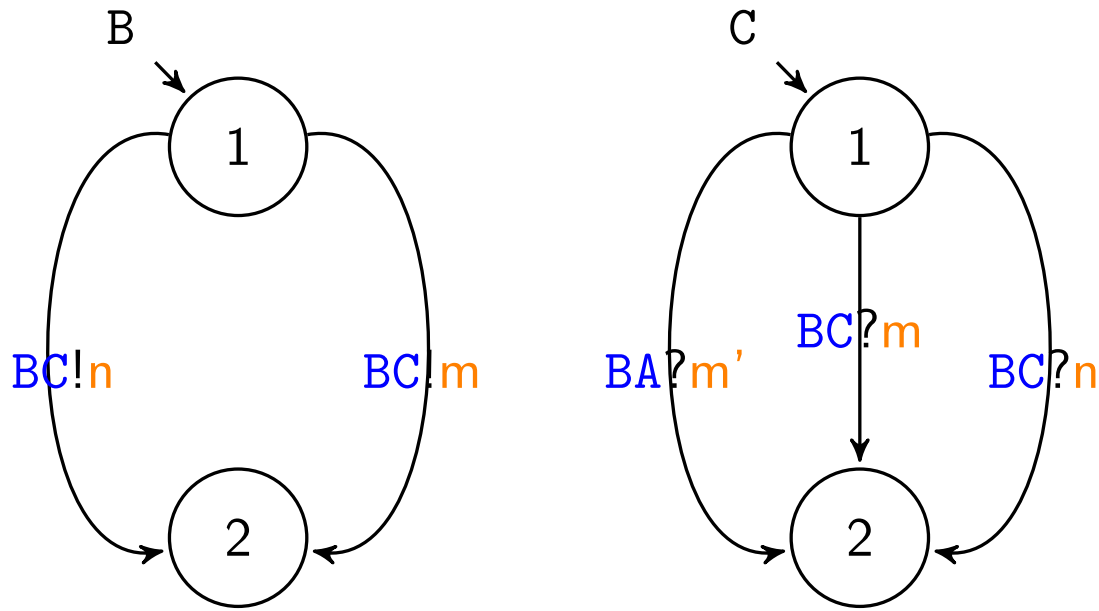

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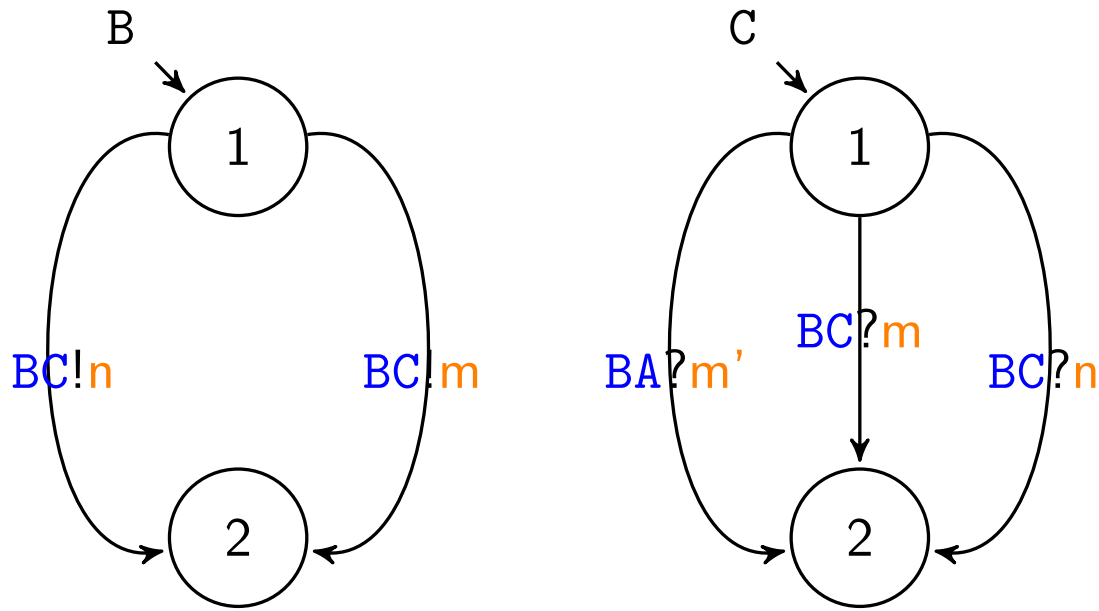

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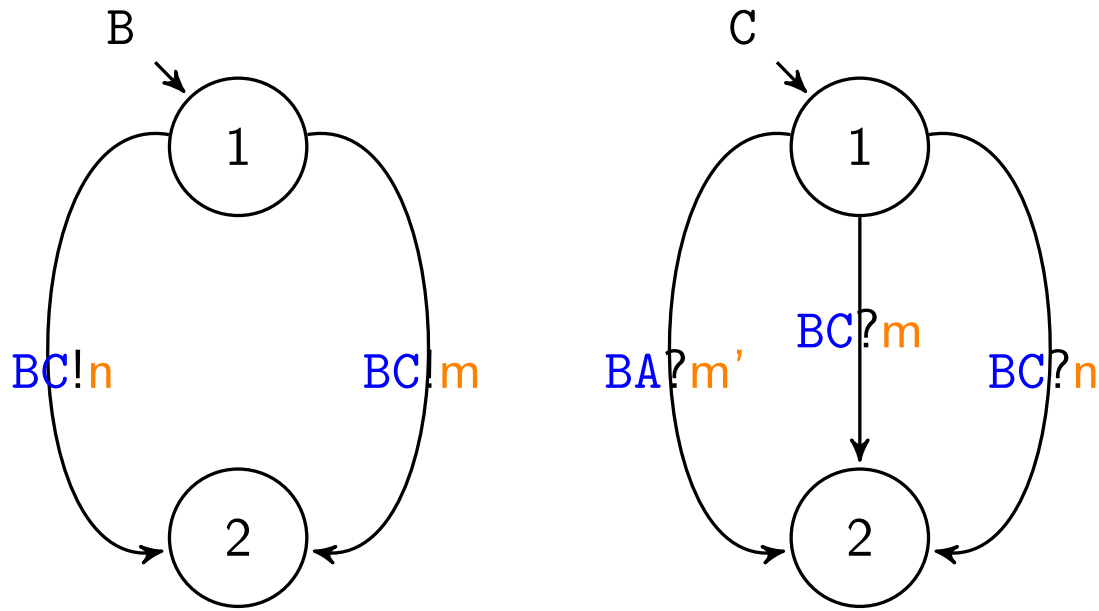

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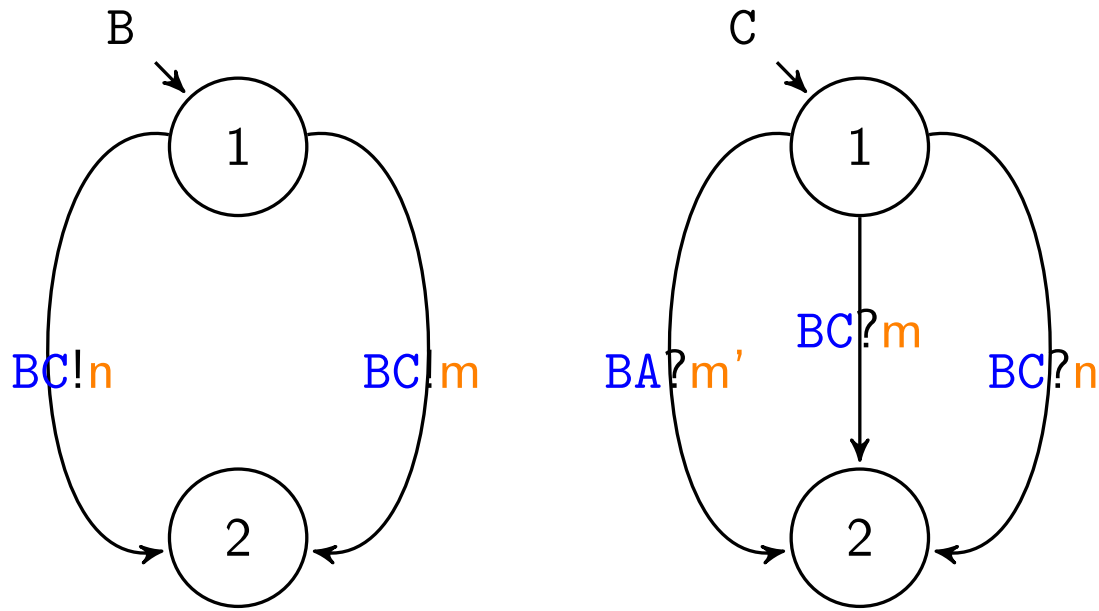

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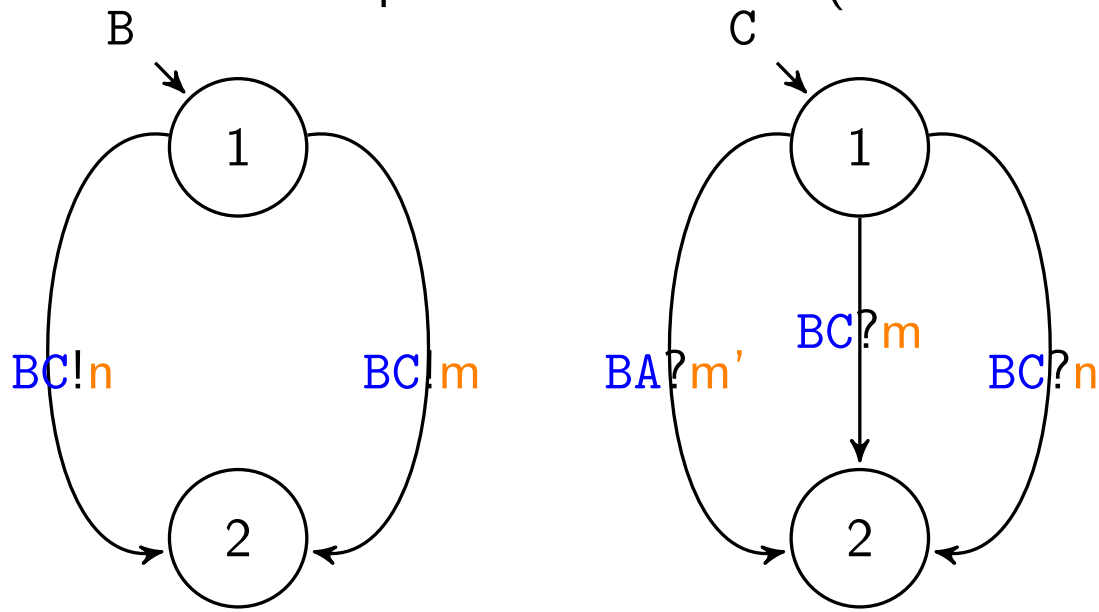

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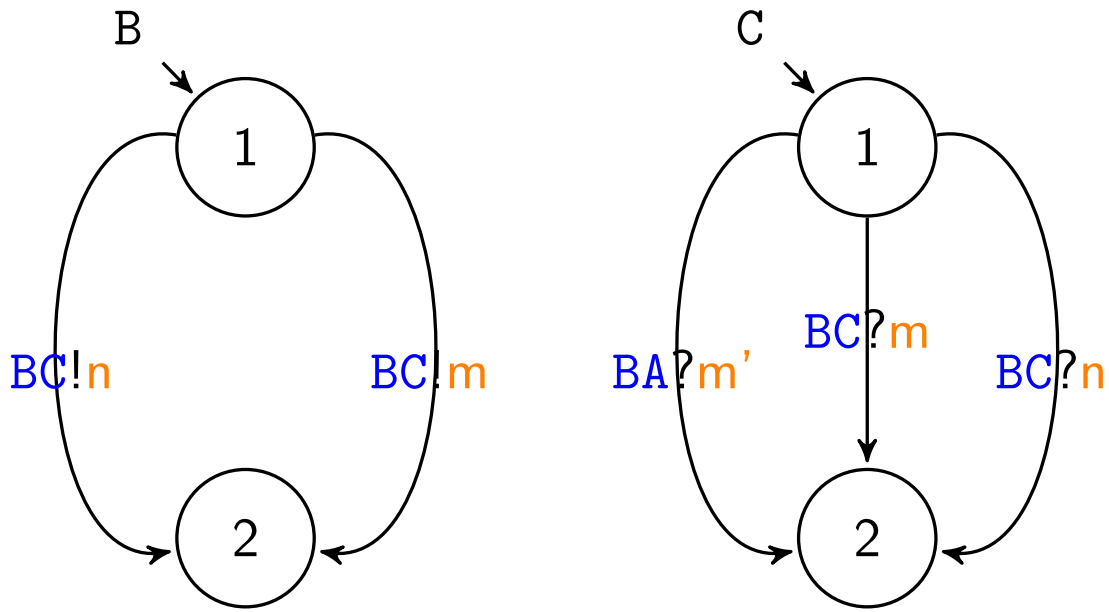

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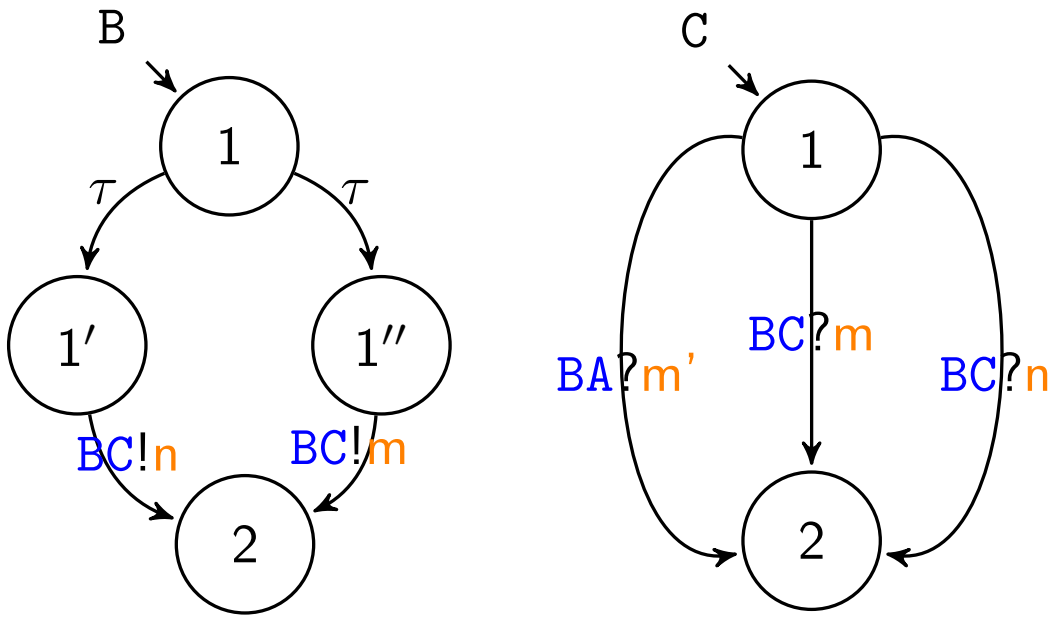

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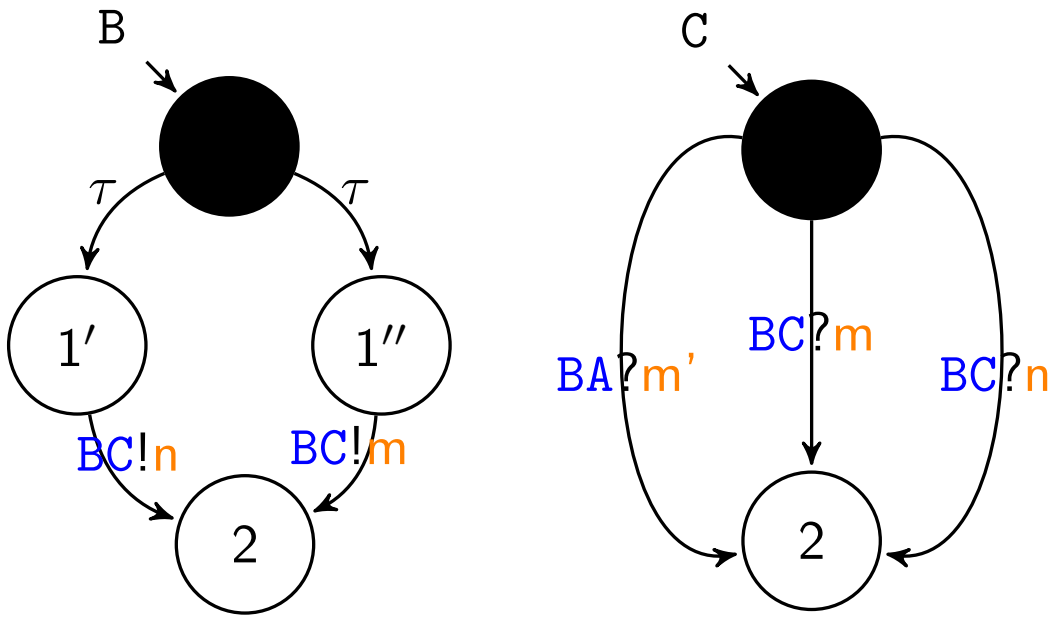

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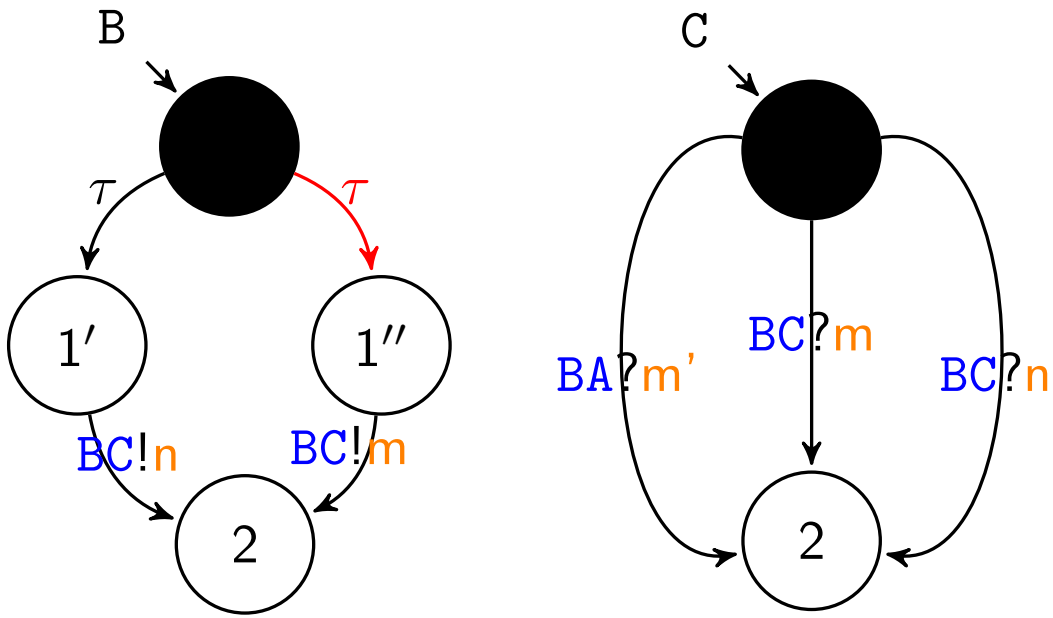

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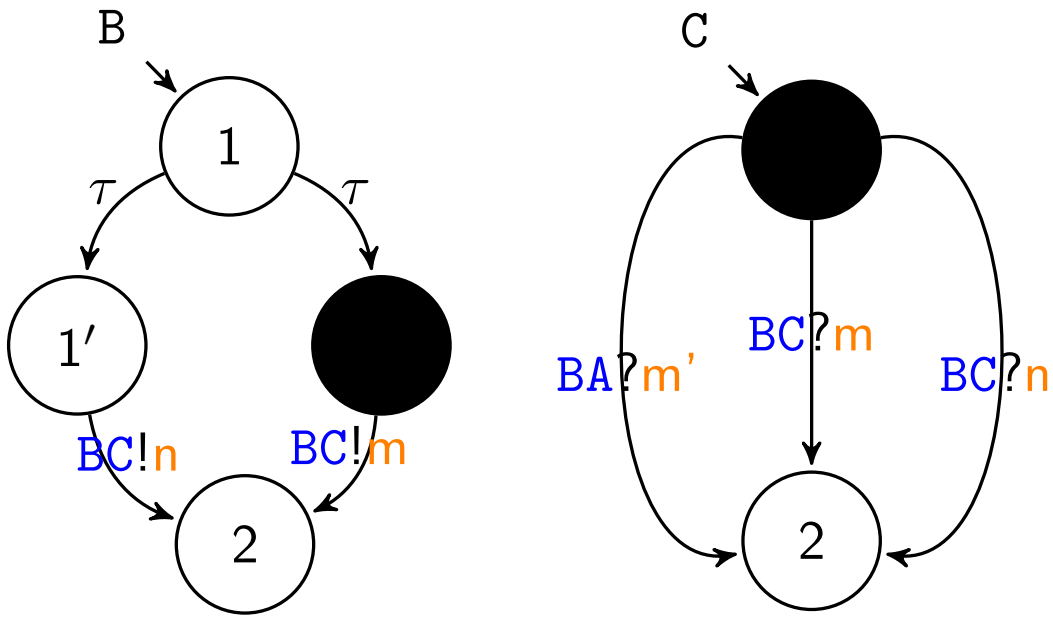

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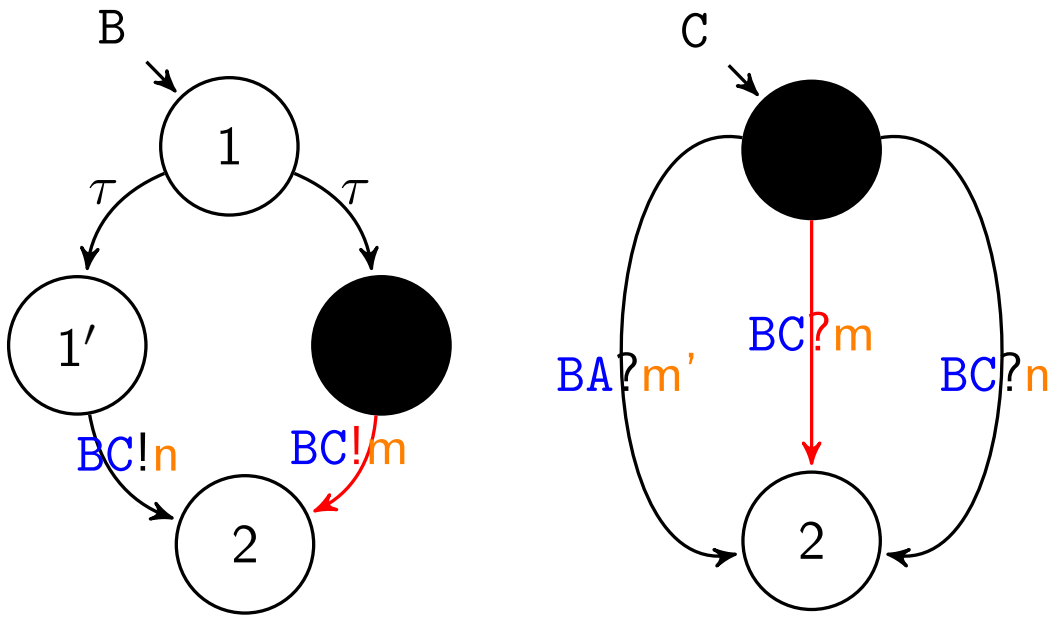

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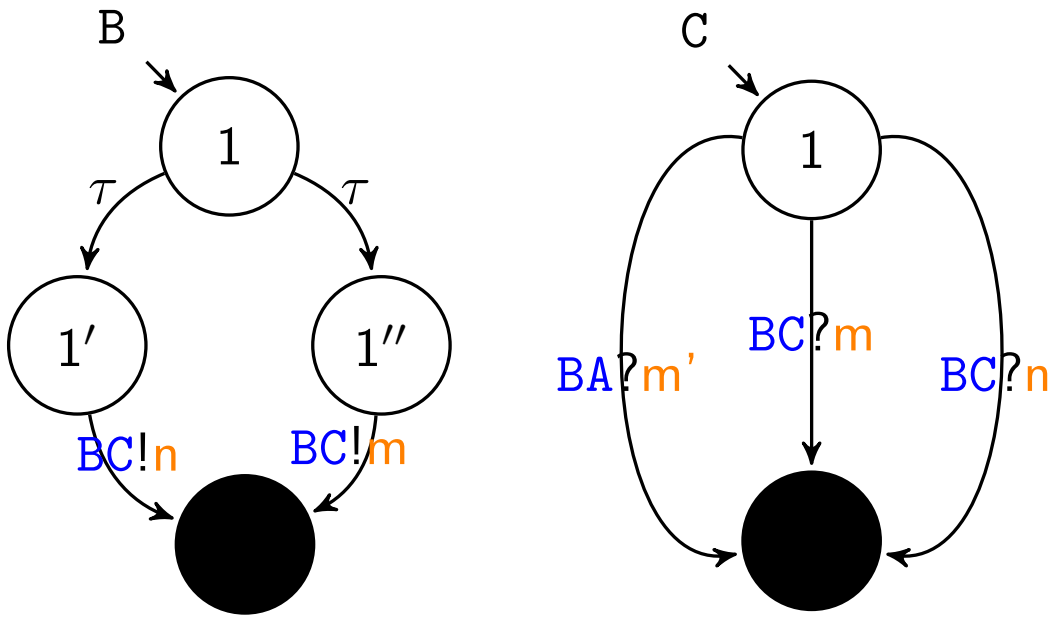

PaI with **Asymmetric synchronous** interactions

Barbanera, Lanese, Tuosto

ICE 2022

Composition with **Asymmetric synchronous** interactions

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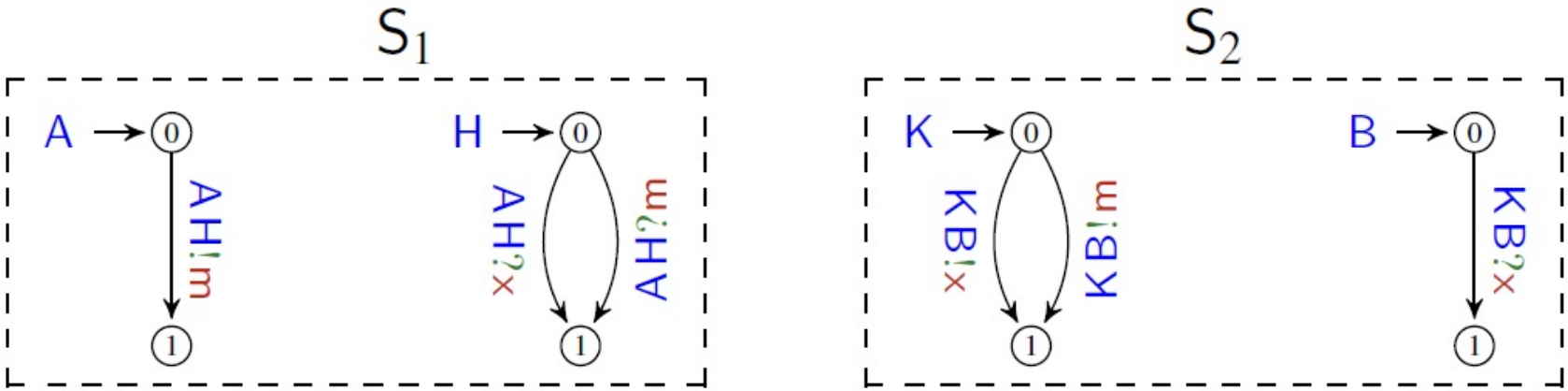

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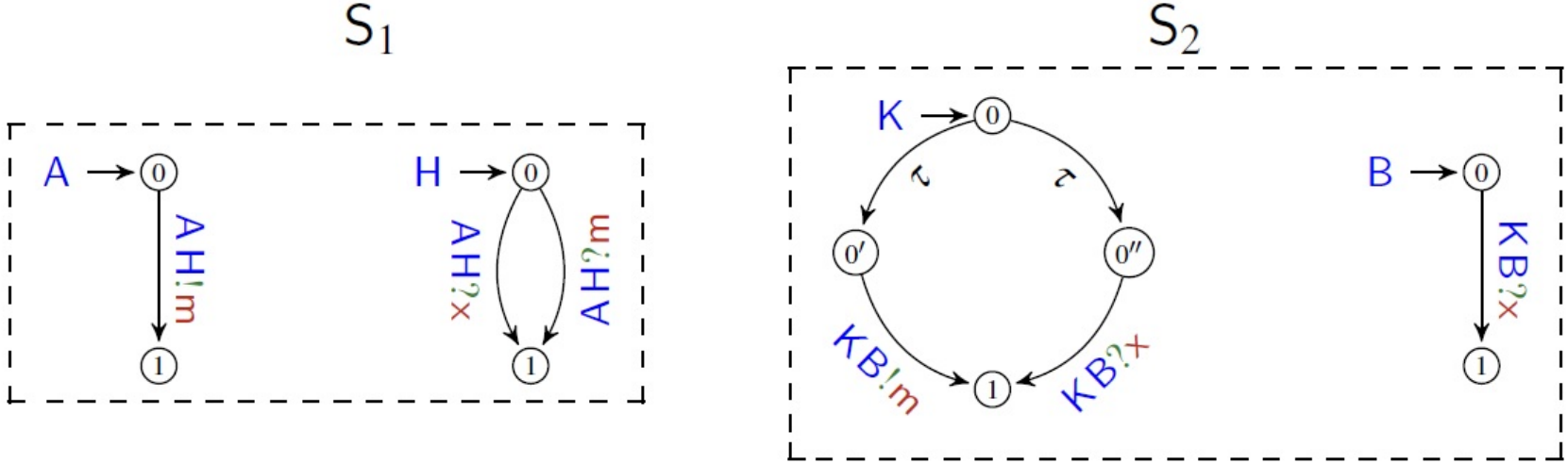

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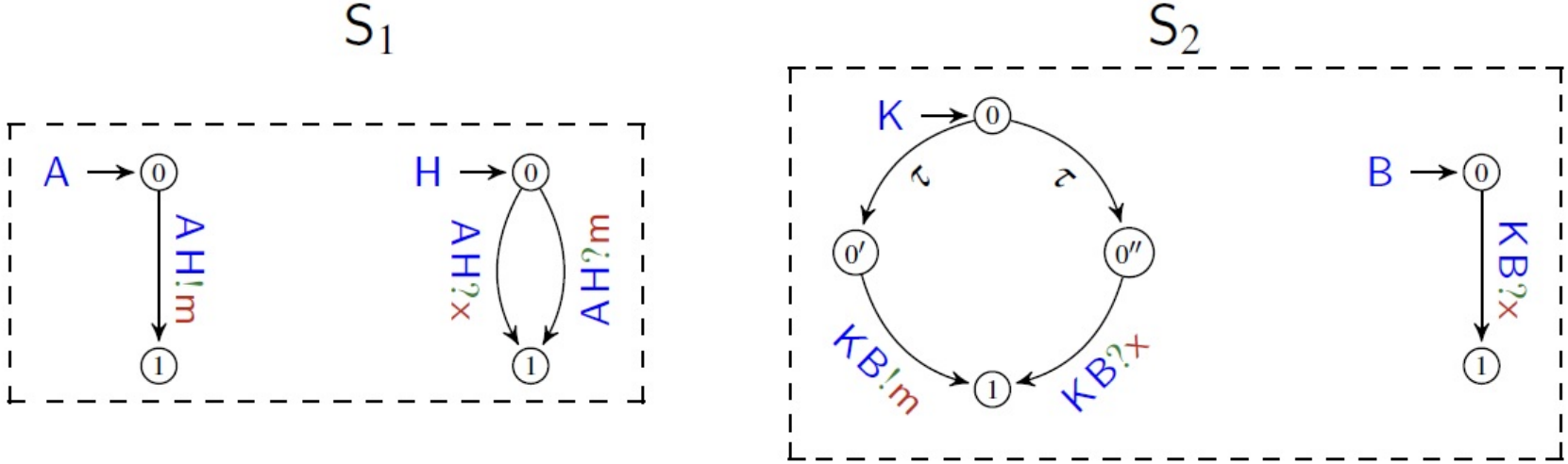

S_2 is not deadlock-free

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Deadlock-freedom: when the system cannot proceed, no participant is willing to proceed;
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For !?-deterministic, no mixed states and compatible interfaces, composition preserves

- *deadlock-freedom (in a sense it implies !-liveness);*
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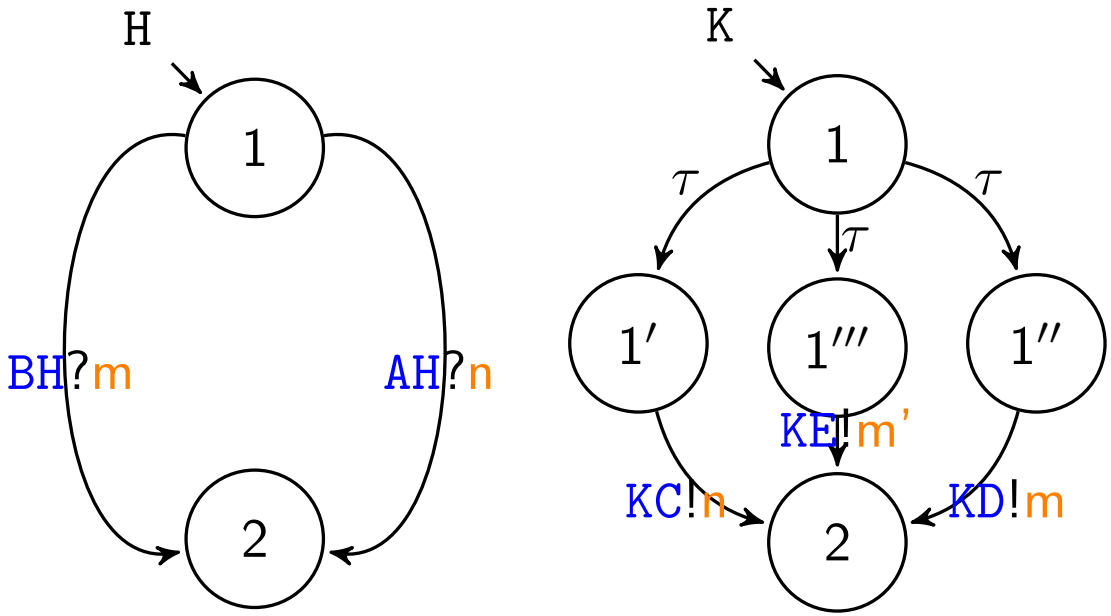

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The need of systems composability

Composability is useful both

- at design phase (modular design);
  Application of PaI for Multi-Party Session Types
- at deployment phase and beyond OUR SETTING

Thank you for your attention.